

CONSTITUTIVE EQUATIONS OF HETEROGENEOUS MICROPOLAR RODS

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1. Introduction

The application of micromorphic theory of mixtures to one-dimensional bodies-rods is presented in paper [1]. The balance laws of the mass, tensor microinertia, momentum and energy, as well as entropic inequalities of α -th constituent of the mixture and the sole mixture are derived.

This paper represents a continuation of paper [1], since using paper one's results constitutive equations of a mixture are derived for the case of a rod.

Since the constitutive theory for classical mixture is not sufficiently developed, because the basic difficulty is the choice of variables which figure in constitutive assumption, we adopted the procedure for the three dimensional body as used by R. J. Twiss and A. C. Eringen [2], adapting it to the rod case (one-dimensional body). In absence of chemical reactions as in paper [3], we derived constitutive equations. In this paper we also ignored interaction between constituents, believing that their omission can be justified in the case of a special model, i.e, a one-dimensional body for which this omission can be done. Thus, during constitutive equation derivation the part relating to the interaction was equalized with zero. Even so, the constitutive theory derived here is more general in character than the existing theories, since it assumes that the mixture is made up of any number of constituents instead of only two.

Since in paper [1] balance laws of α -th constituent of the mixture and the sole mixture are derived in detail, here we shall state only those details that we shall use for the derivation of constitutive equations:

mass balance law of the α -th constituent of the mixture

$$(1.1) \quad \dot{\rho}_{(\alpha)} + \rho_{(\alpha)} \frac{\partial \dot{\varphi}_{(\alpha)}}{\partial \mathcal{J}} = \rho \hat{\beta}_{(\alpha)};$$

microinertia tensor balance law of the α -th constituent of the mixture

$$(1.2) \quad \rho_{(\alpha)} \overline{i_{(\alpha)}^{l_1 \dots l_p}} - \sum_s \rho_{(\alpha)} v_{(\alpha)k}^{l_s} i_{(\alpha)}^{l_1 \dots k \dots l_p} = \rho (\hat{\beta}_{(\alpha)}^{l_1 \dots l_p} - \hat{\beta}_{(\alpha)} i_{(\alpha)}^{l_1 \dots l_p});$$

balance law for movement quantity of the α -th constituent of the mixture

$$(1.3) \quad \frac{\partial \underline{t}_{(\alpha)}}{\partial \mathcal{J}} + \rho_{(\alpha)} (\underline{f}_{(\alpha)} - \dot{\underline{v}}_{(\alpha)}) = \rho \hat{\beta}_{(\alpha)} \underline{v}_{(\alpha)};$$

balance law of the momentum of the α -th constituent of the mixture

$$(1.4) \quad \frac{\partial \underline{t}_{(\alpha)}^l}{\partial \mathcal{J}} + \lambda^l \underline{t}_{(\alpha)} - \bar{i}_{(\alpha)}^l + \rho_{(\alpha)} (\underline{f}_{(\alpha)}^l - i_{(\alpha)}^l \dot{\underline{v}}_{(\alpha)}) - \rho_{(\alpha)} i_{(\alpha)}^{kl} (\dot{\underline{v}}_{(\alpha)k} + \underline{v}_{(\alpha)r} \dot{v}_{(\alpha)k}^r) = \\ = \rho (\hat{\beta}_{(\alpha)}^l \underline{v}_{(\alpha)} + \hat{\beta}_{(\alpha)}^{kl} \underline{v}_{(\alpha)k})$$

and energy balance law for the mixture as a whole

$$(1.5) \quad -\rho \dot{\varepsilon} + \underline{t} \frac{\partial v}{\partial \mathcal{J}} + \underline{t}^r \frac{\partial v_r}{\partial \varphi} + (\bar{t}^r - \lambda^r \underline{t}^r) v_r + \frac{\partial q}{\partial \mathcal{J}} + \rho h = 0.$$

2. Micropolar theory of rod

Micropolar theory is a special case of micromorphic theory, as micropolar materials are a special class of micromorphic materials, who indicate microrotation effects, which means that microdisplacement is made up of rotation.

In this case the gyration tensor is asymmetric, i.e.

$$(2.1) \quad v_{(\alpha)kl} = -v_{(\alpha)lk}.$$

The vector

$$(2.2) \quad v_{(\alpha)m} = \frac{1}{2} \varepsilon_{mkr} v_{(\alpha)}^{kr}, \quad v_{(\alpha)}^{kr} = -\varepsilon^{krm} v_{(\alpha)m}$$

determines the rotation speed of material point of the micropolar body.

If we assume that

$$(2.3) \quad i_{(\alpha)}^k = 0$$

which means that the centre of the macroelement mass lies at the same point, thus, we have that (see [1] eq. (4.12))

$$(2.4) \quad \dot{\underline{\sigma}}_{(\alpha)}^l = \rho_{(\alpha)} i_{(\alpha)}^{kl} (\dot{\underline{v}}_{(\alpha)k} + \underline{v}_{(\alpha)k} \dot{v}_{(\alpha)r}^r) + \rho (\hat{\beta}_{(\alpha)}^l \underline{v}_{(\alpha)} + \hat{\beta}_{(\alpha)}^{kl} \underline{v}_{(\alpha)r}),$$

or in component form

$$(2.5) \quad \dot{\sigma}_{(\alpha)}^{lm} = \rho_{(\alpha)} i_{(\alpha)}^{kl} \dot{v}_{(\alpha)k}^m - \rho_{(\alpha)} i_{(\alpha)}^{rk} \dot{v}_{(\alpha)k}^l v_{(\alpha)r}^m + \rho (\hat{\beta}_{(\alpha)}^l v_{(\alpha)}^k + \hat{\beta}_{(\alpha)}^{kl} v_{(\alpha)rk}),$$

From this, it follows that

$$(2.6) \quad \varepsilon_{lmk} \overset{\cdot}{\sigma}_{(\alpha)}^{lm} = \rho_{(\alpha)} \overline{(i_{(\alpha)p}^p q_{kl} - i_{(\alpha)kl}^l)} \overset{\cdot}{v}_{(\alpha)}^l + \rho \varepsilon_{lmk} (\hat{\beta}_{(\alpha)}^l v_{(\alpha)}^k + \hat{\beta}_{(\alpha)}^{kl} v_{(\alpha)rk}),$$

where ε_{lmk} is an alternation tensor, and where we used (2.2).

If we take that

$$(2.7) \quad j_{(\alpha)kl} = i_{(\alpha)p}^p g_{kl} - i_{(\alpha)kl}^l$$

we shall have

$$(2.8) \quad j_{(\alpha)kl} \overset{\cdot}{v}_{(\alpha)}^l = \sigma_{(\alpha)k},$$

i.e.

$$(2.9) \quad \begin{aligned} \rho_{(\alpha)} \overset{\cdot}{\sigma}_{(\alpha)k} &= \rho_{(\alpha)} \overline{j_{(\alpha)kl} \overset{\cdot}{v}_{(\alpha)}^l} = \rho_{(\alpha)} (i_{(\alpha)p}^p v_{(\alpha)k} - i_{(\alpha)k}^p v_{(\alpha)p}) = \\ &= \varepsilon_{lmk} \overset{\cdot}{\sigma}_{(\alpha)}^{lm} - \rho \varepsilon_{lmk} (\hat{\beta}_{(\alpha)}^l v_{(\alpha)}^k + \hat{\beta}_{(\alpha)}^{kl} v_{(\alpha)rk}). \end{aligned}$$

Henceforward we shall use the following relationship

$$(2.10) \quad \begin{aligned} \frac{\partial \overset{\cdot}{t}_{(\alpha)}^l}{\partial \mathcal{J}} &= t_{(\alpha),k}^l \frac{\partial x_{(\alpha)}^k}{\partial \mathcal{J}} = (t_{(\alpha)}^{lm} \underline{g}_m),_k \frac{\partial x_{(\alpha)}^k}{\partial \mathcal{J}} = \\ &= t_{(\alpha),k}^{lm} \underline{g}_m \frac{\partial x_{(\alpha)}^k}{\partial \mathcal{J}} = \frac{\delta t_{(\alpha)}^{lm}}{\delta \mathcal{J}} \underline{g}_m. \end{aligned}$$

If in the micromorphic rod theory of the first degree [1] we use (2.3), we shall obtain the following micropolar theory equations:

mass conservation of the α -th constituent of the mixture

$$(2.11) \quad \rho_{(\alpha)} + \rho_{(\alpha)} \frac{\partial \overset{\cdot}{\varphi}_{(\alpha)}}{\partial \mathcal{J}} = \rho \hat{\beta}_{(\alpha)}:$$

tensor's conservation of microinertia of the α -th constituent of the mixture

$$(2.11) \quad \rho_{(\alpha)} (i_{(\alpha)}^{kl} - v_{(\alpha)r}^k i_{(\alpha)}^{rl} - v_{(\alpha)r}^l i_{(\alpha)}^{kr}) = \rho (\hat{\beta}_{(\alpha)}^{kr} - \hat{\beta}_{(\alpha)}^{kl} i_{(\alpha)}^{kr});$$

balance of the momentum of the α -th constituent of the mixture

$$(2.13) \quad \frac{\partial \overset{\cdot}{t}_{(\alpha)}}{\partial \mathcal{J}} + \rho_{(\alpha)} (f_{(\alpha)} - \overset{\cdot}{v}_{(\alpha)}) = \rho \hat{\beta}_{(\alpha)} \underline{v}_{(\alpha)};$$

energy balance of the α -th constituent of the mixture

$$(2.14) \quad \begin{aligned} \rho_{(\alpha)} \overset{\cdot}{\varepsilon}_{(\alpha)} - \overset{\cdot}{t}_{(\alpha)} \left(\frac{\partial \underline{v}_{(\alpha)}}{\partial \mathcal{J}} - \underline{\lambda} \times \underline{v} \right) - \overset{\cdot}{t}_{(\alpha)r}^r \frac{\partial \underline{v}_{(\alpha)r}}{\partial \mathcal{J}} - \frac{\partial q_{(\alpha)}}{\partial \mathcal{J}} - \rho_{(\alpha)} h_{(\alpha)} = \\ = \rho \hat{\beta}_{(\alpha)} \left(\frac{1}{2} \underline{v}_{(\alpha)} \underline{v}_{(\alpha)} - \overset{\cdot}{\varepsilon}_{(\alpha)} \right) + \frac{1}{2} \rho \hat{\beta}_{(\alpha)}^{rs} v_{(\alpha)r} v_{(\alpha)s}, \end{aligned}$$

where

$$\begin{aligned}\lambda^r \underset{\sim}{v}_{(\alpha)r} &= \lambda_r \underset{\sim}{v}_{(\alpha)}^{kr} \underset{\sim}{g}_k = -\lambda \times \underset{\sim}{v}_{(\alpha)} \\ \bar{t}_{(\alpha)}^r \underset{\sim}{v}_{(\alpha)r} &= \bar{t}_{(\alpha)}^{rm} \underset{\sim}{v}_{(\alpha)rm} = 0,\end{aligned}$$

considering (2.1), (2.2) and

$$(2.15) \quad t_{(\alpha)}'^{kl} = t_{(\alpha)}'^{lk} \Rightarrow \bar{t}_{(\alpha)}^{kl} dv = \int_{dv} t_{(\alpha)}'^{kl} dv' = \bar{t}_{(\alpha)}^{lk}.$$

Conservation of momentum on obtains that (1.4), and using (2.10) in the component form

$$(2.16) \quad \frac{\delta t_{(\alpha)}^{lm}}{\delta \mathcal{J}} + \lambda^l t_{(\alpha)}^m - \bar{t}_{(\alpha)}^{lm} + \rho_{(\alpha)} f_{(\alpha)}^{lm} - \overset{\cdot}{\sigma}_{(\alpha)}^{lm} = 0$$

where

$$(2.17) \quad \overset{\cdot}{\sigma}_{(\alpha)}^{lm} = \rho_{(\alpha)} \overline{i_{(\alpha)}^{kl} v_{(\alpha)k}^m} - \rho_{(\alpha)} i_{(\alpha)}^{rk} v_{(\alpha)k}^l v_{(\alpha)r}^m + \rho (\hat{\beta}_{(\alpha)}^l v_{(\alpha)}^k + \hat{\beta}_{(\alpha)}^{kl} v_{(\alpha)rk}).$$

If Equation (2.16) is multiplied by ε_{lmk} , which in effect is equivalent to the operation of determining its symmetric part, and using

$$(2.18) \quad \mathfrak{M}_{(\alpha)k} = \varepsilon_{lmk} t_{(\alpha)}^{lm}, \quad l_{(\alpha)k} = \varepsilon_{lmk} f_{(\alpha)}^{lm}$$

and (2.9), we shall obtain the balance of the momentum in the form of

$$(2.19) \quad \frac{\delta \mathfrak{M}_{(\alpha)k}}{\delta \mathcal{J}} + \varepsilon_{lmk} \lambda^l t_{(\alpha)}^m + \rho_{(\alpha)} l_{(\alpha)k} = \rho_{(\alpha)} \overset{\cdot}{\sigma}_{(\alpha)k} + \rho \varepsilon_{lmk} (\hat{\beta}_{(\alpha)}^l v_{(\alpha)}^k + \hat{\beta}_{(\alpha)}^{kl} v_{(\alpha)rk}).$$

Considering that part $\bar{t}_{(\alpha)}^r \frac{\partial \underset{\sim}{v}_{(\alpha)r}}{\partial \varphi}$ in (2.14) we can rewrite it in the following form

$$(2.20) \quad \begin{aligned}\bar{t}_{(\alpha)}^r \frac{\partial \underset{\sim}{v}_{(\alpha)r}}{\partial \varphi} &= \bar{t}_{(\alpha)}^r \frac{\delta v_{(\alpha)rm}}{\delta \mathcal{J}} \underset{\sim}{g}^m = t_{(\alpha)}^{rm} \frac{\delta v_{(\alpha)mr}}{\delta \mathcal{J}} = -\varepsilon_{mrk} \bar{t}_{(\alpha)}^{rm} \frac{\delta v_{(\alpha)}^k}{\delta \mathcal{J}} = \\ &= \varepsilon_{rmk} \bar{t}_{(\alpha)}^{rm} \frac{\delta v_{(\alpha)}^k}{\delta \mathcal{J}} = \mathfrak{M}_{(\alpha)k} \frac{\delta v_{(\alpha)}^k}{\delta \varphi} = \mathfrak{M}_{(\alpha)} \frac{\partial \underset{\sim}{v}_{(\alpha)}}{\partial \mathcal{J}},\end{aligned}$$

where (2.2) and (2.18) were used, thus, the new equation for energy balance of the α -th constituent of the mixture becomes

$$(2.21) \quad \begin{aligned}\rho_{(\alpha)} \overset{\cdot}{\varepsilon}_{(\alpha)} - \bar{t}_{(\alpha)} \left(\frac{\partial \underset{\sim}{v}_{(\alpha)}}{\partial \varphi} - \lambda \times \underset{\sim}{v}_{(\alpha)} \right) - \mathfrak{M}_{(\alpha)} \frac{\partial \underset{\sim}{v}_{(\alpha)}}{\partial \mathcal{J}} - \frac{\partial q_{(\alpha)}}{\partial \mathcal{J}} - \rho_{(\alpha)} h_{(\alpha)} = \\ = \rho \hat{\beta}_{(\alpha)} \left(\frac{1}{2} \underset{\sim}{v}_{(\alpha)} \underset{\sim}{v}_{(\alpha)} - \varepsilon_{(\alpha)} \right) + \frac{1}{2} \rho \hat{\beta}_{(\alpha)}^{rs} \underset{\sim}{v}_{(\alpha)r} \underset{\sim}{v}_{(\alpha)s}.\end{aligned}$$

3. Constitutive equations

In order to have a specific system of equations, the number of equations should be the same as the number of variables. In micromorphic balance equations of the α -th constituent the variables are

$$(3.1) \quad \left\{ \begin{array}{l} i_{(\alpha)}^{kl}, \quad t_{(\alpha)}^k, \quad q_{(\alpha)}^k, \quad \psi_{(\alpha)}, \quad \eta_{(\alpha)} \\ x_{(\alpha)k}, \quad \chi_{(\alpha)kK}, \quad \theta \\ i_{(\alpha)}^{kl}, \quad \rho_{(\alpha)} \\ v_{(\alpha)}^{lm}, \quad v_{(\alpha)}^l, \quad \varepsilon_{(\alpha)}, \quad \mathcal{J}_{(\alpha)}, \quad \dot{v}_{(\alpha)}^l \\ f_{(\alpha)}^l, \quad h_{(\alpha)}, \quad t. \end{array} \right.$$

It is assumed that variables in (3.1)₅ are predefined, whilst in (3.1)₄ they are determined on the basis of the remaining variables. Variables in (3.1)₃ are given by (1.1) and (1.2) for $p=2$. It is assumed that motion and temperature are independent variables, as they are not dependent on the process. Remaining variables in (3.1)₁ are independent variables.

There are $(12n+1)$ variables in (3.1)₂ where $\alpha=1, 2, \dots, n$ and more $17n$ variables in (3.1)₁, giving a total of $(29n+1)$ variables. Using the balance equation for movement quantity of the α -th constituent (1.3), the balance equation of momentum of the α -th constituent (1.4) for $p=1$, as energy balance equation for mixture (1.5), we shall have $(12n+1)$ equations. If we write constitutive equation for each dependent variable as a function of independent variables, we shall have additional $17n$ equations, i.e. a total of $(29n+1)$ equations for $(29n+1)$ variables, thus defining the equation system.

For micromorphic theory of mixtures the constitutive equation is

$$(3.2) \quad \Psi_{(\alpha)}(S_{(\alpha)}, t) = \psi_{(\alpha)} \left\{ u_{(\alpha-\beta)k}, \frac{\delta x_{(\gamma)k}}{\delta S_{(\gamma)}}, \chi_{(\gamma)kK}, \frac{\delta \chi_{(\gamma)kK}}{\delta S_{(\gamma)}}, \Lambda_{(\alpha)K}, \theta, S_{(\alpha)} \right\}$$

$$\alpha = 1, 2, \dots, n, \quad \beta = 1, 2, \dots, \alpha(\dots, n).$$

Objective principle imposes limitations on constitutive equations, requiring constitutive function to have an invariant form within an appropriate group of orthogonal transformations of spacial coordinate system, i.e.

$$(3.3) \quad \psi_{(\alpha)} \left\{ u_{(\alpha-\beta)k}, \frac{\delta x_{(\gamma)k}}{\delta S_{(\gamma)}}, \chi_{(\gamma)kK}, \frac{\delta \chi_{(\gamma)kK}}{\delta S_{(\gamma)}}, \Lambda_{(\alpha)K}, \theta, S_{(\alpha)} \right\} =$$

$$= \psi_{(\alpha)} \left\{ Q_{kl} u_{(\alpha-\beta)k}, Q_{kl} \frac{\delta x_{(\gamma)k}}{\delta S_{(\gamma)}}, Q_{kl} \chi_{(\gamma)kK}, Q_{kl} \frac{\delta \chi_{(\gamma)kK}}{\delta S_{(\gamma)}}, \Lambda_{(\alpha)K}, \theta, S_{(\alpha)} \right\}$$

where $u_{(\alpha-\beta)k}$ is a microchange relative vector given by

$$(3.4) \quad u_{(\alpha-\beta)k} = u_{(\alpha)k} - u_{(\beta)k}$$

where according to definition

$$(3.5) \quad u_{(\alpha)k} = X_{(\alpha)k} - X_{(\alpha)K} \delta_{Kk}$$

$$u_{(\beta)k} = X_{(\beta)k} - X_{(\beta)K} \delta_{Kk}.$$

Condition (3.3) for scalar value of the vectors variables function $\Psi_{(\alpha)} b_k^{(r)}$, $r = 1, 2, \dots, r_0$, $k = 1, 2, 3$, assumes that

$$(3.6) \quad \Psi_{(\alpha)}(b_k^{(r)}) = \Psi_{(\alpha)}(Q_{kl} b_k^{(r)}) = \Psi(B^{(pr)})$$

$$p = 1, 2, 3, \quad r = 1, 2, \dots, r_0 \geq 3$$

where $B^{(pr)}$ has an independent set of all possible scalar multiples derived from vector $b_k^{(r)}$, i.e.

$$(3.7) \quad B^{(pr)} \equiv b_k^{(p)} b_k^{(r)}, \quad p = 1, 2, 3, \quad r = 1, 2, \dots, r_0 \geq 3$$

and since

$$b_k^{(r)} = \sum_p B^{(pr)} b^{-1(p)}, \quad b^{(s)} = \sum_q B^{(qs)} b_k^{-1(q)}$$

remaining scalar products shall be

$$(3.8) \quad b_k^{(r)} b_k^{(s)} = \sum_{p,q=1}^3 B^{(pr)} B^{(qs)} B^{-1(pq)}, \quad r, s, = 1, 2, \dots, r_0.$$

Entropic inequality also constrains the constitutive equations. Due to equation system's specific nature, only energy equation for a mixture can be used, thus, we have to use entropic inequality of a mixture in a developed form (see eq. (3.4.60)), i.e.,

$$(3.9) \quad \sum_{\alpha} \left\{ -\rho_{(\alpha)} (\dot{\Psi} + \dot{\theta} \eta_{(\alpha)}) + t_{(\alpha)}^k \left(\frac{\delta v_{(\alpha)k}}{\delta \mathcal{J}} + v_{(\alpha)rk} \lambda^r \right) + t_{(\alpha)}^{rm} \frac{\delta v_{(\alpha)mr}}{\delta \mathcal{J}} + \right.$$

$$\left. + (\bar{t}_{(\alpha)}^{rk} - 2 \lambda^r t_{(\alpha)}^k) v_{(\alpha)(kr)} + \frac{q_{(\alpha)}}{\theta} \frac{\partial \theta}{\partial \mathcal{J}} + \rho \beta_{(\alpha)} \left(\frac{1}{2} v_{(\alpha)}^2 + \Psi_{(\alpha)} \right) + \right.$$

$$\left. + \frac{1}{2} \rho \hat{\beta}_{(\alpha)}^{rs} v_{(\alpha)kr} v_{(\alpha)ks} \right\} \geq 0.$$

During the derivation of equations, we shall consider micropolar mixture case, as a special micromorphic mixture class, excluding the existence of chemical reaction. Then,

$$(3.10) \quad v_{(\alpha)(kr)} = 0, \quad \hat{\beta}_{(\alpha)} = 0, \quad \hat{\beta}_{(\alpha)}^{rs} = 0.$$

Since the tensor $\chi_{(\alpha)kK}$ is now orthogonal, which means that it has three mutually independent coordinates, the number of variables in (3.1)₂ being reduced, it now has $(6n+1)$ variables which together with $17n$ variables in (3.1)₁ make a total of $(23n+1)$ variables. Using balance equations for movement quantity (2.13), the balance of the momentum (2.19) and balance equation for mixtures energy, we shall have $(6n+1)$ equations, which with remaining $17n$ equations gives a total of $(23n+1)$ equations.

Using (3.10), from (3.9) it follows that

$$(3.11) \quad \sum_{\alpha} \left\{ -\rho_{(\alpha)} (\dot{\psi}_{(\alpha)} + \dot{\theta} \eta_{(\alpha)}) + t_{(\alpha)}^k \left(\frac{\delta v_{(\alpha)k}}{\delta \mathcal{J}} + v_{(\alpha)rk} \lambda^r \right) + t_{(\alpha)}^{rm} \frac{\delta v_{(\alpha)mr}}{\delta \mathcal{J}} + \frac{q_{(\alpha)}}{\theta} \frac{\partial \theta}{\partial \mathcal{J}} \right\} \geq 0,$$

i.e.

$$(3.12) \quad -\sum_{\alpha} \rho_{(\alpha)} (\dot{\psi}_{(\alpha)} + \dot{\theta} \eta_{(\alpha)}) + \sum_{\gamma} \left\{ t_{(\gamma)}^k \left(\frac{\delta v_{(\gamma)k}}{\delta \mathcal{J}} + v_{(\gamma)rk} \lambda^r \right) + t_{(\gamma)}^{rm} \frac{\delta v_{(\gamma)mr}}{\delta \mathcal{J}} + \frac{q_{(\gamma)}}{\theta} \frac{\partial \theta}{\partial \mathcal{J}} \right\} \geq 0.$$

If in (3.12) we introduce (3.2) and use a rule related differentiation, we shall have

$$(3.13) \quad \begin{aligned} & -\sum_{\alpha} \rho_{(\alpha)} \left(\frac{\partial \psi_{(\alpha)}}{\partial \theta} + \eta_{(\alpha)} \right) \dot{\theta} + \sum_{\alpha} \left\{ \frac{q_{(\alpha)}}{\theta} - \rho_{(\alpha)} \left(\frac{\partial \psi_{(\alpha)}}{\partial \theta} + \eta_{(\alpha)} \right) u_{(\alpha)} \right\} \frac{\partial \theta}{\partial \mathcal{J}} + \\ & + \sum_{\gamma} \left(t_{(\gamma)}^k - \sum_{\alpha} \rho_{(\alpha)} \frac{\partial \psi_{(\alpha)}}{\partial x_{(\gamma)k,S}} J_{(\gamma)} \right) \frac{\delta v_{(\gamma)k}}{\delta \mathcal{J}} + \\ & + \sum_{\gamma} \left(t_{(\alpha)}^{rk} - \sum_{\alpha} \rho_{(\alpha)} \frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK,S}} \chi_{(\gamma) \cdot K}^l J_{(\gamma)} \right) \frac{\delta v_{(\gamma)kl}}{\delta \mathcal{J}} - \\ & - \sum_{\gamma} \left[\sum_{\alpha} \rho_{(\alpha)} \left(\frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK,S}} \chi_{(\gamma) \cdot K}^l + \frac{\partial \psi}{\partial \chi_{(\gamma)kK}} \chi_{(\gamma) \cdot K}^l \right) - t_{(\gamma)}^l \lambda^k \right] v_{(\gamma)kl} - \\ & - \sum_{\alpha} \sum_{\gamma} \rho_{(\alpha)} J_{(\gamma)}^{-1} w_{(\alpha-\gamma)} \left(\frac{\partial \psi_{(\alpha)}}{\partial x_{(\gamma)k,S}} x_{(\gamma)k,S^2} + \frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK,S}} \chi_{(\gamma)kK,S^2} + \right. \\ & \left. + \frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK}} \chi_{(\gamma)kK,S} + \frac{\partial \psi_{(\alpha)}}{\partial u_{(\alpha-\gamma)k}} \Lambda_{(\alpha)K} \delta_{kl} \right) \geq 0, \\ & \sum_{\gamma} \left[\sum_{\alpha} \rho_{(\alpha)} \left(\frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK,S}} \chi_{(\gamma) \cdot K}^l + \frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK}} \chi_{(\gamma) \cdot K}^l \right) + t_{(\gamma)}^k \lambda^l \right]_{[kl]} = 0, \end{aligned}$$

where we used the following expression

$$\begin{aligned}
 J_{(\gamma)} &\equiv \frac{\partial \mathcal{F}}{\partial S_{(\gamma)}}(S_{(\gamma)}, t) \\
 J_{(\gamma)}^{-1} &= \frac{\partial S_{(\gamma)}}{\partial \mathcal{F}} \\
 \lambda^k &= -J_{(\gamma)}^{-1} \frac{\partial x^k}{\partial S_{(\gamma)}} \\
 \frac{D^{(\alpha)}}{Dt} \mathcal{F}_{(\gamma)} &= \dot{\mathcal{F}}_{(\alpha)} = w_{(\alpha-\gamma)} \\
 \frac{D^{(\alpha)}}{Dt} x_{(\beta)i} &= v_{(\alpha)l} - v_{(\beta)l} = \lambda_l w_{(\alpha-\beta)} \\
 \dot{\psi}_{(\alpha)}(S_{(\alpha)}, t) &= \sum_{i, \gamma} \frac{\partial \psi_{(\alpha)}}{\partial \Phi_{(\gamma, i)}} \left\{ \frac{D^{(\gamma)} \Phi_{(\gamma, i)}}{Dt} + \Phi_{(\gamma, i), S} J_{(\gamma)}^{-1} w_{(\alpha-\gamma)} \right\} \\
 \dot{\theta} &= \dot{\theta} + \frac{\partial \theta}{\partial \mathcal{F}} u_{(\alpha)} \\
 \dot{x}_{(\gamma)k, S} &= v_{(\gamma)k, S} + x_{(\gamma)k, S^2} J_{(\gamma)}^{-1} w_{(\alpha-\gamma)} \\
 \dot{\chi}_{(\gamma)kK} &= v_{(\gamma)kl} \chi_{(\gamma) \cdot K}^l + \chi_{(\gamma)kK, S} J_{(\gamma)}^{-1} w_{(\alpha-\gamma)} \\
 \dot{\chi}_{(\gamma)kK, S} &= v_{(\gamma)kl, S} \chi_{(\gamma) \cdot K}^l + v_{(\gamma)kl} \chi_{(\gamma) \cdot K, S}^l + \chi_{(\gamma)kK, S^2} J_{(\gamma)}^{-1} w_{(\alpha-\gamma)} \\
 \dot{u}_{(\alpha-\gamma)k} &= \Lambda_{(\gamma)L} \delta_{Ll} J_{(\gamma)}^{-1} w_{(\alpha-\gamma)}.
 \end{aligned}
 \tag{3.14}$$

Since $\dot{\theta}$, $\frac{\partial \theta}{\partial \mathcal{F}}$, $\frac{\delta v_{(\gamma)k}}{\delta \mathcal{F}}$, $v_{(\gamma)kl}$, $\frac{\delta v_{(\gamma)kl}}{\delta \mathcal{F}}$ and $\chi_{(\gamma)kK, S^2}$ are independent variables, then the multipliers along with variables must disappear, and that gives the necessary and sufficient conditions for constitutive equations of the type (3.2) to be thermodynamically acceptable, i.e.

$$\begin{aligned}
 \eta_{(\alpha)} &= -\frac{\partial \psi_{(\alpha)}}{\partial \theta} \\
 \sum_{\alpha} q_{(\alpha)} &= 0 \\
 t_{(\gamma)}^k &= \sum_{\alpha} \rho_{(\alpha)} \frac{\partial \psi_{(\alpha)}}{\partial x_{(\gamma)k, S}} J_{(\gamma)} \\
 t_{(\gamma)}^{lk} &= \rho_{(\gamma)} \frac{\partial \psi_{(\gamma)}}{\partial \chi_{(\gamma)kK, S}} \chi_{(\gamma) \cdot K}^l J_{(\gamma)}
 \end{aligned}$$

$$\begin{aligned}
 (3.15) \quad t_{(\gamma)}^r \lambda^I &= \sum_{\alpha} \rho_{(\alpha)} \frac{\partial \psi_{(\alpha)}}{\partial x_{(\gamma)k,S}} J_{(\gamma)} \lambda^I = \sum_{\alpha} \rho_{(\alpha)} \frac{\partial \psi_{(\alpha)}}{\partial x_{(\gamma)k,S}} x_{(\gamma),S}^I \\
 &= \sum_{\alpha} \sum_{\gamma} \rho_{(\alpha)} J_{(\gamma)}^{-1} w_{(\alpha-\gamma)} \left(\frac{\partial \psi_{(\alpha)}}{\partial x_{(\gamma)k,S}} x_{(\gamma)k,S^2} + \frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK,S}} \chi_{(\gamma)kK,S^2} + \right. \\
 &\quad \left. + \frac{\partial \psi}{\partial \chi_{(\gamma)kK}} \chi_{(\gamma)kK,S} + \frac{\partial \psi_{(\alpha)}}{\partial u_{(\alpha-\gamma)k}} \Lambda_{(\gamma)K} \delta_{KI} \right) = 0 \\
 &\sum_{\gamma} \left[\sum_{\alpha} \rho_{(\alpha)} \left(\frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK,S}} \chi_{(\gamma),\cdot K,S}^I + \frac{\partial \psi_{(\alpha)}}{\partial \chi_{(\gamma)kK}} \chi_{(\gamma),\cdot K}^I \right) + t_{(\gamma)}^k \lambda^I \right]_{[kI]} = 0.
 \end{aligned}$$

If we accept the following definition

$$(3.16) \quad \rho \psi^I = \sum_{\alpha} \rho_{(\alpha)} \psi_{(\alpha)},$$

then using (3.15)₅, (3.15)₇ becomes

$$(3.17) \quad \sum_{\gamma} \left(\frac{\partial \psi^I}{\partial \chi_{(\gamma)kK,S}} \chi_{(\gamma),\cdot K,S}^I + \frac{\partial \psi^I}{\partial \chi_{(\gamma)kK}} \chi_{(\gamma),\cdot K}^I + \frac{\partial \psi^I}{\partial x_{(\gamma)k,S}} x_{(\gamma),S}^I \right)_{[kI]} = 0.$$

Integrals which satisfy the objectivity condition for micropolar mixture are

$$\begin{aligned}
 (3.18) \quad \mathcal{F}_{(\alpha)K} &= x_{(\alpha),S}^k \chi_{(\alpha)kK} \\
 \mathcal{F}_{(\alpha-\mu)K} &= x_{(\alpha),S}^k \chi_{(\mu)kK} \\
 \Gamma_{(\alpha)KL} &= \chi_{(\alpha),\cdot K,S}^k \chi_{(\alpha)kL} \\
 \Gamma_{(\alpha-\mu)KL} &= \chi_{(\alpha),\cdot K,S}^k \chi_{(\mu)kL} \\
 H_{(\alpha-\mu)KL} &= \chi_{(\alpha)kK} \chi_{(\mu),\cdot L}^k.
 \end{aligned}$$

Multiplying (3.18)₅ by $\chi_{(\alpha)}^{IK}$, we shall have

$$\chi_{(\alpha)kK} \chi_{(\mu),\cdot L}^k \chi_{(\alpha)}^{IK} = H_{(\alpha-\mu)KL} \chi_{(\alpha)}^{IK}.$$

Since

$$(3.19) \quad \chi_{(\mu),\cdot L}^k = H_{(\alpha-\mu)KL} \chi_{(\alpha)}^{kK}$$

$$\chi_{(\mu)kL} = H_{(\alpha-\mu)KL} \chi_{(\alpha)k}^K$$

then

$$\chi_{(\mu)kK} \chi_{(\mu),\cdot L}^k = (H_{(\alpha-\mu)MK} \chi_{(\alpha)K}^M) (H_{(\alpha-\mu)NL} \chi_{(\alpha)}^{kN})$$

i.e.

$$(3.20) \quad \delta_{KL} = H_{(\alpha-\mu)MK} H_{(\alpha-\mu)NL} \chi_{(\alpha)k}^{kN} \chi_{(\alpha)k}^M = \delta^{MN} H_{(\alpha-\mu)MK} H_{(\alpha-\mu)NL}$$

from which it can be seen that the symmetrical part $H_{(\alpha-\mu)MK}$ as a function of its antisymmetric part, i.e.

$$(3.21) \quad H_{(\alpha-\mu)(MK)} = H_{(\alpha-\mu)(MK)} (H_{(\alpha-\mu)L})$$

since

$$H_{(\alpha-\mu)M} = \frac{1}{2} \varepsilon_{MKL} H_{(\alpha-\mu)KL} = \frac{1}{2} E_{MKL} \chi_{(\alpha)kK} \chi_{(\mu)L}^k$$

i.e.

$$(3.22) \quad H_{(\alpha-\mu)[KL]} = \varepsilon_{KLM} H_{(\alpha-\mu)M}$$

In the following way it can be shown that (3.18)₂ and (3.18)₄ can be expressed like antisymmetric part $H_{(\alpha-\mu)KL}$, i.e.

$$(3.23) \quad \mathcal{F}_{(\alpha-\mu)N} = \mathcal{F}_{(\alpha-\mu)N} (\mathcal{F}_{(\mu)K}, H_{(\gamma-\mu)K}),$$

$$\Gamma_{(\alpha-\mu)NL} = \Gamma_{(\alpha-\mu)NL} (\Gamma_{(\mu)M}, H_{(\alpha-\mu)M}).$$

$$(3.24) \quad \psi^I = \psi^I (u_{(\alpha-\mu)k}, \mathcal{F}_{(\gamma)k}, \Gamma_{(\gamma)K}, H_{(\alpha-\mu)K}, \Lambda_{(\gamma)K}, \theta)$$

$$\gamma = 1, 2, \dots, n, \quad \mu = 1, 2, \dots, \alpha (\dots, n).$$

By demanding that mixtures free energy function ψ^I and free energy function of the α -th constituent $\psi_{(\alpha)}$ should satisfy the objectivity principle, we obtain further constraints on constitutive equations. A constraint of type (3.3) can be represented by a partial differential equation

$$(3.25) \quad \varepsilon_{klm} \sum_{\gamma} \left(\frac{\partial \psi^I}{\partial u_{(\alpha-\gamma)l}} u_{(\alpha-\gamma)m} + \frac{\partial \psi^I}{\partial x_{(\gamma)l,s}} x_{(\gamma)m,s} + \frac{\partial \psi^I}{\partial \chi_{(\gamma)lk}} \chi_{(\gamma)mk} + \frac{\partial \psi^I}{\partial \chi_{(\gamma)lk,s}} \chi_{(\gamma)mk,s} \right) = 0$$

and with a same equation for $\psi_{(\alpha)}$. Subtracting (3.17) from (3.25), we shall have

$$\varepsilon_{klm} \sum_{\gamma} \frac{\partial \psi^I}{\partial u_{(\alpha-\mu)l}} u_{(\alpha-\mu)m} = 0$$

and in a similar way

$$\varepsilon_{klm} \sum_{\gamma} \sum_{\mu} \rho_{(\alpha)} \frac{\partial \psi_{(\gamma)}}{\partial u_{(\alpha-\mu)l}} u_{(\alpha-\mu)m} = 0. \tag{3.26}$$

If we use (3.7) and (3.8), the solution of above equations can be written in this way

$$(3.27) \quad \begin{aligned} \psi^I &= \psi^I(y^{(\delta\mu)}, \mathcal{F}_{(\gamma)K}, \Gamma_{(\gamma)K}, H_{(\beta-\mu)K}, \Lambda_{(\gamma)K}, \theta) \\ \gamma &= 1, 2, \dots, n, \quad \mu = 1, 2, \dots, \beta(\dots, n) \\ \alpha &= 1, 2, \dots, n \end{aligned}$$

$$(3.28) \quad \psi_{(\alpha)} = \psi_{(\gamma)}(\mathcal{F}_{(\mu)K}, \mathcal{F}_{(\gamma)K}, \Gamma_{(\alpha)K}, H_{(\beta-\mu)K}, \Lambda_{(\alpha)K}, \theta)$$

where we used (3.21), (3.23), (3.24) and definitions

$$(3.29) \quad \mathcal{F}_{(\alpha, \alpha-\mu)K} = x_{(\alpha)kK} u_{(\alpha-\mu)k} \stackrel{\text{def}}{=} \mathcal{F}_{(\mu)K}$$

$$(3.30) \quad y^{(\delta\mu)} = u_l^{(\alpha-\delta)} u_l^{(\alpha-\mu)} = \mathcal{F}_K^{(\delta)} \mathcal{F}_K^{(\mu)}$$

Here the sign δ takes up three values in a cyclic set α .

When (3.28) is replaced in (3.15) we have appropriate constitutive equations

$$(3.31) \quad t_{(\gamma)}^k = \sum_{\alpha} \rho_{(\alpha)} \frac{\partial \psi_{(\alpha)}}{\partial x_{(\gamma)k,S}} = J_{(\gamma)} \chi_{(\gamma) \cdot K}^k \sum_{\alpha} \rho_{(\alpha)} \frac{\partial \psi_{(\alpha)}}{\partial \mathcal{F}_{(\gamma)K}} = \rho J_{(\gamma)} \chi_{(\gamma) \cdot K}^k \frac{\partial \psi^I}{\partial \mathcal{F}_{(\gamma)K}}$$

$$(3.32) \quad t_{(\gamma)}^{lk} = \frac{1}{2} \rho_{(\gamma)0} \chi_{(\gamma)iK} \chi_{(\gamma)kR} \varepsilon_{KRM} \frac{\partial \psi_{(\gamma)}}{\partial \Gamma_{(\gamma)M}}$$

$$(3.33) \quad M_{(\gamma)m} = \rho_{(\gamma)0} \chi_{(\gamma)mM} \frac{\partial \psi_{(\gamma)}}{\partial \Gamma_{(\gamma)M}}$$

$$(3.34) \quad \begin{aligned} p_{(\gamma)} &= \sum (\delta_{\alpha\sigma} \delta_{\gamma\rho} - \delta_{\gamma\sigma} \delta_{\alpha\rho}) J_{(\rho)}^{-1} \rho_{(\sigma)} \left(\frac{\partial \psi_{(\sigma)}}{\partial x_{(\rho)k,S}} x_{(\rho)k,S^2} + \right. \\ &\quad \left. + \frac{\partial \psi_{(\sigma)}}{\partial \chi_{(\rho)kK}} \chi_{(\rho)kK,S} + \frac{\partial \psi_{(\sigma)}}{\partial u_{(\sigma-\rho)k}} \Lambda_{(\rho)K} \delta_{KI} \right) = 0. \end{aligned}$$

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КОПСТИТУТИВНЫЕ УРАВНЕНИЯ ГЕТЕРОГЕННЫХ МИКРОПОЛЯРНЫХ СТЕРЖНЕЙ

П. Цветкович

Р е з ю м е

Пользуясь законами баланса массы, тензора микроинерции, количества движения и энергии микроморфной теорией смеси, примененной к теориям стержней, в статье выведены конститутивные уравнения смеси для случая микрополярной теории стержней.

KONSTITUTIVNE JEDNAČINE HETEROGENIH MIKROPOLARNIH ŠTAPOVA

Predrag Cvetković

I z v o d

U radu [1] izložena je mikromorfna teorija heterogenih tela (mešavine) primenjena za slučaj jednodimenzionalnog tela, odnosno štapova, i izvedeni zakoni balanca kako za jedan sastojak tako i za heterogeno telo (mešavinu) u celini. Koristeći zakone balansa mase, tenzora mikroinercije, količine kretanja i energije za slučaj mikropolarne teorije štapa, izvedene su konstitutivne jednačine za tenzore napona prvog i drugog reda i naponskog sprega. Konstitutivne jednačine su izvedene u odsustvu hemijskih reakcija kao u radu [3], a pošto se radi o štapu kao jednodimenzionalnom telu, to su zanemarene interakcije između sastojaka. I pored ovih zanemarivanja konstitutivne jednačine su opštijeg karaktera od postojećih, jer se pretpostavlja da se heterogeno telo sastoji od proizvoljnog broja sastojaka, a ne samo iz dva.

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