## TRANSFORMATIONS OF MEASURABLE SETS BY AUTOMORPHISM GROUPS

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1. The purpose of this note is to extend the Theorem of [3] into more general settings and at the same time generalize the Theorems of [5] into more general representations.

We follow the notations of [3] and the definitions are standard by [1]. G always denotes locally compact group (regarded Hausdorff by [1]) and  $\mu$  denotes a left Haar measure on G.  $R^+$  denotes the set of all positive real numbers and C denotes the set of all complex numbers. Suppose  $f: G \to C$ . The left and right translations of f are denoted by  $_af$  and  $f_a$  for any  $a \in G$ ; namely  $_af(x) = f(ax)$  and  $f_a(x) = f(xa)$  for all  $x \in G$ .  $L^1(G)$  denotes the Banach space of all complex-valued integrable functions and  $\|\cdot\|$  is used to denote the  $L^1$ -norm. Suppose  $T: G \to G$  and  $f: G \to C$ . Denote  $f_T = f \cdot T: G \xrightarrow{T} G \xrightarrow{f} C$ . We use  $l^A$  to denote the characteristic function of the subset  $l^A$  of  $l^A$  or otherwise.  $l^A$  is understood to be  $l^A \cdot T$ .

Let  $\mathfrak{S}(G)$  denote the collection of all automorphisms of G ([1], page 426). In the following, we will assume as open neighbourhoods of the identity  $l_G$  of  $\mathfrak{S}(G)$ , the collection  $\{\mathfrak{B}(F,U)\}$ , where for a compact subset F of G and U an open neighbourhood of the identity e of G,  $\mathfrak{B}(F,v)$  is the set of all  $\sigma \in \mathfrak{S}(G)$  such that  $\sigma(a) \in Ua$  and  $\sigma^{-1}(a) \in Ua$  for all  $a \in F$ . Then  $\mathfrak{S}(G)$  is a topological group with the topology of open sets of the form  $\cup \{\sigma \mathfrak{B}(F,U)\}$  where  $\sigma \in \mathfrak{S}(G)$  ([1], page 427). It is easy to see that  $(x,\sigma) \to \sigma(x)$  is a continuous mapping of  $G \times \mathfrak{S}(G)$  into G. Hence  $\mathfrak{S}(G)$  is a transformation group on G.

Theorem: Let  $A, B_1, B_2, \ldots, B_n$  be subsets of a locally compact group G of strictly positive finite Haar measure. Then the mapping

$$(x_1, x_2, \ldots, x_n, y_1, y_2, \ldots, y_n, T_1, T_2, \ldots, T_n) \rightarrow \mu [A \cap L_{x_1} R_{y_1} T_1(B_1) \cap L_{x_2} R_{y_2} T_2(B_2) \cap \cdots \cap L_{x_n} R_{y_n} T_n B_n)]$$

is a nontrivial continuous mapping of  $G^{2n} \times [\mathfrak{S}(G)]^n$  into  $R^+$  where  $x_i \in G$ ,  $y_i \in G$ ,  $T_i \in \mathfrak{S}(G)$ ,  $L_{x_i} : G \to G$  and  $R_{y_i} : G \to G$  such that  $L_{x_i}(z) = x_i z$  and  $R_{y_i}(z) = zy_i$  for all  $z \in G$  and  $|\leqslant i \leqslant n$ . The Theorem is irrelevant of the order of  $L_i$ ,  $R_{y_i}$  and  $T_i$ .

2. The following three lemmas are important to the proof of the Theorem.

Lemma 1. There exists a continuous homomorphism  $\rho$  of  $\mathfrak{S}(G)$  into the multiplicative group  $R^+ / \{0\}$  such that for any  $f \in L^1(G)$ , then

$$\int_{G} f_{T}(x) d\mu(x) = \rho(T^{-1}) \int_{G} f(x) d\mu(x)$$

for any  $T \in \mathfrak{S}(G)$ . Hence  $f_T \in L^1(G)$  if  $f \in L^1(G)$  and  $T \in \mathfrak{S}(G)$ .

Proof: As for the existence and continuity of  $\rho$  see [2]. The second part of this Lemma is easy.

Lemma 2: Suppose  $f \in L^1(G)$  and  $\{T_\gamma\}$  is a net in  $\mathfrak{S}(G)$  such that  $T_\gamma \to S \in \mathfrak{S}(G)$ . Then

$$\lim_{\Upsilon} ||f_{T_{\Upsilon}} - f_{S}|| = 0.$$

Proof Given  $\varepsilon > 0$ , choose a continuous function g with compact support K such that

$$||f-g|| \leq \frac{\varepsilon}{4 \rho(S^{-1})}.$$

Then

$$||fr_{Y}-f_{S}|| \leq ||fr_{Y}-gr_{Y}|| + ||gr_{Y}-g_{S}|| + ||g_{S}-f_{S}||$$

$$\leq \rho (T_{Y}^{1-})||f-g|| + \int_{G} |g(T_{Y}(x))-g(S(x))| d\mu(x) + \rho (S^{-1})||g-f||$$

$$\leq \frac{\varepsilon}{2} + \frac{\varepsilon}{4} + \frac{\varepsilon}{4} = \varepsilon, \text{ as } T_{Y} \text{ is sufficiently close to } S.$$

For

$$l = \int_{G} |g(T_{\gamma}(x) - g(S(x)))| d\mu(x)$$
$$= \rho(S^{-1}) \int_{G} |g(T_{\gamma}S^{-1}(x)) - g(x)| d\mu(x)$$

and we can find an open neighbourhood  $\overline{W}$  of e with compact closure  $\overline{W}$  such that  $ST_{\gamma}^{-1}(K) \subset \overline{W}K$  whenever  $T_{\gamma}$  is sufficiently close to S. Hence we have

$$\begin{split} &l = \rho\left(S^{-1}\right) \int\limits_{\overline{W}K} \left| g\left(T_{\gamma} S^{-1}\left(x\right)\right) - g\left(x\right) \right| d\mu\left(x\right) \\ &\leqslant \rho\left(S^{-1}\right) \varepsilon_{1} \mu\left(\overline{W}K\right) \leqslant \frac{\varepsilon}{4}, \text{ (by letting } \varepsilon_{1} \leqslant \frac{\varepsilon}{4 \rho\left(S^{-1}\right) \mu\left(\overline{W}K\right)}, \end{split}$$

because for any  $x \in \overline{W}K$ ,  $[T_{\gamma}S^{-1}(x)x^{-1}]$  is sufficiently close to e whenever  $T_{\gamma}$  is sufficiently close to S.

Lemma 3: Let  $f \in L^1(G)$ . Then  $(x, y, T) \to {}_x(f_T)_y$  is a continuous mapping of  $G^2 \times \mathfrak{S}(G)$  into  $L^1(G)$ .

Proof. For any  $(u, v, S) \in G^2 \times \mathfrak{S}(G)$  we have

$$\| \|_{x}(f_{T})_{y} - \|_{u}(f_{S})_{y} \| \le \| \|_{x}(f_{T})_{y} - \|_{x}(f_{S})_{y} \| + \| \|_{x}(f_{S})_{y} - \|_{u}(f_{S})_{y} \|.$$

By Lemma 1 and Lemma 1 of [3],

$$||_{\mathbf{y}}(f_S)_{\mathbf{y}} - u(f_S)_{\mathbf{y}}|| \to 0 \quad \text{as} \quad (\mathbf{x}, \mathbf{y}) \to (\mathbf{u}, \mathbf{v})$$

and

$$\| x(f_T)_y - x(f_S)_y \| = \Delta (y^{-1}) \| f_T - f_S \| \to 0$$

as  $(x, y, T) \rightarrow (u, v, S)$  by Lemma 2 and the continuity of the modular function  $\Delta$  of G (see [1], [3]).

Hence 
$$\|x(f_T)_y - u(f_S)_y\| \to 0$$
 as  $(x, y, T) \to (u, v, S)$ .

Proof of the Theorem: For any fixed  $(u_1, u_2, ..., u_n, v_1, ..., v_n, S_1, S_2, ..., S_n)$  in  $G^{2n} \times [\mathfrak{S}(G)]^n$ , and any  $(x_1, x_2, ..., x_n, y_1, y_2, ..., y_n, T_1, T_2, ..., T_n)$  in

$$G^{2n} \times [\mathfrak{S}(G)]^n$$
,  $|\mu(A \cap x_1 T_1(B_1) y_1 \cap \cdots \cap x_n T_n(B_n) y_n) - \mu(A \cap u_1 S_1(B_1) y_1)$ 

$$\bigcap \cdots \bigcap u_n S_n(B_n) v_n \leq \sum_{j=1}^n \| l^{x_j T_j(B_j) y_j} - l^{u_j S_j(B_j) y_j} \|$$

(by Lemma 2[3])

$$\leq \sum_{j=1}^{n} \| \sum_{x_{j}^{-1}} \left( l_{T_{j}}^{B_{j}} \right)_{y_{j}^{-1}} - \sum_{u_{j}^{-1}} \left( l_{S_{j}}^{B_{j}} \right)_{y_{j}^{-1}} \| \to 0$$

as  $(x_j, y_j, T_j) \rightarrow (u_j, v_j, S_j)$  for j = 1, 2, ..., n, by lemma 3. Hence the mapping is continuous. By Lemma 3 of [3], it is easy to see that the mapping is non-trivial.

If we change the order of the composition of  $L_{x_i}$ ,  $R_{y_i}$  and  $T_i$ , then the mapping is also continuous and not identically zero since  $\sigma L_x = L_{\sigma(x)} \sigma$ ,  $\sigma R_y = R_{\sigma(y)} \sigma$  and  $(x, \sigma) \to \sigma(x)$  is jointly continuous for any  $\sigma \in \mathfrak{S}(G)$  and  $x, y \in G$ . Now the proof is complete.

Corollary: Suppose  $\infty > \mu(A) > 0$ ,  $\infty > \mu(B) > 0$ . Then for any  $\sigma_0 \in \mathfrak{S}(G)$  there exists an open neighbourhood of W of  $\sigma_0$  such that  $\bigcap_{\sigma \in W} A[\sigma(B^{-1})]$  contains an open subset of G.

By the above corollary, if we take  $\sigma_0 = l_G$  then  $AB^{-1}$  will contain an open subset of G. This is practically the Steinhaus Theorem [7] in the case of locally compact group.

Under composition, we see that the general linear group Gl(n, R) of non-singular linear transformations of  $R^n$  with topology inherited from the uniform topology on the collection  $\mathcal{L}(R^n, R^n)$  of all linear transformations is a topological group and Gl(n, R) is topological isomorphic to  $\mathfrak{L}(R^n)$ . Hence it is easy to get all the consequences of [5] from our Theorem.

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