

PRODUCT — CONCIRCULAR CURVATURE TENSOR

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1. Introduction.

In the paper [1] is investigated conformal transformation of a n -dimensional on Riemannian space V_n , given by

$$(1) \quad \bar{g}_{ji} = \rho^2 g_{ji} \quad i, j, = 1, 2, \dots, n$$

which transforms any geodesic circle into a geodesic circle. In the same paper is proved that for such, so-called concircular, transformation condition

$$(2) \quad \rho_{ji} = \Phi g_{ji}$$

must be satisfied, where ρ and φ are scalars, and

$$\rho_{ji} = \nabla_j \rho_i - \rho_j \rho_i + \frac{1}{2} g^{mn} \rho_m \rho_n g_{ji}.$$

$$\rho_i = \frac{\partial(\log \rho)}{\partial u^i}$$

∇ denotes the operator of covariant differentiation.

An invariant of the concircular transformation (1), (2) is the tensor

$$(3) \quad Z_{kji}{}^h = R_{kji}{}^h + \frac{R}{n(n-1)} (\delta_j^h g_{ki} - \delta_k^h g_{ji})$$

where δ_j^i is the Kronecker symbol, R_{kji} Rieman-Christoffel curvature tensor and R curvature tensor.

$Z_{kji}{}^h$ is called *concircular curvature tensor*.

2. Concircular infinitesimal transformation.

Let us give conformal infinitesimal transformation

$$(4) \quad \mathfrak{L} g_{ji} = 2\theta g_{ji}^{1)} \quad \theta \text{ — scalar}$$

of a Riemannian space V_n . From (4) we have

$$(5) \quad \mathfrak{L} \begin{Bmatrix} \tilde{k} \\ ji \end{Bmatrix} = \theta_j \delta_i^k + \theta_i \delta_j^k - \theta^k g_{ji}^{2)}$$

where $\theta_i = \frac{\partial \theta}{\partial u^i}$, and $\theta^i = g^{ia} \theta_a$ and

$$(6) \quad \begin{Bmatrix} k \\ ji \end{Bmatrix} = \begin{Bmatrix} k \\ ji \end{Bmatrix} + (\theta_j dt) \delta_i^k + (\theta_i dt) \delta_j^k - (\theta^k dt) g_{ji}^{3)}$$

where $\begin{Bmatrix} \tilde{k} \\ ji \end{Bmatrix}$ is transform of $\begin{Bmatrix} k \\ ji \end{Bmatrix}$ with respect to transformation (4).

But from (1) we get

$$(7) \quad \begin{Bmatrix} \bar{k} \\ ji \end{Bmatrix} = \begin{Bmatrix} k \\ ji \end{Bmatrix} + \rho_j \delta_i^k + \rho_i \delta_j^k - \rho^k g_{ji}$$

$$\rho_j = \frac{\partial (\log \rho)}{\partial u^j}, \quad \rho^i = g^{ia} \rho_a.$$

Comparing (6) and (7) we see that ρ_i , in the transformation (1), (2) is corresponding to $\theta_i dt$ in the transformation (4).

Now we get for the condition (2) the following form

$$\nabla_j (\theta_i dt) - (\theta_j dt) (\theta_i dt) = \sigma_1 g_{ji} \quad \sigma_1 \text{ — scalar}$$

from which

$$(8) \quad \nabla_j \theta_i = \sigma g_{ji} \quad \sigma = \frac{\sigma}{dt}$$

up to infinitesimals of first order with respect to dt .

By a straightforward calculation we get

$$\mathfrak{L} Z_{kji}^h = 0$$

for transformation (4), (8).

¹⁾ See [3] p. 31.

\mathfrak{L} denotes the operator of Lie derivation with respect to ν^i .

²⁾ See [2] p. 16.

³⁾ See [3] p. 4.

Definition: A transformation (4) which satisfies condition (8) is called *concircular infinitesimal transformation*.

3. Product-concircular infinitesimal transformation.

We shall consider, so-called, product-concircular infinitesimal transformation and find an invariant of it.

Let us give an n -dimensional locally product Riemannian space $V_n = V_p \times V_q$. Then, by definition⁴⁾, there exists a system of coordinate neighbourhoods $\{U_\alpha\}$ such that in each U_α the line element is given by the form

$$ds^2 = g_{ba}(u^c) du^b du^a + g_{yx}(u^z) du^y du^x$$

and in $U_\alpha \cap U_\beta$ the coordinate transformation $(u^a, u^x) \rightarrow (u^{a'}, u^{x'})$ is given by the form

$$u^{a'} = u^{a'}(u^a), \quad u^{x'} = u^{x'}(u^x)$$

Such coordinate system will be called a separating coordinate system.

The existence of a separating coordinate system is equivalent to the existence of a tensor field φ_i^h ($\varphi_i^h \neq \delta_i^h$) with following properties:

$$\varphi_i^r \varphi_r^h = \delta_i^h$$

$$g_{ri} \varphi_j^r = g_{jr} \phi_i^r = \varphi_{ji}$$

$$\nabla_j \varphi_i^h = 0$$

Matrices (g_{ji}) , (φ_j^h) and (φ_{ji}) in the separating coordinate system are given by the form

$$(9) \quad \begin{aligned} (g_{ji}) &= \begin{pmatrix} g_{ba} & 0 \\ 0 & g_{yx} \end{pmatrix} \\ (\varphi_j^h) &= \begin{pmatrix} \delta_b^a & 0 \\ 0 & -\delta_y^x \end{pmatrix} \\ (\varphi_{ji}) &= \begin{pmatrix} g_{ba} & 0 \\ 0 & -g_{yx} \end{pmatrix} \end{aligned}$$

⁴⁾ See [2] p. 213.

⁵⁾ The indices a, b, c, d, e run over the range $1, 2, \dots, p$, the indices t, x, y, z over the range $p-1, p+2, \dots, p+q=n$, and the indices h, i, j, k, l, r over the range $1, 2, \dots, p, p+1, \dots, n$. We denote by

$$g_{ba}(u^c) = g_{ba}(u^1, \dots, u^p) \text{ and } g_{yx}(u^z) = g_{yx}(u^{p+1}, \dots, u^n).$$

Let us apply transformation (4), (8) to each of the subspaces V_p and V_q , of a space V_n . We will get in V_p

$$(10) \quad \underset{v}{\mathfrak{L}} g_{ba} = 2 \lambda g_{ba} \quad \nabla_b \lambda_a = \psi_1 g_{ba}$$

where $\lambda = \lambda(u^a)$ and $\psi_1 = \psi_1(u^a)$ are scalars, $\lambda_a = \frac{\partial \lambda}{\partial u^a}$, and in V_q

$$(11) \quad \underset{v}{\mathfrak{L}} g_{yx} = 2 \mu g_{yx} \quad \nabla_y \mu_x = \psi_2 g_{yx}$$

where $\mu = \mu(u^x)$ and $\psi_2 = \psi_2(u^x)$ are scalars, $\mu_x = \frac{\partial \mu}{\partial u^x}$.

From (9), (10), (11), we have the following transformation on V_n

$$(12) \quad \underset{v}{\mathfrak{L}} g_{ji} = 2 (\rho g_{ji} + \sigma \varphi_{ji})$$

where $\rho = \rho(u^i)$ and $\sigma = \sigma(u^i)$ are scalars and satisfy the conditions

$$\rho = \frac{1}{2} (\lambda + \mu)$$

$$\sigma = \frac{1}{2} (\lambda - \mu)$$

$$(13) \quad \rho_i = \varphi_i^r \sigma_r$$

$$(14) \quad \nabla_j \rho_i = \frac{1}{2} (\theta_1 g_{ji} + \theta_2 \varphi_{ji})$$

$$(15) \quad \nabla_j \sigma_i = \frac{1}{2} (\theta_2 g_{ji} + \theta_1 \varphi_{ji})$$

$$(16) \quad \nabla_j \rho^h = \frac{1}{2} (\theta_1 \delta_j^h + \theta_2 \varphi_j^h)$$

$$(17) \quad \nabla_j \sigma^h = \frac{1}{2} (\theta_2 \delta_j^h + \theta_1 \varphi_j^h)$$

$$(18) \quad x = \nabla_r \rho^r = \frac{1}{2} (n \theta_1 + \varphi \theta_2)$$

$$(19) \quad y = \nabla_r \sigma^r = \frac{1}{2} (\varphi \theta_1 + n \theta_2)$$

where

$$\theta_1 = \frac{1}{2} (\psi_1 + \psi_2), \quad \theta_2 = \frac{1}{2} (\psi_1 - \psi_2), \quad n = \delta_r^r = p + q, \quad \varphi = \varphi_r^r = p - q.$$

Definition: A transformation (12), (13), (14) of n -dimensional locally product Riemannian space V_n is called *product-concircular infinitesimal transformation*.

From above, by straight-forward calculation we obtain

$$\begin{aligned}
 \underset{v}{\mathfrak{L}} g^{ji} &= -2(\rho g^{ji} + \sigma \varphi^{ji}) & \varphi^{ji} &= \varphi_r^j g^{ri} \\
 \underset{v}{\mathfrak{L}} \varphi_{ji} &= 2(\sigma g_{ji} + \rho \varphi_{ji}) \\
 \underset{v}{\mathfrak{L}} \varphi^{ji} &= -2(\sigma g^{ji} + \rho \varphi^{ji}) \\
 \underset{v}{\mathfrak{L}} \{j_i\}^h &= \rho_j \delta_i^h + \rho_i \delta_j^h - \rho^h g_{ji} + \sigma_j \varphi_i^h + \sigma_i \varphi_j^h - \sigma^h \varphi_{ji} \\
 (20) \quad \underset{v}{\mathfrak{L}} R_{kji}{}^h &= \delta_j^h \nabla_k \rho_i - \delta_k^h \nabla_j \rho_i + g_{ki} \nabla_j \rho^h - g_{ji} \nabla_k \rho^h + \\
 &\quad + \varphi_j^h \nabla_k \sigma_i - \varphi_k^h \nabla_j \sigma_i + \varphi_{ki} \nabla_j \sigma^h - \varphi_{ji} \nabla_k \sigma^h \\
 \underset{v}{\mathfrak{L}} R_{ji} &= -(n-4) \nabla_j \rho_i - \varphi \nabla_j \sigma_i - x \cdot g_{ji} - y \cdot \varphi_{ji} \\
 \underset{v}{\mathfrak{L}} R_j^h &= -(n-4) \nabla_j \rho^h - \varphi \cdot \nabla_j \sigma^h - x \delta_j^h - y \cdot \varphi_j^h - \\
 &\quad - 2(\rho R_j^h + \sigma R_j^{*h}) \\
 (21) \quad \underset{v}{\mathfrak{L}} R &= -2(n-2)x - 2\varphi y - 2\rho R - 2\sigma R^* \\
 \underset{v}{\mathfrak{L}} R_{ji}^* &= -\varphi \cdot \nabla_j \rho_i - (n-4) \nabla_j \sigma_i - y \cdot g_{ji} - x \cdot \varphi_{ji} \\
 \underset{v}{\mathfrak{L}} R_j^{*h} &= -\varphi \cdot \nabla_j \rho^h - (n-4) \nabla_j \sigma^h - y \cdot \delta_j^h - x \cdot \varphi_j^h - \\
 &\quad - 2(\sigma R_j^h + \rho R_j^{*h}) \\
 (22) \quad \underset{v}{\mathfrak{L}} R^* &= -2\varphi x - 2(n-2)y - 2\sigma R - 2\rho R^* \\
 \underset{v}{\mathfrak{L}} r_{kji}{}^h &= 2(\rho r_{kji}{}^h + \sigma r_{kji}^{*h}) \\
 \underset{v}{\mathfrak{L}} r_{kji}^{*h} &= 2(\sigma r_{kji}{}^h - \rho r_{kji}^{*h})
 \end{aligned}$$

where

$$\begin{aligned}
 R_{kji}{}^h &= \frac{\partial}{\partial u^k} \left\{ \begin{matrix} h \\ ji \end{matrix} \right\} - \frac{\partial}{\partial u^j} \left\{ \begin{matrix} h \\ ki \end{matrix} \right\} + \left\{ \begin{matrix} h \\ kl \end{matrix} \right\} \left\{ \begin{matrix} l \\ ji \end{matrix} \right\} - \left\{ \begin{matrix} h \\ jl \end{matrix} \right\} \left\{ \begin{matrix} l \\ ki \end{matrix} \right\} \\
 R_{ji} &= R_{rji}{}^r & R_{ji}^* &= R_{jr} \cdot \varphi_i^r \\
 R_j^h &= R_{jr} g^{rh} & R_j^{*h} &= R_{jr} \cdot \varphi^{rh} = R_j^r \cdot \varphi_r^h
 \end{aligned}$$

$$R = R_r^r = R_{ji} g^{ji} \quad R^* = R_r^*{}^r = R_{ji} \varphi^{ji}$$

$$r_{kji}{}^h = \delta_j^h g_{ki} - \delta_k^h g_{ji} + \varphi_j^h \varphi_{ki} - \varphi_k^h \varphi_{ji}$$

$$r_{kji}^*{}^h = \varphi_j^h g_{ki} - \varphi_k^h g_{ji} + \delta_j^h \varphi_{ki} - \delta_k^h \varphi_{ji} = r_{kji}{}^r \cdot \varphi_r^k$$

Substituting (14), (15), (16), (17), (18), (19) in (20), (21), (22) we obtain

$$(20') \quad \underset{\nu}{\mathfrak{E}} R_{kji}{}^h = \theta_1 r_{kji}{}^h + \theta_2 r_{kji}^*{}^h$$

$$(21') \quad \underset{\nu}{\mathfrak{E}} R = -\theta_1 [n(n-2) + \varphi^2] - \theta_2 \cdot 2\varphi(n-1) - 2(\rho R + \sigma R^*)$$

$$(22') \quad \underset{\nu}{\mathfrak{E}} R^* = -\theta_1 \cdot 2\varphi(n-1) - \theta_2 [n(n-2) + \varphi^2] - 2(\rho R + \sigma R^*)$$

and from this

$$\underset{\nu}{\mathfrak{E}} E_{kji}{}^h = 0$$

where

$$(23) \quad E_{kji}{}^h = R_{kji}{}^h + (\alpha R + \beta R^*) r_{kji}{}^h + (\beta R + \alpha R^*) r_{kji}^*{}^h$$

$$\alpha = \frac{n(n-2) + \varphi^2}{[n(n-2) + \varphi^2]^2 - 4\varphi^2(n-1)^2}$$

$$\beta = \frac{-2\varphi(n-1)}{[n(n-2) + \varphi^2]^2 - 4\varphi^2(n-1)^2}$$

Tensor (23) is invariant under the transformation (12), (13), (14), and has following properties:

a) $E_{kji}{}^h$ is pure in all its indices, that is, all its components are identically zero except $E_{cba}{}^d$ and $E_{zyx}{}^t$. Moreover, $E_{cba}{}^d$ are functions of u^a only, and $E_{zyx}{}^t$ are functions of u^x only. The above statements follow from the corresponding properties of tensors $R_{kji}{}^h$ and $r_{kji}{}^h$.

b) 1° $E_{cba}{}^d = Z_{cba}{}^d$ 2° $E_{zyx}{}^t = Z_{zyx}{}^t$

1° Indeed,

$$\begin{aligned} E_{cba}{}^d &= R_{cba}{}^d + (\alpha R + \beta R^*) r_{cba}{}^d + (\beta R + \alpha R^*) r_{cba}^*{}^d = \\ &= R_{cba}{}^d + (\alpha R_{ji} g^{ji} + \beta R_{ji} \varphi^{ji}) r_{cba}{}^d + \\ &+ (\beta R_{ji} g^{ji} + \alpha R_{ji} \varphi^{ji}) r_{cba}^*{}^d \end{aligned}$$

Since

$$R_{ji} g^{ji} = R_{ba} g^{ba} + R_{yx} g^{yx} = \overset{(p)}{R} + \overset{(q)}{R}$$

$$R_{ji} \varphi^{ji} = R_{ba} \varphi^{ba} + R_{yx} \varphi^{yx} = \overset{(p)}{R} - \overset{(q)}{R}$$

where $R^{(p)}$ and $R^{(q)}$ are curvature scalars of the spaces V_p and V_q respectively and

$$r_{cba}{}^d = r_{cba}{}^{*d} = 2(\delta_b^d g_{ca} - \delta_c^d g_{ba})$$

$$n = p + q$$

$$\varphi = p - q$$

we obtain finally

$$E_{cba}{}^d = R_{cba}{}^d + \frac{R^{(p)}}{p(p-1)}(\delta_b^d g_{ca} - \delta_c^d g_{ba}) = Z_{cba}{}^d$$

The proof of 2° is similar.

Since the projections of the tensor $E_{kji}{}^h$ into spaces V_p and V_q are concircular curvature tensors (b), tensor $E_{kji}{}^h$ we call the *product-concircular curvature tensor*.

It is interesting that the same tensor is obtained in the paper [5] in totally different way.

BIBLIOGRAPHY

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