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# SYMPLECTIC AND COSYMPLECTIC FOLIATIONS ON COSYMPLECTIC MANIFOLDS\*

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**Abstract.** We prove that a compact symplectic or cosymplectic foliation on a cosymplectic manifold is stable. This result extends to the odd-dimensional case the corresponding one for symplectic foliations on symplectic manifolds. A large family of examples is given.

## 1. Introduction

As it is \* well-known a compact holomorphic foliation of a Kähler manifold is stable (see [10]). The result holds for compact almost complex (resp., symplectic) foliations of an almost Kähler (resp., symplectic) manifold (see [6, 7]).

In this paper, we study the stability of foliations on cosymplectic manifolds. First, we introduce the notion of symplectic and cosymplectic foliations on a cosymplectic manifold, accordingly to the dimension of the foliation. Then we prove that a compact symplectic or cosymplectic foliation on a cosymplectic manifold is stable. To prove this, we use our previous results for the stability of invariant foliations of almost contact manifolds [2].

## 2. Algebraic preliminaries

Let *E* be a (2n + 1)-dimensional vector space over *R*. The space *E* is called *cosymplectic* if there exist a 2-form  $\Phi$  and a 1-form  $\eta$  such that  $\eta \wedge \Phi^n \neq 0$ . In such a case we say that the pair  $(\Phi, \eta)$  is a *cosymplectic structure* on *E* and the triple  $(E, \Phi, \eta)$  is called a *cosymplectic vector space*.

Let  $(E, \Phi, \eta)$  be a cosymplectic vector space. Then there is a unique vector  $\xi$  such that

$$\eta(\xi) = 1, \quad \Phi(\xi, v) = 0,$$

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for all vector  $v \in E$ . The vector  $\xi$  is called the *canonical vector* of the cosymplectic vector space  $(E, \Phi, \eta)$ . Note that the vector  $\xi$  is characterized by the following condition :

$$\omega(\xi)\eta \wedge \Phi^n = \omega \wedge \Phi^n,$$

for all 1-forms  $\omega$  on E.

Let  $E_n^{\perp}$  be the annihilator space of  $\eta$ , i.e.,

$$E_{\eta}^{\perp} = \{ v \in E \mid \eta(v) = 0 \}.$$

It is clear that  $E_{\eta}^{\perp}$  is a symplectic vector space with respect to the induced 2-form  $\Phi$ .

A 2s-dimensional subspace F is called *symplectic* if it is a symplectic subspace of  $E_{\eta}^{\perp}$ . If dim F = 2s + 1, then F is called *cosymplectic* if the pair  $(\Phi, \eta)$  induces a cosymplectic structure on F with canonical vector  $\xi$ .

A (2n + 1)-dimensional vector space E over R is said to be *almost contact* if it admits a linear mapping  $\phi : E \longrightarrow E$ , a vector  $\xi$  and a 1-form  $\eta : E \longrightarrow R$  such that

$$\phi^2 = -I + \eta \otimes \xi, \qquad \eta(\xi) = 1.$$

A subspace F of E is said to be *invariant* if  $\phi(v) \in F$  for all  $v \in F$  (see [11]). We easily see that only two cases occur for any invariant subspace F of E.

(1) If the vector  $\xi\notin F$  , then F has even dimension,  $\phi$  induces an almost complex structure on F and  $\eta|_F=0.$ 

(2) If the vector  $\xi \in F$ , then F has odd dimension and it is an almost contact vector space endowed with the restrictions of  $\phi$  and  $\eta$ .

These definitions may be extended fiberwise to vector bundles. Thus, let  $\pi: E \longrightarrow M$  be a vector bundle over an *n*-dimensional manifold M and with fiber  $R^{2n+1}$ . Then  $\pi: E \longrightarrow M$  is called *cosymplectic* if there exist cross-sections  $\Phi$  and  $\eta$  of  $\Lambda^2 E^*$  and  $\Lambda^1 E^*$ , respectively, whose restrictions to the fibers of E define a cosymplectic structure. Hence there exists a unique cross-section  $\xi$  of  $\pi: E \longrightarrow M$  such that

$$\eta(\xi) = 1, \qquad \Phi(\xi, X) = 0,$$

for all sections X of E.

The section  $\xi$  is called the *canonical section* of the cosymplectic vector bundle  $\pi: E \longrightarrow M$ . Note that for each point  $\xi_x$  is the canonical vector of the cosymplectic structure induced in the fiber  $E_x$ .

A vector bundle  $\pi : E \longrightarrow M$  is called *almost contact* if there exist a vector bundle automorphism  $\phi$ , a cross-section  $\xi$  of E and a cross-section  $\eta$  of  $\Lambda^1 E^*$ , whose restrictions to the fibers of E define an almost contact structure.

In a similar way, we define symplectic and cosymplectic subbundles of a cosymplectic bundle, and invariant subbundles of an almost contact bundle.

Next, let  $(E, \Phi, \eta)$  be a cosymplectic vector bundle over M with canonical section  $\xi$ , and F a symplectic or cosymplectic subbundle. Then we have

PROPOSITION 1. There exists an almost contact structure  $(\phi, \xi, \eta)$  and a metric g in E such that:

(1) 
$$g_x(\phi_x u, \phi_x v) = g_x(u, v) - \eta_x(u)\eta_x(v),$$

- (2)  $\Phi_x(u,v) = g_x(u,\phi_x v),$
- (3)  $F_x$  is an invariant vector subspace of  $E_x$ ,

for all  $x \in M, u, v \in E_x$ .

 $\mathit{Proof}\,.$  Let  $E_\eta^\perp$  be the symplectic subbundle of E whose fiber at  $x\in M$  is the space

$$(E_{\eta}^{\perp})_{x} = \{ u \in E_{x} \mid \eta_{x}(u) = 0 \}.$$

We consider two cases, say F is a symplectic or cosymplectic subbundle of E. First, suppose that F is a symplectic subbundle of E. Thus, F is a symplectic subbundle of  $E_{\eta}^{\perp}$ . Then, from Theorem 3.4 of [6], there exists an almost complex structure J on  $E_{\eta}^{\perp}$  (i.e., J is an automorphism  $J : E_{\eta}^{\perp} \longrightarrow E_{\eta}^{\perp}$  of the vector bundle  $E_{\eta}^{\perp}$  with  $J^2 = -I$ ) and a metric h in  $E_{\eta}^{\perp}$  such that:

(i)  $h_x(u,v) = h_x(J_xu,J_xv),$ 

(ii) 
$$\Phi_x(u,v) = h_x(u,J_xv),$$

(iii) F is a complex subbundle of  $E_n^{\perp}$ .

We set

$$\phi_x u = J_x (u - \eta_x (u) \xi_x),$$

and

$$g_x(u, v) = h_x(u - \eta_x(u)\xi_x, v - \eta_x(v)\xi_x) + \eta_x(u)\eta_x(v),$$

for all  $x \in M, u, v \in E_x$ . Then it is easy to prove that  $(\phi, \xi, \eta)$  is an almost contact structure, g a metric on M and (1), (2) and (3) are satisfied.

Now, suppose that F is a cosymplectic subbundle of E. Then  $F_{\eta}^{\perp}$  is a symplectic subbundle of  $E_{\eta}^{\perp}$ . Thus, by a similar device, we deduce the result.  $\Box$ 

### 3. Foliations on cosymplectic manifolds

First, we recall some definitions about foliations on manifolds [5, 9].

Let F be a foliation of dimension p on a n-dimensional manifold M. We denote by TF the vector subbundle of TM which consists of the tangent vectors to F, and by  $T_xF$  the fiber of TF over x. If X is a vector field tangent to F (i.e.,  $X(x) \in T_xF$  for all  $x \in M$ ) then we put  $X \in F$ .

The foliation F is said to be *compact* if each leaf of F is compact. A leaf L of a compact foliation F is said to be *stable* if every neighborhood U of L contains an invariant neighborhood V of L, i.e., V is a collection of leaves. F is said to be *stable* if every leaf of F is stable.

Let M be a cosymplectic manifold with structure  $(\Phi, \eta)$ , i.e.,  $\eta \wedge \Phi^n \neq 0$ ,  $d\eta = 0, d\Phi = 0$ . Then  $(TM, \Phi, \eta)$  is a cosymplectic vector bundle. A foliation F of dimension p = 2s (resp. p = 2s + 1) is said to be *symplectic* (resp. *cosymplectic*) if the vector subbundle TF of TM is symplectic (resp. cosymplectic).

Let us recall that an almost contact metric manifold  $(M, \phi, \eta, \xi, g)$  is called almost cosymplectic (in the sense of Blair [1]) if  $d\Phi = 0, d\eta = 0$ , where  $\Phi$  is the fundamental 2-form of M, i.e.,  $\Phi(X, Y) = g(X, \phi Y)$ .

Now, let  $(M, \Phi, \eta)$  be a cosymplectic manifold with canonical vector field  $\xi$ , and F a symplectic or cosymplectic foliation. Then, from Proposition 1, we have.

PROPOSITION 2. There exists on M an almost contact metric structure  $(\phi, \eta, \xi, g)$  with fundamental 2-form  $\Phi$  which is almost cosymplectic, and the foliation F is invariant.

Finally, from Proposition 2 and Theorem 1 of [2] we easily deduce our main result.

THEOREM 1. A compact symplectic or cosymplectic foliation F of a cosymplectic manifold  $(M, \Phi, \eta)$  is stable.

#### 4. Examples

Let  $S_r$  be the  $2r+1\mbox{-}\mathrm{dimensional}$  solvable non-nilpotent Lie group of matrices of the form

$e^{z}$	0	0	0		0	0	0	$x_1$ `
0	$e^{-z}$	0	0		0	0	0	$y_1$
0	0	$e^z$	0		0	0	0	$x_2$
0	0	0	$e^{-z}$		0	0	0	$y_2$
:	:	:	:		:	:	:	:
0	0	0	0		$e^{z}$	0		$\dot{x}_{-}$
0	0	0	0		0	$e^{-z}$	0	$u_r$
0	Ő	Ő	Ő		Õ	0	1	z
0 /	0	0	0		0	0	0	1,
	$e^z$ 0 0 0 0 $\vdots$ 0 0 0 0 $0$ $0$ 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{ccccc} e^z & 0 \\ 0 & e^{-z} \\ 0 & 0 \\ 0 & 0 \\ \vdots & \vdots \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$

where  $x_i, y_i, z \in R, 1 \leq i \leq r$ . Then  $S_r$  may be identified with  $R^{2r+1}$  by assigning to each matrix in  $S_r$  its global coordinates  $(x_1, y_1, ..., x_r, y_r, z)$ .

There exists a canonical injective Lie group homomorphism  $j_r: S_r \longrightarrow S_{r+1}$  defined by

$$j_r(x_1, y_1, ..., x_r, y_r, z) = (x_1, y_1, ..., x_r, y_r, 0, 0, z)$$

Then  $S_r$  may be considered as a Lie subgroup of  $S_{r+1}$  and we have a chain of Lie groups

$$\{e\} \subset S_1 \subset S_2 \subset \ldots \subset S_r \subset S_{r+1} \subset \ldots$$

Alternatively,  $S_r$  can be described as the semidirect group  $S_r = R \propto_{\phi} R^{2r}$ , where  $\phi(z) : R^{2r} \longrightarrow R^{2r}$  is given by the matrix

$e^{z}$	0	0	0	 0	0 \
0	$e^{-z}$	0	0	 0	0
0	0	$e^z$	0	 0	0
0	0	0	$e^{-z}$	 0	0
:		÷	÷	÷	
0	0	0	0	 $e^z$	0
$\setminus 0$	0	0	0	 0	$e^{-z}$

A simple computation shows that

$$\{\bar{\alpha}_i = e^{-z} dx_i, \ \bar{\beta}_i = e^z dy_i, \ \bar{\gamma} = dz\}$$

is a family of linearly independent left invariant 1 - forms on  $S_r$ . Then we have

$$d\bar{\alpha}_i = \bar{\alpha}_i \wedge \bar{\gamma}, \ d\bar{\beta}_i = -\bar{\beta}_i \wedge \bar{\gamma}, \ d\bar{\gamma} = 0$$

The corresponding dual basis of left invariant vector fields on  $S_r$  is

$$\left\{\bar{X}_i = e^z \frac{\partial}{\partial x_i}, \ \bar{Y}_i = e^{-z} \frac{\partial}{\partial y_i}, \ \bar{Z} = \frac{\partial}{\partial z}\right\}$$

and we have

$$[\bar{X}_i, \bar{Z}] = -\bar{X}_i, \ [\bar{Y}_i, \bar{Z}] = \bar{Y}_i,$$

all the other brackets being zero.

Now, let  $B \in \text{Sl}(2, \mathbb{Z})$  be an unimodular matrix with positive real and different eigenvalues  $\lambda$  and  $\lambda^{-1}$  and  $P \in \text{Gl}(2, \mathbb{R})$  such that

$$PBP^{-1} = \begin{pmatrix} \lambda & 0\\ 0 & \lambda^{-1} \end{pmatrix}$$

Let be  $z_0 \in R$  such that  $\lambda = e^{z_0}$  and consider the lattice  $L_r = P_r(Z^{2r})$ , where

$$P_r = \begin{pmatrix} P & 0 & \dots & 0 \\ 0 & P & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & P \end{pmatrix}$$

Then  $L_r$  is invariant by  $\phi(nz_0) = \phi(z_0)^n$ ,  $\forall n \in \mathbb{Z}$  and  $\Gamma_r = (z_0)\mathbb{Z} \propto_{\phi} L_r$  is a co-compact subgroup of  $S_r$ , i.e.,  $\operatorname{Solv}(r) = \Gamma_r \setminus S_r$  is a compact non-nilpotent solvmanifold of dimension 2r+1. We notice that  $\operatorname{Solv}(1)$  is the manifold considered in [8] and  $\operatorname{Solv}(1) \times S^1$  is the manifold considered in [3, 4]. Alternatively, the manifold  $\operatorname{Solv}(r)$  may be seen as the total space of a  $T^{2r}$ bundle over  $S^1$ . In fact, let  $T^{2r} = R^{2r}/L_r$  the 2*r*-dimensional torus and  $\rho: Z \longrightarrow$  $\operatorname{Diff}(T^{2r})$  the representation defined as follows :  $\rho(n)$  represents the transformation of  $T^{2r}$  covered by the linear transformation of  $R^{2r}$  given by the matrix

$e^{z}$	0	0	0		0	0 \
0	$e^{-z}$	0	0		0	0
0	0	$e^z$	0		0	0
0	0	0	$e^{-z}$		0	0
÷		÷	÷	· · .	÷	
0	0	0	0		$e^z$	0
0	0	0	0		0	$e^{-z}$

This representation determines an action  $A:Z\times (T^{2r}\times R)\longrightarrow T^{2r}\times R$  defined by

$$A(n, [x_1, y_1, \dots, x_r, y_r], z) = (\rho(n)([x_1, y_1, \dots, x_r, y_r]), z + n).$$

Then  $p: T^{2r} \times_Z R \longrightarrow S^1$  is a  $T^{2r}$ -bundle where the projection p is given by

$$p[[x_1, y_1, ..., x_r, y_r], z] = [z]$$

Then it is clear that  $T^{2r} \times_Z R$  may be canonically identified to Solv(r).

Since  $j_r(\Gamma_r) \subset \Gamma_{r+1}$  then  $j_r$  induces a canonical embedding

$$J_r: \operatorname{Solv}(r) \longrightarrow \operatorname{Solv}(r+1)$$

If  $\pi_r : S_r \longrightarrow \text{Solv}(r)$  is the canonical projection, then we have a global basis  $\{\alpha_i, \beta_i, \gamma\}$  of 1-forms on Solv(r) such that

$$\pi_r^* \alpha_i = \bar{\alpha}_i, \quad \pi_r^* \beta_i = \beta_i, \quad \pi_r^* \gamma = \bar{\gamma}, \\ d\alpha_i = \alpha_i \wedge \gamma, \quad d\beta_i = -\beta_i \wedge \gamma, \quad d\gamma = 0, \end{cases}$$

and the corresponding dual basis of vector fields, denoted by  $\{X_i, Y_i, Z\}$  verifies

$$[X_i, Z] = -X_i, \qquad [Y_i, Z] = Y_i,$$

the other brackets being all zero. Obviously,  $\bar{X}_i$ ,  $\bar{Y}_i$ ,  $\bar{Z}$  and  $X_i$ ,  $Y_i$ , Z are  $\pi_r$ -related.

Now, for any integer  $s, 1 \leq s < r$ , let us consider the left invariant involutive distribution  $\bar{\mathbf{F}}_s$  on  $S_r$  globally spanned by  $\{\bar{X}_i, \bar{Y}_i, \bar{Z} \mid 1 \leq i \leq s\}$ . Then  $\bar{\mathbf{F}}_s$  is a subalgebra of the Lie algebra of  $S_r$ ; in fact,  $\bar{\mathbf{F}}_s$  is the Lie algebra of the Lie subgroup  $S_s$ . Thus, the leaves of the foliation  $\bar{F}_s$  determined by  $\bar{\mathbf{F}}_s$  are all diffeomorphic to  $S_s$ . Furthermore, since  $\bar{\mathbf{F}}_s$  is left invariant, then it descends to a distribution  $\mathbf{F}_s$  on  $\mathrm{Solv}(r)$ ;  $\mathbf{F}_s$  defines a foliation  $F_s$  on  $\mathrm{Solv}(r)$  whose leaves are all diffeomorphic to  $\mathrm{Solv}(s)$ .

Consider the cosymplectic structure  $(\Phi, \eta)$  on Solv(r) defined by

$$\Phi = \sum_{i=1}^{r} \alpha_i \wedge \beta_i, \qquad \eta = \gamma.$$

A simple computation shows that  $F_s$  is a cosymplectic foliation on the cosymplectic manifold (Solv(r),  $\Phi$ ,  $\eta$ ) and, from Theorem 1, it is stable.

Next, let **F** be the involutive distribution on Solv(r) globally spanned by  $\{X_i, Y_i \mid 1 \leq i \leq r\}$ . Then **F** determines a foliation F on Solv(r) whose leaves are precisely the fibres of the fibration  $p: \text{Solv}(r) \longrightarrow S^1$ , which are 2*r*-dimensional tori. Thus, F is a compact foliation. Furthermore, it is easy to prove that F is a symplectic foliation on the cosymplectic manifold  $(\text{Solv}(r), \Phi, \eta)$  and, from Theorem 1, it is stable. (We notice that this last result follows directly since the leaves of F are the fibres of p, which is a fibration with compact fibres [**9**]).

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