

EFFECTS OF HALL CURRENT ON FREE CONVECTION AND MASS TRANSFER FLOW THROUGH A POROUS MEDIUM

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1. Introduction

The study of magnetohydrodynamic viscous flows with Hall currents has important engineering applications in problems of magneto-hydrodynamic generators and of Hall accelerators as well as in flight magnetohydrodynamics. Raptis [2] has studied the unsteady free convection and mass transfer flow through porous medium bounded by an infinite vertical plate, by using the model of Yamamoto and Iwamura [5] for the generalized Darcy's law. Recent studies [1, 4, 3, 7] on the hydromagnetic flows with Hall currents are mainly focused upon those where the magnetic field is imposed normal to the plate.

Hence, the purpose of the present investigation is to study the effects of Hall current on free convection and mass transfer through a porous medium bounded by an infinite vertical plate when a strong magnetic field acts in a plane which makes an angle α with the plane transverse along to the plate and the plate temperature fluctuates in time about a non-zero constant mean.

2. Equations of motion

Consider the x -axis along the vertical limiting surface in the upward direction and y -axis normal to it. A uniform magnetic field $\vec{H} = (0, H_0 \lambda, H_0 \sqrt{1-\lambda^2})$, where $\lambda = \cos \alpha$ is imposed on the fluid. Since the plate is infinite in extent, all physical quantities, except pressure, are functions of W and t only. The equation of continuity $\Delta \cdot \vec{q} = 0$ gives $v = -v_0$ ($v_0 > 0$), where $\vec{q} = (u, v, w)$. When the strength of magnetic field is very large, the generalized ohm's law in the absence of the electric field [6] is of the form:

$$\vec{J} + \frac{w_e T_e}{H_0} \vec{J} \times \vec{H} = \sigma (\mu e \vec{q} \times \vec{H} + \frac{1}{ene} \Delta \cdot p e), \quad (1)$$

where σ , μe , w_e , T_e , e , ne , and pe are the electric conductivity, the permeability, the cyclotron frequency, the electron collision time, the electric charge, the number

density of electron, and the electron pressure respectively. Neglecting the electron pressure, thermoelectric pressure and ion slip, we have from equation (1).

$$j_{x1} = \frac{\sigma H_0 \mu e \lambda}{1 + m^2 \lambda^2} [m \lambda u^1 - w^1],$$

$$j_{z1} = \frac{\sigma H_0 \mu e \lambda}{1 + m^2 \lambda^2} [u^1 + m \lambda w^1],$$

where $m = w_e T_e$ is the Hall parameter.

We consider further the case of short circuit problem in which the applied electric field $\vec{E} = 0$. Under these assumptions, the non-dimensional form of the equations of motion and energy reduce to:

$$\left[\frac{\partial}{\partial t} - \frac{\partial}{\partial y} - \frac{\partial^2}{\partial y^2} \right] q + m_1 q = G \theta + G^* \theta^*, \quad (2)$$

$$\frac{P \partial \theta}{\partial t} - \frac{P \partial \theta}{\partial y} = \frac{\partial^2 \theta}{\partial y^2}, \quad (3)$$

$$\frac{Sc \partial \theta^*}{\partial t} - \frac{Sc \partial \theta^*}{\partial Y} = \frac{\partial^2 \theta^*}{\partial Y^2}, \quad (4)$$

where $y = \frac{y_1 v^0}{\nu}$, $t = \frac{t^1 v_0^2}{\nu}$, $\omega = \frac{\nu \omega^1}{\nu_0^2}$, $u = \frac{u^1}{v_0}$, $w = \frac{w^1}{v_0}$,

$$w = \frac{w^1}{v_0}, \quad \theta = \frac{T^1 - T_\infty^1}{T_w^1 - T_\infty^1}, \quad \theta^* = \frac{c^1 - c_\infty^1}{c_w^1 - c_\infty^1},$$

$$P = \frac{\rho \nu c_p}{K}, \quad Sc = \frac{\nu}{D}, \quad G = \frac{\nu g \beta (T_w^1 - T_\infty^1)}{v_0^3},$$

$$G^* = \frac{\nu g \beta (c_w^1 - c_\infty^1)}{v_0^3}, \quad M^2 = \frac{\sigma \mu e^2 H_0^2 \nu}{\rho v_0^2}, \quad K = \frac{v_0^2 K^1}{\nu^2},$$

and

$$q = u + i w$$

The corresponding boundary conditions reduce to

$$u = 0, \quad w = 0, \quad \theta = 1 + \varepsilon e^{i\omega t} \quad \text{at } y = 0$$

$$\theta^* = 1 + \varepsilon e^{i\omega t} \quad (5)$$

$$u = 0, \quad w = 0, \quad \theta \rightarrow 0, \quad \theta^* \rightarrow 0 \quad \text{as } y \rightarrow \infty$$

To solve equations (2)—(4) under the boundary conditions (5), we now represent the velocity, temperature and concentration in the neighbourhood of the plate as

$$\begin{aligned} q &= q_0 + \varepsilon q_1 e^{i\omega t} + 0(\varepsilon^2), \\ \theta &= \theta_0 + \varepsilon \theta_1 e^{i\omega t} + 0(\varepsilon^2), \\ \theta^* &= \theta_0^* + \varepsilon \theta_1^* e^{i\omega t} + 0(\varepsilon^2), \end{aligned} \quad (6)$$

where $\varepsilon \ll 1$

substituting (6) in equations (2)—(4) and equating harmonic and non-harmonic terms, we have

$$q_0'' + q_0' - M_1 q_0 + G Q_0 + G^* \theta_0^* = 0 \quad (7)$$

$$q_1'' + q_1' - (M_1 + i\omega) q_1 + G \theta_1 + G^* \theta_1^* = 0 \quad (8)$$

$$\theta_0'' + P \theta_0' = 0, \quad (9)$$

$$\theta_0'' + S c \theta_0^* = 0, \quad (10)$$

$$\theta_1'' + P \theta_1' - i\omega P \theta_1 = 0, \quad (11)$$

$$\theta_1'' + S c \theta_1^* - i\omega S c \theta_1^* = 0, \quad (12)$$

where the primes denote differentiation with respect to y , and

$$M_1 = \left[\frac{M^2 \lambda^2 (1 - i m \lambda)}{1 + \lambda^2 m^2} + \frac{1}{K} \right]$$

The appropriate boundary conditions are

$$\begin{aligned} q_0 = q_1 = 0, \quad \theta_0 = \theta_0^* = 1, \quad \theta_1 = \theta_1^* = 1 \quad \text{at } \lambda = 0 \\ q_0 = q_1 = 0, \quad \theta_0 = \theta_0^* = 0, \quad \theta_1 = \theta_1^* = 0 \quad \text{as } \lambda \rightarrow \infty \end{aligned} \quad (13)$$

The solutions of equations (7)—(12) subject to the boundary conditions (13) are the following:

$$q_0 = \frac{G(e^{-hy} - e^{-py})}{P^2 - P - M_1} + \frac{G^*(e^{-hy} - e^{-scy})}{S c^2 - S c - M_1}, \quad \theta_0 = e^{-py}, \quad \theta_0^* = e^{-Sc} y,$$

$$q_1 = \frac{G(e^{-h_2y} - e^{-h_1y})}{h_2^2 - h_1^2 - (M_1 + i\omega)} + \frac{G^*(e^{-h_2y} - e^{-h_1^*y})}{h_2^{*2} - h_1^{*2} - (M_1 + i\omega)}, \quad \theta_1 = e^{-h_1y}, \quad \theta_1^* = e^{-h_1^*y},$$

where

$$h = \frac{1}{2} [1 + \sqrt{1 + 4 M_1}], \quad h_1 = \frac{1}{2} [P + \sqrt{P^2 + 4 i \omega P}]$$

$$h^* = \frac{1}{2} [S c + \sqrt{S c^2 + 4 i \omega S c}], \quad h_2 = \frac{1}{2} [1 + \sqrt{1 + 4 (M_1 + i \omega)}]$$

3. Results

The dimensionless velocity profiles (the transient primary velocity u and the transient secondary velocity w) are plotted in figures 1 and 2 ($P=0.71$, $Sc=0.7$, $G=5.0$, $G^*=5.0$, $\omega=5.0$, $\varepsilon=0.01$, $\omega t=\pi/2$, $M^2=10$) for different values of α and m . It is observed that for constant values of M and m , both u and w increases with the increase of α where as for fixed value of α primary velocity u increases and secondary velocity w decreases with the increase of Hall parameter m . For $\lambda=1$, $M=0$ and $m=0$, the velocity distributions coincide with results of Raptis [2].

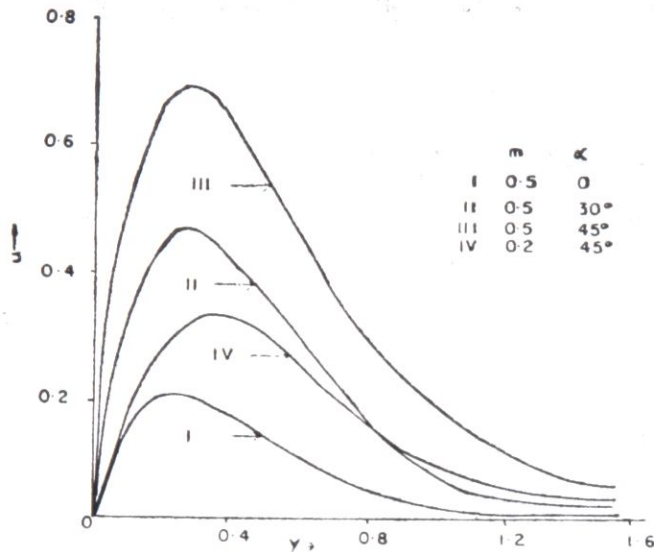


Fig 1: Profiles of non-dimensional primary velocity u .

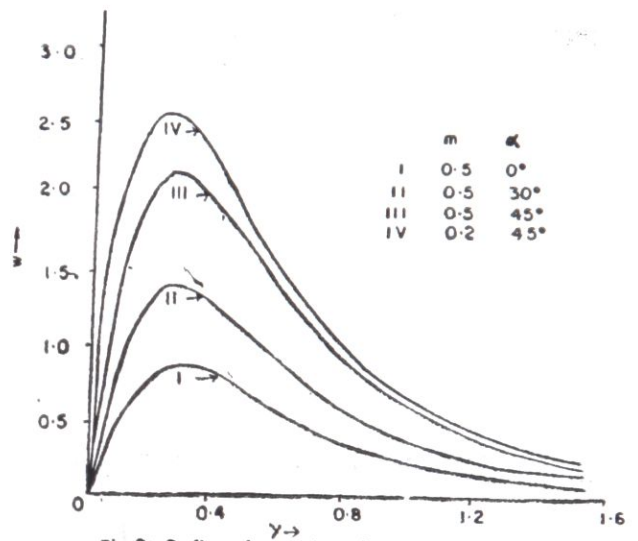


Fig 2: Profiles of non-dimensional secondary velocity w .

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