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THEOREMS CONCERNING CERTAIN SPECIAL TENSOR FIELDS ON RIEMANNIAN MANIFOLDS AND THEIR APPLICATIONS

Czesław Konopka

Abstract. Let M be an n-dimensional Riemannian manifold and F a symmetric (0, 2)-tensor field on M, which satisfies the condition $R \cdot F = 0$. Let, additionally, H, A and B be symmetric (0, 2)-tensor fields on M. If the tensor B commutes with F (cf. (1.3)) and H satisfies the condition $R \cdot H = Q(A, B)$, then

$$(A_{jk} - \frac{\operatorname{tr}(A)}{\operatorname{tr}(B)}B_{jk})(B_{ir}F_m^r - \frac{\operatorname{tr}(B,F)}{\operatorname{tr}(B)}B_{im}) = 0$$

on the open subset of M on which $tr(B) \neq 0$. It is also proved that, in certain separately Einstein manifolds, null geodesic collineation and projective collineations reduce to motions.

1. Preliminary results. Let M be an n-dimensional Riemannian manifold with not necessarily definite metric g. We denote by g_{ij} , Γ_{ij}^h , R_{ijk}^h and S_{ij} the local components of the metric g, the Levi Civita connection ∇ , The Riemann-Christoffel curvature tensor R and the Ricci tensor S of M, respectively.

For (0, p)-tensor T with local components $T_{i_1...i_p}$, we define (0, p + 2)-tensor $R \cdot T$ by

$$(R \cdot T)_{i_1 \dots i_p m k} = (\nabla_k \nabla_m - \nabla_m \nabla_k) T_{i_1 \dots i_p}$$

= $-T_{ri_2 \dots i_p} R^r_{i_1 m k} - \dots - T_{i_1 \dots i_{p-1} r} R^r_{i_p m k}.$

Moreover, for (0, 2)-tensors A and B with local components A_{ij} and B_{ij} respectively, define (0, 4)-tensor Q(A, B) by

$$Q(A,B)_{ijkh} = A_{ih}B_{jk} + A_{jh}B_{ik} - A_{ik}B_{jh} - A_{jk}B_{ih}.$$

LEMMA 1.1. Let F be a symmetric (0,2)-tensor field on M satisfying the condition

$$R \cdot F = 0. \tag{1.1}$$

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If H, A and B are symmetric (0, 2)-tensor fields on M satisfying the relations

$$R \cdot H = Q(A, B), \tag{1.2}$$

$$B \ commutes \ with \ F \ (i.e., \ B_{ir}F^r_{\ j} = B_{jr}F^r_{\ i}), \tag{1.3}$$

then

$$\widetilde{a}B_{jk} - \widetilde{b}A_{jk} = aB_{jr}F^r_{\ k} - bA_{jr}F^r_{\ k}, \qquad (1.4)$$

$$\widetilde{a}b = a\widetilde{b},\tag{1.5}$$

where $a = tr(A) = A_{ij}g^{ij}$, $b = tr(B) = B_{ij}g^{ij}$, $\tilde{a} = tr(A, F) = A_{ij}F^{ij}$, $\tilde{b} = tr(B, F) = B_{ij}F^{ij}$, $F_j^r = F_{sj}g^{rs}$ and $F^{ij} = F_{rs}g^{ri}g^{sj}$, etc.

Proof. At first we note that by virtue of Ricci identity the relations (1.1) and (1.2) can be written in the following forms

$$F_{ir}R^{r}_{\ jmk} + F_{jr}R^{r}_{\ imk} = 0, (1.6)$$

$$H_{ir}R^{r}_{jkm} + H_{jr}R^{r}_{ikm} = A_{ik}B_{jm} + A_{jk}B_{im} - A_{im}B_{jk} - A_{jm}B_{ik}.$$
 (1.7)

We remark also that from (1.7) it follows

$$A_{rm}B^r{}_k = A_{rk}B^r{}_m. aga{1.8}$$

Transvecting (1.6) with H^{ij} , we have $F^{ir}H_{is}R^s_{\ rkm} = 0$. Transvecting again (1.7) with F^{ij} and applying the above equality,

$$A_{mr}F^{rs}B_{sk} = A_{kr}F^{rs}B_{sm}.$$
 (1.9)

Moreover, we see from (1.1) that $R_{ijr}^{h}F_{k}^{r}$ is antisymmetric with respect to indices j, k. Therefore the following equality holds good

$$(H_{ir}R^{r}_{\ jks} + H_{jr}R^{r}_{\ iks})F^{s}_{m} = (H_{ir}R^{r}_{\ jsm} + H_{jr}R^{r}_{\ ism})F^{s}_{k}.$$

Hence by (1.7)

$$\begin{aligned}
A_{ir}F^{r}_{\ m}B_{jk} + A_{jr}F^{r}_{\ m}B_{ik} - A_{ik}B_{jr}F^{r}_{\ m} - A_{jk}B_{ir}F^{r}_{\ m} \\
&= A_{im}B_{jr}F^{r}_{\ k} + A_{jm}B_{ir}F^{r}_{\ k} - A_{ir}F^{r}_{\ k}B_{jm} - A_{rj}F^{r}_{\ k}B_{im}.
\end{aligned}$$
(1.10)

Transvecting this with g^{im} and using (1.3), (1.8) and (1.9), we obtain (1.4). Hence (1.5) follows, completing the proof.

THEOREM 1.2. Let F be a symmetric (0,2)-tensor field on M satisfying the conditon (1.1). If H, A and B are symmetric (0,2)-tensor fields on M satisfying the conditions (1.2) and (1.3), then

$$(A_{jk} - \frac{a}{b}B_{jk})(B_{ir}F^r_{\ m} - \frac{\widetilde{b}}{b}B_{im}) = 0$$

on the open subset of M on which $b \neq 0$.

Proof. From (1.4) it follows that tensor A commutes with F, that is, $A_{ir}F_j^r = A_{rj}F_i^r$. Moreover, from (1.4) we derive $A_{jr}F_k^r = \frac{1}{b}(aB_{jr}F_k^r + \tilde{b}A_{jk} - \tilde{a}B_{jk})$, which together with (1.5) substituted to (1.10) gives the equality

$$W_{jm}P_{ik} + W_{im}P_{jk} + W_{jk}P_{im} + W_{ik}P_{jm} = 0, (1.11)$$

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where $W_{jm} = B_{jr}F^r_m - \frac{\tilde{b}}{b}B_{jm}$ and $P_{ik} = A_{ik} - \frac{a}{b}B_{ik}$. Now the antisymmetrization of (1.11) with respect to the indices m, j yields an equation which compared with (1.11) leads to

$$W_{im}P_{jk} + W_{jk}P_{im} = 0.$$

Hence, it follows that $W_{im}P_{jk} = 0$, completing the proof.

THEOREM 1.3. Let F be a symmetric (0,2)-tensor field on M satisfying the condition $R \cdot F = 0$. Let H, H and A be symmetric (0,2)-tensor fields on M satisfying the relations (a) $R \cdot H = Q(A,g)$ and (b) $R \cdot H = Q(A,F)$. Then A = 0 at every point of M at which F is nonsingular and nonproportional to the metric g.

Proof. We restrict our consideration to a point of M at which F is nonsingular and nonproportional to g. As an immediate consequence of Theorem 1.2, we have by (a)

$$A_{ij} = \frac{a}{n}g_{ij}.$$
 (1.12)

Moreover, from Lemma 1.1 by (a) it follows that

$$\tilde{a}n - af = 0, \tag{1.13}$$

and by (b) it follows that

$$\widetilde{a}F_{jk} - \widetilde{f}A_{jk} = aF_{jr}F^r_{\ k} - fA_{jr}F^r_{\ k}, \qquad (1.14)$$

$$\widetilde{a}f - a\overline{f} = 0, \tag{1.15}$$

where $f = \operatorname{tr}(F)$, $\tilde{f} = \operatorname{tr}(F, F)$, $a = \operatorname{tr}(A)$ and $\tilde{a} = \operatorname{tr}(A, F)$. Because of (1.12) to prove the theorem it is sufficient to show that a = 0.

Consider the case f = 0. By (1.13), we have $\tilde{a} = 0$ and by (1.15) a = 0 or $\tilde{f} = 0$. If $\tilde{f} = 0$, then from (1.14) and nonsingularity of F, we find a = 0.

Let now $f \neq 0$. Comparing the relations (1.13) and (1.15), we have $a(f^2 - n\tilde{f}) = 0$. In the sequal we assume that $a \neq 0$. Then

$$f^2 - n\tilde{f} = 0. (1.16)$$

Next, in virtue of Theorem 1.2 by (b), we get $(A_{ij} - \frac{a}{f}F_{ij}(F_{mr}F_n^r - \frac{f}{f}F_{mn}) = 0$. This, because of (1.12) and because F is not proportional to g, can be written as $a(F_{mr}F_n^r - \frac{\tilde{f}}{f}F_{mn}) = 0$. Hence $F_{mr}F_n^r - \frac{\tilde{f}}{f}F_{mn} = 0$. So, by virtue of (1.14) and (1.15), we get $A_{jr}F_k^r = \frac{\tilde{f}}{f}A_{jk}$. The last equation, together with (1.12) and (1.16) implies a = 0. This is a contradiction. Therefore a = 0. This completes the proof.

Remark. In the above, we have indeed proved that, under our assumptions, A = 0 at every point of M at which $F_{ir}F_{j}^{r} \neq 0$ and F is nonproportional to g.

THEOREM 1.5. Let F be a symmetric (0,2)-tensor field on M satisfying the condition $R \cdot F = 0$. Let H, \widetilde{H} and A be symmetric (0,2)-tensor field on Msatisfying the relations (a) $R \cdot H = Q(A,g)$ and (b) $R \cdot \widetilde{H} = Q(\widetilde{A},g)$, where $\widetilde{A}_{ij} = A_{ir}F_j^r$. Then A = 0 at every point of M at which F is nonproportional to the metric g.

Proof. We restrict our considerations to a point of M at which F is nonproportional to g. At first we note that by (a) and Theorem 1.2 it follows that

$$A_{ij} = \frac{a}{n}g_{ij}, \text{ where } a = \operatorname{tr}(A).$$
(1.17)

Transvecting now (1.17) with F_k^i we see that $\stackrel{\sim}{A}$ is symmetric. Next, from Theorem 1.2 by (b), we get

$$A_{ir}F^r{}_j = \frac{a}{n}g_{ij}.$$
(1.18)

Substituting now (1.17) into (1.18), we get a = 0. This, with the help of (1.17), gives our assertion.

2. Applications. In this section we apply the results obtained in the previous section. Let M be a Riemannian manifold with not necessarily definite metric g and of dimension n > 2. For vector field v on M, denote by L_v the Lie derivative with respect to v.

A vector field v on M is said to be a motion if $L_v g = 0$, and affine collineation if $L_v \nabla = 0$ [9]. A curvature collineation on M is a vector field v which satisfies the condition $L_v R = 0$. An investigation of this transformation was strongly motivated by the important role of the Riemannian curvature tensor in the theory of general relativity [3,4].

The assertion of the theorem below is quite obvious.

THEOREM A. In a non-Ricci-flat Einstein manifold a curvature collineation is a motion.

Let M be a locally product Riemannian manifold in the sense of Tachibana [8]. Then, there exists an atlas of separating coordinate neighborhoods $\{(U, (x^i))\}$ such that in each $(U, (x^i))$ the metric g can be written as

$$g = \sum_{a,b=1}^{p} g_{ab}(x^c) dx^a \otimes dx^b + \sum_{\alpha,\beta=1}^{q} g_{\alpha\beta}(x^{\gamma}) dx^{\alpha} \otimes dx^{\beta}, \ p+q=n, \ 1 \le p \le n-1$$

Define an (0, 2)-tensor field on M by

$$[F_{ij}] = \begin{bmatrix} g_{ab} & 0\\ 0 & -g_{\alpha\beta} \end{bmatrix}$$

in each $(U, (x^i))$. The tensor field F is nonsingular, nonproportional to g, symmetric and parallel.

A locally product Riemannian manifold M is called to be a separately Einstein manifold if its Ricci tensor has the following form

$$S = cg + dF, \tag{2.1}$$

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where

$$c = \frac{(ns - f\widetilde{s})}{(n^2 - f^2)}, \quad d = \frac{(n\widetilde{s} - fs)}{(n^2 - f^2)}, \quad f = \operatorname{tr}(F) = p - q, \quad s = \operatorname{tr}(S) \text{ and } \widetilde{s} = \operatorname{tr}(S, F).$$

In a separately Einstein manifold M, c = const and d = const if p > 2 and q > 2 (see [8]). Note that a separately Einstein manifold is Ricci-flat if and only if c = d = 0. In the case d = 0, it reduces to an Einstein one.

It has been proved (cf. [5]) that

THEOREM B. In a seprately Einstein manifold with c = const, $d = const \neq 0$ and $c^2 \neq d^2$, a curvature collineation is necessarily a motion.

According to Katzin and Levine [4], a vector field v on M is said to be a null geodesic collineation (NGC) if

$$L_v \Gamma^h_{ij} = g^{hr} A_r g_{ij}, \tag{2.2}$$

where $A_r = \nabla_r p$ and p is a function. For such a transformation, we have

$$L_v R^h_{\ ijk} = A^h_{\ k} g_{ij} - A^h_{\ i} g_{jk}, \qquad (2.3)$$

where $A_{hk} = \nabla_k \nabla_h p$ and $A_k^h = A_{rk} g^{hr}$. If additionaly $A_{hk} = 0$, then the NGC is said to be special. Note also that a special null geodesic collineation is a curvature collineation.

THEOREM 2.1. Let F be a symmetric (0,2)-tensor field on a Riemannian manifold M. Assume additionaly that F is nonproportional to the metric tensor g at every point of M and satisfies the condition $R \cdot F = 0$. Then any NGC on M is special.

Proof. Applying the Lie derivative to the equation $R \cdot F = 0$ and making use of (2.3), we have $R \cdot H = Q(A, g)$, where $H = L_v F$ and tensor A have the local components $A_{ir}F_j^r$. Similarly, applying the Lie derivative to the equation $R \cdot g = 0$ and using (2.3) we find $R \cdot H = Q(A, g)$, where $H = L_v g$. In our situation, Theorem 1.5 yields $A_{ij} = 0$, which completes the proof.

From Theorem 2.1, we get

THEOREM 2.2. In a locally product Riemannian manifold M any NGC is special.

Combining Theorems A, B and 2.2, we derive

THEOREM 2.3. In a separately Einstein manifold M with c = const, d = const and $c^2 \neq d^2$, an NGC is necessarily a motion.

Moreover, from Theorem 2.1, for F = S it follows

THEOREM 2.4. If the Ricci tensor S of a Riemannian manifold M satisfies the relation $R \cdot S = 0$ and if S is nonproportional to g at every point of M, then any NGC on M is special.

A Riemannian manifold is called semisymmetric [7] if the condition $R \cdot R = 0$ is satisfied on M.

As an immediate consequence of Theorem 2.4, we get

THEOREM 2.5. In a semisymmetric manifold M with the Ricci tensor S nonproportional to g at every point, any NGC is special.

A vector field v on a Riemannian manifold is said to be a projective collineation (PC) if

$$L_v \Gamma^h_{ij} = \delta^h_j A_i + \delta^h_i A_j, \qquad (2.4)$$

where the 1-form A is defined by $A_j = (n+1)^{-1} \nabla_j (g^{rs} \nabla_r v_s)$. If $A_j = 0$, then the PC is an affine one. It is well-known that for any PC, we have

$$L_v R^h_{\ ijk} = \delta^h_j A_{ik} - \delta^h_k A_{ij}, \qquad (2.5)$$

where $A_{ik} = \nabla_k A_i$. Projective collineation is said to be special, if $A_{ij} = 0$. Note also that a special projective collineation is a curvature collineation.

THEOREM 2.6. Let F be a nonsingular, nonproportional to g at every point of M and summetric (0,2)-tensor field satisfying the condition $R \cdot F = 0$ on a Riemannian manifold M. Than any PC on M is special.

Proof. Applying the Lie derivative to the relations $R \cdot g = 0$ and $R \cdot F = 0$ and using of (2.5), we see that a PC satisfies $R \cdot H = Q(A, g)$ and $R \cdot \widetilde{H} = Q(A, F)$, respectively, where $H = L_v g$ and $\widetilde{H} = L_v F$. In view of Theorem 1.3, we obtain $A_{ij} = 0$, which gives our assertion.

From Theorem 2.6, we find

THEOREM 2.7. In a locally product Riemannian manifold M any PC is special.

Combining Theorems A, B and 2.7, we derive

THEOREM 2.8. In a separately Einstein manifold M with c = const, d = const and $c^2 \neq d^2$, any PC is necessarily a motion.

Moreover, we prove

THEOREM 2.9. Let the Ricci tensor S of a Riemannian manifold M be nonsingular, nonproportional to the metric g at each point and satisfy the relation $R \cdot S = 0$. Then, any PC on M is an affine collineation.

Proof. From Theorem 2.6, for F = S, we have $\nabla_j A_i = 0$. This, by the Ricci identity, leads to $A_r R^r_{ijk} = 0$ and also $A_r S^r_{\ k} = 0$. Since S is nonsingular, $A_i = 0$. This completes the proof.

As an immediate consequence of Theorem 2.9, we get

COROLLARY 2.10. Let the Ricci tensor S of a semisymmetric manifold M be nonsingular and nonproportional to the metric g at each point of M. Then, any PC on M is an affine collineation.

For projective collineation in a locally symmetric or Ricci-symmetric manifolds ($\nabla R = 0$ or $\nabla S = 0$, respectively) see Sumitomo [6].

The next theorem can be deduced from Theorem 1.4.

THEOREM 2.11. Let M be a Riemannian manifold whose Ricci tensor S satisfies the condition $R \cdot S = 0$. Assume additionally that, at each point of M, the scalar curvature $s \neq 0$ and S is nonproportional to the metric g. Then, any PC on M is special.

COROLLARY 2.12. Let the Ricci tensor S of a semisymmetric manifold M be nonproportional to the metric g and the scalar curvature $s \neq 0$ at each point of M. Then, any PC on M is special.

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Added in proof: Theorem 1.2 is a generalization of Grycakś theorem from [2]. Certain other generalization of his theorem can also be found in [1].

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Institute of Mathematics Technical University ul. Wybrzeże Wyspiańskiego 27 50-376 Wrocław Poland