

COINCIDENCE DEGREE AND RABINOWITZ'S BIFURCATION THEOREM

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1. Introduction

In [17] Rabinowitz investigates the structure of solutions of a nonlinear eigenvalue problem of the form $x = G(\lambda, x)$ where $G: \mathbf{R} \times X \rightarrow X$ is a completely continuous, in 0 Fréchet-differentiable operator and X a Banach space. He demonstrates the existence of continua of solutions and gives an alternative description of them. Applications are given to nonlinear Sturm-Liouville problems for second-order ordinary differential equations, to nonlinear eigenvalue problems for a class of quasilinear elliptic partial differential equations on bounded domains in \mathbf{R}^n , and to Hammerstein integral equations with oscillation kernels ([17], [18], [19]).

In dealing with differential equations on unbounded domains the assumption of a completely continuous nonlinearity has to be relaxed. Thus Stuart [10] considers the operator equation $x = \lambda Nx$, where $N: X \rightarrow X$ is a k -set-contraction.

On the other hand the study of nonlinear Steklov problems leads Stuart and Toland [22] to an extension of Rabinowitz's result to the case, where the derivative of G has the form $A_1 + \lambda A_2$.

In his thesis Laloux [10] shows, that some technical assumptions which Stuart and Toland had to suppose, can be avoided by using an extension of Rabinowitz's result for a bifurcation equation $Lx = N(\lambda, x)$, where X, Y are Banach spaces, $L: X \supseteq D(L) \rightarrow Y$ is a Fredholm operator with index 0 and $N: X \rightarrow Y$ is completely continuous. Some other applications are also given.

In proving their alternative results Rabinowitz and Stuart use the Leray-Schauder respectively the Nussbaum degree. The extension, given by Laloux, is based on a coincidence degree for completely continuous nonlinearities, established by J. Mawhin in [14]. Using coincidence degree for k -set-contractions [5], we derive Stuart's result for operator equations $Lx = \lambda Nx$, where L is like above, but N is a k -set-contraction (Section 3. and 4.).

In Section 5. we reduce as an application a boundary value problem for a nonlinear functional differential equation of neutral type to an eigenvalue problem for a linear functional integral equation. In Section 2. we collect some later needed definitions and results.

2. Preliminaries

Let X be a real Banach space. The set-measure of noncompactness γ of a subset M of X is defined by:

$\gamma(M) := \inf \{ \varepsilon \mid \varepsilon > 0, \text{ there exists a finite covering of } M \text{ by subsets of } X \text{ with diameter lower than } \varepsilon \}$.

Assume that Y is a further real Banach space, $\Omega \subseteq X$ and $k \in \mathbf{R}^+$, then a continuous function $f: \Omega \rightarrow Y$ is called k -set-contraction, if $\gamma(f(M)) \leq k\gamma(M)$ for each bounded subset M of Ω . Usually a 0-set-contraction is said to be completely continuous (compact). We introduce the following notation: $D(f)$ means the domain of f , $R(f)$ the range of f . If $L: X \supseteq D(L) \rightarrow Y$ is a linear operator, $\text{Ker}(L)$ denotes the null space of L , and we set:

$$\alpha(L) := \dim(\text{Ker}(L)), \quad \beta(L) := \dim(Y/R(L)),$$

where $\alpha(L) = \infty$ respectively $\beta(L) = \infty$ in the infinite dimensional case:

L is called a Φ_+ -operator, if L is closed, $R(L)$ is closed, and $\alpha(L) < \infty$, and a Fredholm operator, if additionally $\beta(L) < \infty$. If L is a Fredholm operator, $\text{ind}(L) := \alpha(L) - \beta(L)$ means the (Fredholm-) index of L . Further we set:

$$l(L) := \sup \{ r \mid r \in \mathbf{R}^+, r\gamma(M) \leq \gamma(L(M)) \text{ for each bounded } M \subseteq D(L) \}$$

In [5] is shown that for a closed operator L , $l(L) > 0$, if and only if L is a Φ_+ -operator. Basic for the sequel is the concept of coincidence degree, given in [5]. We sketch the here needed case; we assume:

- (a) X, Y are Banach spaces, $L: X \supseteq D(L) \rightarrow Y$ is a Fredholm operator, and $\text{ind}(L) = 0$.
- (b) $\Omega \subseteq X$ is open and bounded, $\Omega \cap D(L) \neq \emptyset$, $N: \bar{\Omega} \rightarrow Y$ is a k -set-contraction with $0 \leq k < 1(L)$.
- (c) $Lx \neq Nx$ for $x \in \partial\Omega \cap D(L)$, where $\partial\Omega$ denotes the boundary of Ω .

From (a) we deduce the existence of continuous projectors $P: X \rightarrow X$, $Q: Y \rightarrow Y$ with $R(P) = \text{Ker}(L)$ and $\text{Ker}(Q) = R(L)$, and of a linear isomorphism $J: R(Q) \rightarrow R(P)$. Further we set $L_P := L|_{\text{Ker}(P) \cap D(L)}$ and remark that L_P^{-1} is continuous according to (a). Finally let $M_J: \bar{\Omega} \rightarrow X$ be defined by:

$$M_J := P + J \circ Q \circ N + L_P^{-1} \circ (I - Q) \circ N$$

then M_J is a $k/1(L)$ -set-contraction and $0 \notin (I - M_J)(\partial\Omega)$, since (b) and (c) are satisfied. Therefore we can define the coincidence degree of (L, N) by:

$$D_J[(L, N), \Omega] := \text{deg}(I - M_J, \Omega, 0)$$

where deg denotes the degree for k -set-contractions with $0 \leq k < 1$, [15]. $D_J[(L, N), \Omega]$ is independent of P and Q and has the following properties;

- (1) $D_J[(L, N), \Omega] \neq 0$ implies that there exists an

$$x \in \Omega \cap D(L) \text{ with } Lx = Nx.$$

- (2) If Ω_1, Ω_2 are open subsets of Ω with $\Omega_1 \cap \Omega_2 = \emptyset$ and $\{x \mid x \in \Omega \cap D(L), Lx = Nx\} \subseteq \Omega_1 \cup \Omega_2$, then:

$$D_J[(L, N), \Omega] = D_J[(L, N), \Omega_1] + D_J[(L, N), \Omega_2].$$

- (3) If $\tilde{N}: [0, 1] \times \bar{\Omega} \rightarrow Y$ is a k -set-contraction with

$$Lx \neq \tilde{N}(\lambda, x) \text{ for each } x \in \partial\Omega \cap D(L) \text{ and } \lambda \in [0, 1], \text{ then}$$

$$D_J[(L, \tilde{N}(0, \circ)), \Omega] = D_J[(L, N(1, \circ)), \Omega].$$

For convenience we set: $D[(L, N), \Phi] = 0$. Then one obtains the following, later needed homotopy property from proposition 7 in [15]:

Lemma 1: Assume that (a) is satisfied, I is a compact interval in \mathbf{R} and $\Phi \neq \Omega \subseteq I \times X$ is open and bounded in $\mathbf{R} \times X$ with $pr_2(\Omega) \cap D(L) \neq \Phi$, where $pr_2: \mathbf{R} \times X \rightarrow X$ denotes the projection on X . Let $F: \Omega \rightarrow Y$ be continuous and $k \in [0, 1(L))$ with: $\gamma(F(B)) \leq k\gamma(pr_2(B))$ for each $B \subseteq \Omega$. Furthermore set $\Omega_t := \{x \mid (t, x) \in \Omega\}$ for $t \in I$. Then $D[(L, F(t, \circ)), \Omega_t]$ is independent of $t \in I$, provided that $Lx \neq F(t, x)$ for all $(t, x) \in \partial\Omega \cap D(L)$.

We end this section with the definition of a coincidence index. Assume that (a) and (b) hold, but Ω is not necessary bounded, and that $\bar{x} \in \Omega \cap D(L)$ is an isolated coincidence point of (L, N) . For each $B_\rho := \{x \mid x \in X, \|x - \bar{x}\| \leq \rho\}$ with $Lx \neq Nx$ for each $\bar{x} \neq x \in B_\rho \cap D(L)$ $D[(L, N), \overset{\circ}{B}_\rho]$ is defined and independent of ρ . Therefore we can define the coincidence index by:

$$i[(L, N), \bar{x}] = D[(L, N), \overset{\circ}{B}_\rho]$$

Additivity and homotopy property can be deduced, using the corresponding assertions for the coincidence degree.

3. Rabinowitz's Theorem for (L, N)

We recall the following definitions:

Definition 1: Let X, Y be Banach spaces, and $L: X \supseteq D(L) \rightarrow Y$ and $A: X \rightarrow Y$ be linear, then $\lambda \in \mathbf{R}$ is called a characteristic value of (L, A) , if $\text{Ker}(L - \lambda A) \neq \{0\}$, otherwise regular.

Definition 2: Let X, Y be Banach spaces, $L: X \supseteq D(L) \rightarrow Y$ be linear, and $N: \mathbf{R} \times X \rightarrow Y$ continuous with $N(\lambda, 0) = 0$ for each $\lambda \in \mathbf{R}$, then $(\mu, 0)$ is called a bifurcation point, if for every $\varepsilon > 0$ there exists $(\lambda, x) \in \mathbf{R} \times X$ with: $|\lambda - \mu| < \varepsilon$, $0 < \|x\| < \varepsilon$, and $Lx = N(\lambda, x)$.

In the sequel we suppose:

(H 1) X, Y are Banach spaces over \mathbf{R} , $L: X \supseteq D(L) \rightarrow Y$

is a Fredholm operator with $\text{ind}(L) = 0$.

(H2) $N: X \rightarrow Y$ is a k -set-contraction with $k \in [0, 1(L))$,

$A, B: X \rightarrow Y$ are continuous maps with:

$$A \text{ linear, } \lim_{\|x\| \rightarrow 0} \frac{\|Bx\|}{\|x\|} = 0, \text{ and } N = A + B.$$

Under these assumptions we consider the bifurcation problem $Lx = \lambda Nx$. The restriction, concerning λ in regard to [17], [18] and [11], is caused by the fact, that the contraction constant is dependent on λ in contrast to the case, where N is compact.

We need the following assertions:

Lemma 2: *Let (H1) be satisfied, $A: X \rightarrow Y$ be a linear k -set-contraction with $k \in [0, 1(L))$, and $\mu \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)^{1)}$ be regular. Then the set of characteristic values in each compact subinterval of $\left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ is finite.*

Proof: The case $k=0$ (i.e. A is completely continuous) is proven in [13]. Hence assume $k \in (0, 1(L))$. Since μ is regular, $L - \mu A$ is injective. Therefore $\lambda \in \mathbf{R}$ is a characteristic value of (L, A) , if and only if λ is a characteristic value of

$$(L - \mu A)^{-1} \circ (L - \lambda A) = I - (\lambda - \mu)(L - \mu A)^{-1} \circ A.$$

Now assume that $\varepsilon > 0$ is sufficiently small. We show:

Case 1: If $\mu \geq 0$, the set of characteristic values in $\left[0, \frac{1(L)}{k} - \varepsilon\right]$ is finite, and there is a regular value of (L, A) in $\left[-\frac{1(L)}{k} + \varepsilon, 0\right]$. Since $1(L - \mu A) \geq 1(L) - \mu k$ ([5] Theorem 2), $T := \left(\frac{1(L)}{k} - \varepsilon - \mu\right)(L - \mu A)^{-1} \circ A$ is an α -set-contraction with $\alpha = \left(\frac{1(L)}{k} - \varepsilon - \mu\right)k(1(L) - \mu k)^{-1} < 1$. Using [1] Theorem 12, we obtain: The set of characteristic values in $[-1, 1]$ of (I, T) is finite, hence the set of (L, A) in $\left[-\frac{1(L)}{k} + \varepsilon + 2\mu, \frac{1(L)}{k} - \varepsilon\right]$. If $-2\mu > -\frac{1(L)}{k} + \varepsilon$, case 1 is proved. Otherwise we choose a regular value μ_1 with; $\mu_1 \leq \mu - \frac{1}{2}\left(\frac{1(L)}{k} - \varepsilon - \mu\right) = -\frac{1}{2}\left(\frac{1(L)}{k} - \varepsilon - 3\mu\right)$, and repeat the above described process. Then we receive: (L, A) has only a finite number of characteristic values in $\left[-\frac{1(L)}{k} + \varepsilon + 2\mu_1, \frac{1(L)}{k} - \varepsilon\right]$. Since $-\frac{1(L)}{k} + \varepsilon + 2\mu - \left(-\frac{1(L)}{k} + \varepsilon + 2\mu_1\right) \geq \frac{1(L)}{k} - \varepsilon - \mu > 0$ we obtain case 1 after a finite number of steps.

¹⁾ For $k=0$ we put $1(L)/k = \infty$

Case 2: If $\mu \leq 0$, the set of characteristic values in $\left[-\frac{1(L)}{k} + \varepsilon, 0\right]$ is finite and there exist a regular value of (L, A) in $\left(0, \frac{1(L)}{k} - \varepsilon\right)$.

Obviously this assertion can be reduced to case 1 by considering $(L, -A)$ and $-\mu$.

Both cases give the conclusion of Lemma 2.

Lemma 3: Let (H 1) and (H 2) be satisfied, and assume that $\mu \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ is not a characteristic value of (L, A) . Then $(\mu, 0)$ is not a bifurcation point for (L, N) .

Proof: (H2) implies that A is the Fréchet derivate of N in 0. Therefore A is a k -set-contraction according to [16]. Hence $L - \mu A$ is a Fredholm operator with index 0 [7], so $L - \mu A$ is bijective, because μ is not characteristic value of (L, A) . Then there exists an $m > 0$ with: $\|(L - \mu A)x\| \geq m \|x\|$ for $x \in D(L)$. On the other hand there is an open ball K with center 0 and a $c \in \left(0, \frac{m}{2(|\mu| + 1)}\right)$ with $\|Bx\| \leq c \|x\|$ for $x \in K$. Set $\delta := \frac{1}{\|A\| + c} \left(\frac{m}{2} - |\mu|c\right)$. Then we have for $\lambda \in \mathbf{R}$ with $|\lambda - \mu| \leq \delta$ and $x \in K$:

$$\begin{aligned} \|Lx - \lambda Nx\| &= \|Lx - \lambda Ax - \lambda Bx\| = \|Lx - \mu Ax - (\lambda - \mu)Ax - \\ &\quad - \lambda Bx\| \geq m \|x\| - |\lambda - \mu| \|A\| \|x\| - (|\mu| + \delta) c \|x\| \geq \\ &\quad \geq (m - \delta(\|A\| + c) - |\mu|c) \|x\| = \frac{m}{2} \|x\|. \end{aligned}$$

So μ is not a bifurcation point.

We set $E := \mathbf{R} \times X$, equipped with the norm $\|(\lambda, x)\| := (|\lambda|^2 + \|x\|^2)^{\frac{1}{2}}$ and Γ to be the closure of $\{(\lambda, x) | (\lambda, x) \in E, x \neq 0, Lx = \lambda Nx\}$ in E . We state:

Lemma 4: Assume that (H 1) and (H 2) are satisfied, and that μ is an isolated characteristic value of (L, A) in $\left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$. If φ denotes the component of $\Gamma \cup \{(\mu, 0)\}$ in E with $(\mu, 0) \in \varphi$, suppose that φ fulfills: φ is bounded, φ contains only μ as a characteristic value of (L, A) and

$$\inf \left\{ \left| \lambda \pm \frac{1(L)}{k} \right| \mid (\lambda, x) \in \varphi \right\} > 0.$$

Then there are a bounded, open subset 0 of $\left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right) \times X$, a $\rho > 0$ and an $\eta > 0$ with:

- (1) $\varphi \subseteq 0$.
- (2) $\Gamma \cap \partial 0 = \emptyset$
- (3) $\overline{pr_1(0)} \subseteq \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$, where $pr_1: E \rightarrow \mathbf{R}$ is the projection on \mathbf{R} ,

(4) $(\lambda, x) \in 0$ and $|\lambda - \mu| \geq \rho$ imply $\|x\| \geq \eta$

(5) $\lambda \neq \mu$ and $\lambda \in [-\rho + \mu, \rho + \mu]$ imply λ regular.

The proof of this Lemma follows the argument used in [20] to prove Lemma 1.7. We note that Lemma 2 ensures the finiteness of the set of characteristic values in each compact subset of $\left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$, and that Lemma 3 has to be used instead of proposition 1.5. there. Using the fact, that for a sequence $(\lambda_n, x_n) \in (\mathbf{R} \times X)^N$ with $Lx_n = \lambda_n Nx_n$ holds:

$$\gamma(\{x_n | n \in \mathbf{N}\}) \leq \frac{1}{1(L)} \gamma(\{Lx_n | n \in \mathbf{N}\}) = \frac{1}{1(L)} \gamma(\{\lambda_n Nx_n | n \in \mathbf{N}\})$$

the compactness of a closed, bounded subset of Γ can be deduced like there.

If $\mu \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ is an isolated characteristic value of (L, A) , one observes that $i[(L, \lambda N), 0]$ is defined for $0 < |\lambda - \mu| < \delta$ and δ sufficient small in regard to Lemma 3. Now we can state the Rabinowitz alternative in the here considered case:

Theorem 1: *Let (H1) and (H2) be satisfied, and*

$$\mu \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$$

be an isolated charateristic value. φ, Γ are defined as in Lemma 4.

$$\text{If } \lim_{\lambda \rightarrow \mu^-} i[(L, \lambda N), 0] \neq \lim_{\lambda \rightarrow \mu^+} i[(L, \lambda N), 0],$$

then one of the following assertions holds:

- (i) φ is unbounded.
- (ii) φ meets $(\tilde{\mu}, 0)$ with $\tilde{\mu} \neq \mu$,
- (iii) $\inf \left\{ \left| \lambda \pm \frac{1(L)}{k} \right| \mid (\lambda, x) \in \varphi \right\} = 0$.

The proof is analogous to the corresponding in [19] and [20]. We indicate it:

If φ does not satisfy (i) – (iii), assertions (1) – (5) of Lemma 4 hold. Define;

$$r(\lambda) := \begin{cases} \frac{1}{2} \inf \{ \zeta \mid \zeta > 0, \text{ there is an } x \in D(L) \text{ with:} \\ \quad Lx = \lambda Nx \text{ and } \|x\| = \zeta, \text{ if } \lambda \in [\mu - \rho, \mu + \rho] \\ \frac{1}{2} \eta, \text{ if } \lambda \in \mathbf{R} \setminus [\mu - \rho, \mu + \rho] \end{cases}$$

For each $\varepsilon > 0$ there exists an $a > 0$ with: $r(\lambda) \geq a$ for $\lambda \in \mathbf{R} \setminus [\mu - \varepsilon, \mu + \varepsilon]$. Let $O_\lambda := \{x \mid x \in X, (\lambda, x) \in 0\}$ and $K_{r(\lambda)} := \{x \mid x \in X, \|x\| \leq r(\lambda)\}$, then for $\lambda \neq \mu$ $D[(L, \lambda N), O_\lambda \setminus K_{r(\lambda)}]$ is defined. Choose $c \in \mathbf{R}^+$, such that

$$c < \frac{1(L)}{k} \text{ and } O_{\pm c} = \emptyset.$$

Using Lemma 1 $D[(L, \lambda N), O_\lambda \setminus K_{r(\lambda)}]$ is constant for $\lambda \in [\Lambda, c]$ and $\mu < \Lambda < c$. Hence $D[(L, \lambda N), O_\lambda \setminus K_{r(\lambda)}] = 0$ for $\lambda \in (\mu, c)$. The same assertion holds for $\lambda \in -(c, \mu)$. On the other hand $D[(L, \lambda N), O_\lambda]$ is defined for $\lambda \in [\mu - \delta, \mu + \delta]$ and δ sufficient small, and is constant, using Lemma 1. Now property (2) of the coincidence degree involves that $D[(L, \lambda N), \overset{\circ}{K}_{r(\lambda)}]$ is constant for $\lambda \neq \mu$ and $\lambda \in [\mu - \delta, \mu + \delta]$. Hence: $\lim_{\lambda \rightarrow \mu^-} i[(L, \lambda N), 0] = \lim_{\lambda \rightarrow \mu^+} i[(L, \lambda N), 0]$.

Remarks:

- (1) An example for computing the coincidence index of $(L, \lambda N)$ near an isolated characteristic value without using the multiplicity of $(L, \lambda A)$, can be found in [12].
- (2) In applications (e. g. Lyapunov's integral power series [9]) it is possible that one has to restrict the nonlinearity N on a subset of X , to get a suitable k -set-contraction. The following assertion holds in this case: Let the assumptions of Theorem 1 be satisfied, but $D(N) = \bar{\Omega}$, where Ω is an open subset of X with $\Omega \cap D(L) \neq \emptyset$, then φ fulfills one of the assertion (i) – (iii) in Theorem 1, or there is an $(\lambda, x) \in \varphi$ with $x \in \partial \Omega$.

4. The case of odd multiplicity

We introduce the concept of multiplicity of a characteristic value of (L, A) given by Laloux and Mawhin [13]. The extension, we need is obvious.

In addition to (H1) and (H2) we assume;

(H3) $Ax \in R(L)$ for $x \in \text{Ker}(L) \setminus \{0\}$.

Then there exists a unique projector $Q_A: Y \rightarrow Y$ with $R(Q_A) = A(\text{Ker}(L))$ and $\text{Ker}(Q_A) = R(L)$. For each continuous projector $P: X \rightarrow X$ with $R(P) = \text{Ker}(L)$ the set of nonzero characteristic values for (L, A) is equal to the set of characteristic values of (I, K_P) , where $K_P := L_P^{-1} \circ (I - Q_A) \circ A$. Using results of Ambrosetti [1], we obtain, that the characteristic values of (L, A) in $\left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ are at most countable with possible accumulation points $-\frac{1(L)}{k}$ or $\frac{1(L)}{k}$. For a nonzero characteristic value $\lambda \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ of (L, A) , λK_P is an α -set-contraction with $\alpha < 1$ and therefore $\lim_{i \rightarrow \infty} \dim(\text{Ker}(I - \lambda K_P)^i)$ is finite.

Hence we can define:

Definition 3: Let (H1)–(H3) be satisfied and K_p be defined like above. If $\lambda \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ is a characteristic value of (L, A) we call

$$v(\lambda) := \begin{cases} \lim_{i \rightarrow \infty} \dim(\text{Ker}(I - \lambda K_p)^i) & \text{for } \lambda \neq 0 \\ \dim(\text{Ker}(L)) & \text{for } \lambda = 0 \end{cases}$$

the multiplicity for λ of (L, A) .

Remark: In the case where $X = Y$ and $L = I$, $v(\lambda)$ is equal to the classical definition of multiplicity of λA .

Using this Definition and following the arguments of the proofs to Theorem 5.1 and Corollary 5.1 in [13] we can state:

Lemma 5: Let (H1)–(H3) be fulfilled and $\mu_1, \mu_2 \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ be regular values of (L, A) with $\mu_1 < \mu_2$. Setting $\delta := \sum_{\lambda \in \Lambda} v(\lambda)$, where Λ is the set of characteristic values of (L, A) in (μ_1, μ_2) , we have

$$i[(L, \mu_2 A), 0] = (-1)^\delta i[(L, \mu_1 A), 0].$$

Concerning the proof of this Lemma we have to comment the derivation of the here needed assertion analogous to formula 5.2 in [13]. A correct proof of a product theorem for the Nussbaum degree is unknown to us. But for linear maps one can follow the proof, given by Fenske [4] for the corresponding theorem in his degree theory, using Stuart’s and Toland’s result [21], concerning the connection between classical multiplicity and fixed point index of a linear α -set-contraction with $\alpha < 1$. Finally the separability assumption in [4] can be dropped in view of the following fact. If X is a Banach space and $T: X \rightarrow X$ is a linear α -set-contraction with $0 \leq \alpha < 1$, then $I - T$ is a Fredholm map with index 0, hence $I - T$ surjective, if injective. Therefore each $x \in X$ is regular concerning $I - T$ and one does not need the Smale-Sard-Theorem. We also refer to the remarks in [3].

Using this Lemma we obtain an analogy to Rabinowitz’s results for the case of odd multiplicity.

Theorem 2: Let (H1)–(H3) be satisfied and $\mu \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ be a characteristic value of (L, A) with odd multiplicity. Then the alternative assertion of Theorem 1 is true.

Proof: Let $\lambda \in \left(-\frac{1(L)}{k}, \frac{1(L)}{k}\right)$ be a regular value of (L, A) . Then Lemma 3 implies, that there exists an $\rho_0 > 0$, such that $Lx \neq \lambda Nx$ for each $x \in D(L)$ with $0 < \|x\| \leq \rho_0$. Using (H2), we can further assume, that

$$\|Bx\| \leq \frac{m}{2(|\lambda| + 1)} \|x\| \quad \text{for } \|x\| \leq \rho_0,$$

where $m > 0$ with: $\|(L - \lambda A)x\| \geq m\|x\|$ for $x \in D(L)$ (see proof to Theorem 3). Let $\rho \in (0, \rho_0)$ and set:

$$\tilde{N}(t, x) = t\lambda Nx + (1-t)\lambda Ax$$

for $t \in [0, 1]$ and $x \in K_\rho = \{z \in X, \|z\| \leq \rho\}$ \tilde{N} is a α -set-contraction with $\alpha = |\lambda|k < 1(L)$. Further $x \in \partial K_\rho \cap D(L)$ involves:

$$\begin{aligned} \|Lx - \tilde{N}(t, x)\| &= \|Lx - t\lambda Nx - (1-t)\lambda Ax\| \\ &\geq m\|x\| - t|\lambda| \frac{m}{2(|\lambda| + 1)}\|x\| \geq \frac{m}{2}\|x\| \end{aligned}$$

Hence \tilde{N} is an admissible homotopy and therefore

$$D_J[(L, \lambda N), \overset{\circ}{K}_\rho] = D_J[(L, \lambda A), \overset{\circ}{K}_\rho]$$

for $J: \text{Ker}(L) \rightarrow R(Q_A)$ a linear isomorphism and for any $\rho \in (0, \rho_0)$ (property (3) of the coincidence degree). Now Lemma 5 and Theorem 1 imply the assertion of this Theorem.

Remarks:

- (1) The special case $X = Y, L = I$ is proven by Stuart in [20].
- (2) The corresponding result to remark (2) after Theorem 1 is valid.

5. An application to a functional differential equation of neutral type.

In this section we reduce a nonlinear boundary value problem for a functional differential equation of neutral type to an eigenvalue problem of a linear functional integral equation, using Theorem 2.

First we introduce some notations; Let $n \in \mathbf{N}, s \in \mathbf{Z}^+$ and $|\cdot|$ a norm on \mathbf{R}^n , then $C^s([0, 1], \mathbf{R}^n)$ denotes the Banach space of s -times continuously differentiable \mathbf{R}^n -valued functions with domain $[0, 1]$. We set;

$$\|u\|_\infty := \max\{|u(x)| \mid x \in [0, 1]\} \text{ for } u \in C^0([0, 1], \mathbf{R}^n),$$

$$\|u\|_s := \max\{\|u^{(j)}\|_\infty \mid 0 \leq j \leq s\} \text{ for } u \in C^s([0, 1], \mathbf{R}^n),$$

and assume $\|\cdot\|_s$ to be the norm on $C^s([0, 1], \mathbf{R}^n)$.

For $\sigma: [0, 1] \rightarrow [0, 1]^n$ and $u \in C^0([0, 1], \mathbf{R})$ we set:

$$u \circ \sigma := (u \circ \sigma_1, \dots, u \circ \sigma_n),$$

where $\sigma_1, \dots, \sigma_n$ denote the components of σ .

Now we can state the problem we will consider here. Let

$$p \in C^1([0, 1], \mathbf{R}), m \in \mathbf{N}, a = (a_1, \dots, a_m) \in \mathbf{R}^m \text{ with } \sum_{j=1}^m a_j \neq 0,$$

$\sigma = (\sigma_1, \dots, \sigma_m) \in C([0, 1], \mathbf{R}^m)$ with $\sigma_j(x) = x$ for $x \in [0, 1]$ and $R(\sigma_j) \subseteq [0, 1]$ for $2 \leq j \leq m$, and $f \in C([0, 1] \times \mathbf{R}^{3m}, \mathbf{R})$. We seek $\lambda \in \mathbf{R}$ and $u \in C^2([0, 1], \mathbf{R})$ with:

$$(BVP) \begin{cases} (p(x) u'(x))' = \langle \lambda a, u \circ \sigma(x) \rangle + f(x, u \circ \sigma(x), u' \circ \sigma(x), u'' \circ \sigma(x)) \\ u(0) = u(1), u'(0) = u'(1) \end{cases}$$

where \langle, \rangle denotes the euclidian scalar product of the \mathbf{R}^m . We obtain:

Theorem 3: *Suppose that p, m, a, σ and f satisfy the above described assumptions, and that $p_0 := \min\{p(x) \mid x \in [0, 1]\} > 0$. Further assume:*

(1) *There is a $k \in \mathbf{R}^+$ with:*

$$|f(x, \zeta_1, \zeta_2, \zeta_3) - f(x, \zeta_1, \zeta_2, \zeta_4)| \leq k |\zeta_3 - \zeta_4|$$

for $x \in [0, 1], \zeta_1, \dots, \zeta_4 \in \mathbf{R}^m$

(2) *$f(\cdot, \zeta_1, \zeta_2, \zeta_3)$ is $o(|\zeta_1| + |\zeta_2| + |\zeta_3|)$ for*

$$|\zeta_1| + |\zeta_2| + |\zeta_3| \rightarrow 0 \text{ uniformly on } [0, 1]$$

(3) *Let $h_1(x, z) := \int_z^x \frac{1}{p(y)} dy$ for $z, x \in [0, 1]$ and*

$$h_2(x, z) := -x \int_z^1 \frac{1}{p(y)} dy - \int_0^x \frac{y}{p(y)} dy + x \int_0^1 \frac{y}{p(y)} dy$$

for $z, x \in [0, 1]$. We assume, that there is a $\lambda_0 \in \left(-\frac{p_0}{k}, \frac{p_0}{k}\right)$ with: λ_0 is an eigenvalue with odd dimensional generalized eigenspace of the linear Volterra-Hammerstein integral equation:

$$(J) \begin{cases} u(x) = \lambda \int_0^x h_1(x, z) \langle a, u \circ \sigma(z) \rangle dz + \lambda \int_0^1 h_2(x, z) \langle a, u \circ \sigma(z) \rangle dz \\ u \in C^2([0, 1], \mathbf{R}^n); u(0) = u(1), u'(0) = u'(1) \end{cases}$$

Then there exists a continuum $\varphi \subseteq \mathbf{R} \times C^2([0, 1], \mathbf{R})$ of solutions of (BVP) with $(\lambda_0, 0) \in \varphi$, which satisfies one of the following assertions:

(i) φ is unbounded.

(ii) There exists a further eigenvalue $\lambda_1 \in \left(-\frac{p_0}{k}, \frac{p_0}{k}\right)$ with $\lambda_1 \in \varphi$

(iii) $\inf \left\{ \left| \lambda \pm \frac{p_0}{k} \right| \mid (\lambda, u) \in \varphi \right\} = 0$

Proof: We establish the hypothesis of Theorem 2. Set

$$X := \{u \mid u \in C^2([0, 1], \mathbf{R}), u(0) = u(1), u'(0) = u'(1)\}, Y := C^0([0, 1], \mathbf{R} \Gamma),$$

and assume, that $\|\cdot\|_2$ respectively $\|\cdot\|_\infty$ are the norms on X respectively Y . Let $L: X \rightarrow Y$ be defined by: $Lu := (pu)'$. We claim, that L is a Fredholm operator with index 0. Obviously L is continuous and $\text{Ker}(L) = \{u \mid u \in X, u \text{ is constant}\}$ is one dimensional. Let $v \in Y$ and $\int_0^1 v(x) dx = 0$, then we set

$$u(x) := \int_0^x \left(\frac{1}{p(y)} \int_0^y v(z) dz \right) dy - x \int_0^1 \left(\frac{1}{p(y)} \int_0^y v(z) dz \right) dy.$$

Obviously $u \in X$ and $Lu = v$. On the other hand, if $v = Lu (u \in X)$, then $u'(0) = u'(1)$ implies: $\int_0^1 v(x) dx = 0$. Hence $R(L) = \{v \mid v \in Y, \int_0^1 v(x) dx = 0\}$ and therefore $\dim(Y/R(L)) = 1$. So L is a Fredholm operator with index 0. Further, following the arguments in the proof to „Satz 8“ in [7], we obtain: $l(L) \geq p_0$. Define $A: X \rightarrow Y$ by: $Au(x) := \langle a, u \circ \sigma(x) \rangle$. A is completely continuous (Arzela-Ascoli). Since $\sum_{j=1}^m a_j \neq 0$ for $u \in \text{Ker}(L), u \neq 0$. $B: X \rightarrow Y$ is defined by:

$$Bu(x) := f(x, u \circ \sigma(x), u' \circ \sigma(x), u'' \circ \sigma(x)), x \in [0, 1].$$

Since f is uniformly continuous on bounded sets of $\mathbf{R} \times \mathbf{R}^{3m}$ and σ is continuous, B is a continuous operator. In regard to assumption (1) we deduce analogously to Theorem 3 in [6], that B is a k -set-contraction. From assumption (2) we receive:

$$\lim_{\|u\|_2 \rightarrow 0} \frac{\|Bu\|_\infty}{\|u\|_2} = \lim_{\|u\|_2 \rightarrow 0} \sup_{x \in [0, 1]} \frac{|f(x, u \circ \sigma(x), u' \circ \sigma(x), u'' \circ \sigma(x))|}{\|u\|_2} = 0$$

Therefore $N := A + B$ is a Fréchet-differentiable map in 0 with derivate A .

For applying Theorem 2 we have to show, that λ_0 is a characteristic value of (L, A) with odd multiplicity. We set $P: X \rightarrow X$ by $Pu(x) := u(0)$ and $Q: Y \rightarrow Y$ by $Qv(x) := \int_0^1 v(x) dx$. P is a continuous projector on $\text{Ker}(L)$ and $L_P^{-1}: \text{Ker}(Q) \rightarrow K(P)$ is given by

$$L_P^{-1} v(x) = \int_0^x \left(\frac{1}{p(y)} \int_0^y v(z) dz \right) dy - x \int_0^1 \left(\frac{1}{p(y)} \int_0^y v(z) dz \right) dy$$

Q satisfies the conditions $\text{Ker}(Q) = R(L)$ and $R(Q) = A(\text{Ker}(L))$ and is therefore the projector Q_A of Section 4. We determine $K_A = L_P^{-1} \circ (I - Q) \circ A$: For $u \in X$ we have, after changing the order of integration:

$$\begin{aligned} K_A u(x) &= \int_0^x \left(\int_z^x \frac{1}{p(y)} dy \right) \langle a, u(z) \rangle dz - \\ &\quad - x \int_0^1 \left(\int_z^1 \frac{1}{p(y)} dy \right) \langle a, u \circ \sigma(z) \rangle dz - \\ &\quad - \left[\int_0^1 \langle a, u \circ \sigma(z) \rangle dz \right] \left[\int_0^x \frac{y}{p(y)} dy \right] + \\ &\quad + x \left[\int_0^1 \frac{y}{p(y)} dy \right] \left[\int_0^1 \langle a, u \circ \sigma(z) \rangle dz \right] \\ &= \int_0^x h_1(x, z) \langle a, u \circ \sigma(z) \rangle dz + \int_0^1 h_2(x, z) \langle a, u \circ \sigma(z) \rangle dz \end{aligned}$$

This implies, that the eigenvalue problem $u = \lambda K_A u$ is equivalent to problem (I). Hence assumption (3) ensures, that λ_0 is a characteristic value of (I, K_A) of odd multiplicity, thus for (L, A) . Therefore all hypotheses of Theorem 2 are satisfied.

Remarks:

- (1) Problem (I) leads to a linear operator equation of the form $I = \lambda(V + C)$, where C is an operator with finite dimensional range. Corresponding to the case of a Volterra equation, $I - \lambda V$ is injective and therefore a linear isomorphism. Hence we can reduce (I) to an operator equation of the form $x = \lambda T(\lambda)x$, where $T(\lambda) = (I - \lambda V)^{-1} \circ C$ is an operator with finite dimensional range.
- (2) A second order functional differential equation of neutral type without parameter λ and with other boundary conditions is considered in [8]. In the here considered case $\sigma_j([0, 1]) \subseteq [0, 1]$ for $2 \leq j \leq m$ can be assumed without loss of generality.
- (3) For convenience we have supposed that a is constant, and that the linear part is independent of u' . Equations without these restrictions can be treated analogously.
- (4) For sufficient large a and suitable $\sigma_j (2 \leq j \leq m)$ there exists an eigenvalue $\lambda_0 \in \left(-\frac{p_0}{k}, \frac{p_0}{k} \right)$.

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