

**CHARACTERIZATION OF
THE PSEUDO-SYMMETRIES
OF IDEAL WINTGEN SUBMANIFOLDS
OF DIMENSION 3**

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ABSTRACT. Recently, Choi and Lu proved that the Wintgen inequality $\rho \leq H^2 - \rho^\perp + k$, (where ρ is the normalized scalar curvature and H^2 , respectively ρ^\perp , are the squared mean curvature and the normalized scalar normal curvature) holds on any 3-dimensional submanifold M^3 with arbitrary codimension m in any real space form $\tilde{M}^{3+m}(k)$ of curvature k . For a given Riemannian manifold M^3 , this inequality can be interpreted as follows: for all possible isometric immersions of M^3 in space forms $\tilde{M}^{3+m}(k)$, the value of the intrinsic curvature ρ of M puts a lower bound to all possible values of the extrinsic curvature $H^2 - \rho^\perp + k$ that M in any case can not avoid to “undergo” as a submanifold of \tilde{M} . From this point of view, M is called a Wintgen ideal submanifold of \tilde{M} when this extrinsic curvature $H^2 - \rho^\perp + k$ actually assumes its theoretically smallest possible value, as given by its intrinsic curvature ρ , at all points of M . We show that the pseudo-symmetry or, equivalently, the property to be quasi-Einstein of such 3-dimensional Wintgen ideal submanifolds M^3 of $\tilde{M}^{3+m}(k)$ can be characterized in terms of the intrinsic minimal values of the Ricci curvatures and of the Riemannian sectional curvatures of M and of the extrinsic notions of the umbilicity, the minimality and the pseudo-umbilicity of M in \tilde{M} .

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1. Wintgen ideal submanifolds

For surfaces M^2 in the Euclidean space E^3 , the *Euler inequality* $K \leq H^2$, where K is the (intrinsic) *Gauss curvature* of M^2 and H^2 is the (extrinsic) *squared mean curvature* of M^2 in E^3 , at once follows from the fact that $K = k_1 k_2$ and $H = \frac{1}{2}(k_1 + k_2)$ where k_1 and k_2 are the *principal curvatures* of M^2 in E^3 , and, obviously, $K = H^2$ everywhere on M^2 if and only if the surface M^2 is *totally umbilical* in E^3 , i.e., $k_1 = k_2$ at all points of M^2 , or still, by a *theorem of Meusnier*, if and only if M^2 is a part of a *plane* E^2 or of a *round sphere* S^2 in E^3 .

For surfaces M^2 in the 4-dimensional Euclidean space E^4 , Wintgen proved that the Gauss curvature K and the squared mean curvature H^2 and the (extrinsic) *normal curvature* K^\perp always satisfy the inequality $K \leq H^2 - K^\perp$, and that actually the equality holds if and only if the *curvature ellipse* of M^2 in E^4 is a *circle* [36]; (cf. e.g. [6, 7] for studies also on the global differential geometry of submanifolds by a.o. Smale, Lashof, Chern, Chen and Willmore concerning the Euler characteristic of the normal bundle, the number of self-intersections and the total mean curvature). This fundamental inequality between the most important intrinsic and extrinsic scalar valued curvatures of surfaces M^2 in E^4 was later shown, by Rouxel and by Guadalupe and Rodriguez, to hold more generally for all surfaces M^2 of *arbitrary codimension* m in the *real space forms* $\tilde{M}^{2+m}(k)$ of constant sectional curvature k , inclusive the characterisation of the equality case [21, 29]. After these extensions of the above *Wintgen inequality* for submanifolds of dimension 2 and of codimension 2 to submanifolds of *dimension* 2 and *arbitrary codimension* $m \geq 2$, in 1999 De Smet and Dillen and Vrancken and one of the authors proved the Wintgen inequality $\rho \leq H^2 - \rho^\perp + k$, where ρ and ρ^\perp respectively are the (intrinsic) *normalized scalar curvature* and the (extrinsic) *normalized scalar normal curvature*, for *2-codimensional* submanifolds M^n of *arbitrary dimension* $n \geq 2$ in the real space forms $\tilde{M}^{n+2}(k)$, and characterized the equality situation explicitly in terms of the shape operators of M^n in $\tilde{M}^{n+2}(k)$ [12]. Moreover, in [12] it was conjectured that this Wintgen inequality holds for submanifolds M^n of *any dimension* $n \geq 2$ and of *any codimension* $m \geq 2$ in real space forms $\tilde{M}^{n+m}(k)$, (referring to the initials of the authors of [12], Suceavă recently started to call this “the DDVV conjecture” [31], and was therein followed by others, although the “*conjecture on Wintgen’s inequality*” may well be a more appropriate terminology). Recently, Choi and Lu proved that this conjecture is true for all 3-dimensional submanifolds M^3 of *arbitrary codimension* $m \geq 2$ in $\tilde{M}^{3+m}(k)$ and obtained characteristic expressions for the shape operators of the submanifolds M^3 in $\tilde{M}^{3+m}(k)$ which do realize the equality in this general inequality [8]. Concrete descriptions of some classes of 3-dimensional *Wintgen ideal submanifolds* were given by Bryant, Dillen, Fastenakels and Van der Veken [4, 18].

At this stage we would like further finally to mention that De Smet, Dillen, Fastenakels, Van der Veken, Vrancken and one of the authors studied the Wintgen inequality for *invariant submanifolds in Kaehler, nearly Kaehler and Sasakian spaces* [11, 17], and that Gmira, Haesen, Dillen and two of the authors studied this inequality for *submanifolds in semi-Riemannian spaces* [19, 20].

2. Pseudo-symmetric spaces

Let M^n be an n -dimensional *Riemannian manifold* with *metric* $(0, 2)$ tensor g and *Levi-Civita connection* ∇ . Let R denote the $(0, 4)$ *Riemann-Christoffel curvature tensor* of M as well as the *curvature* $(1, 1)$ operator $R(X, Y) := \nabla_X \nabla_Y - \nabla_Y \nabla_X - \nabla_{[X, Y]}$, thus having

$$(1) \quad R(X, Y, Z, W) := g(R(X, Y)Z, W),$$

where X, Y , etc. denote arbitrary vector fields on M and $[\cdot, \cdot]$ stands for the Lie bracket. By the action of the curvature operator working as a derivation on the curvature tensor R , the following $(0, 6)$ tensor $R \cdot R$ is obtained:

$$\begin{aligned} (R \cdot R)(X_1, X_2, X_3, X_4; X, Y) &:= (R(X, Y) \cdot R)(X_1, X_2, X_3, X_4) \\ &= -R(R(X, Y)X_1, X_2, X_3, X_4) - R(X_1, R(X, Y)X_2, X_3, X_4) \\ &\quad - R(X_1, X_2, R(X, Y)X_3, X_4) - R(X_1, X_2, X_3, R(X, Y)X_4). \end{aligned}$$

As was recently shown by Haesen and one of the authors [22], the tensor $R \cdot R$ can be geometrically interpreted as giving *the second-order measure of the change of the sectional curvatures* $K(p, \pi)$ for *tangent 2-planes* π at *points* p after the *parallel transport of* π around *infinitesimal co-ordinate parallelograms in* M *cornered at* p . Thus, the *semi-symmetric* or *Szabó symmetric spaces* [32, 33], i.e., the manifolds M for which $R \cdot R = 0$, are those Riemannian manifolds for which all sectional curvatures remain preserved after the parallel transport of their planes around all infinitesimal co-ordinate parallelograms. The *locally symmetric* or *Cartan symmetric spaces*, i.e., the manifolds M for which $\nabla R = 0$, constitute a proper subclass of the class of the Szabó symmetric spaces.

We recall that the definition (1) of the curvature tensor goes back to Schouten's geometrical interpretation of R as *the second order measure of the change of the direction of vector fields after their parallel transport around closed infinitesimal curves on* M [30]. Then the *locally flat* or *locally Euclidean spaces*, thus the manifolds M for which $R = 0$, are those Riemannian manifolds for which all directions remain preserved after parallel transport around all closed infinitesimal curves. The simplest nonflat Riemannian manifolds M are the *spaces of constant curvature* $K = k$, i.e., the spaces whose function K is *isotropic* (meaning that, at each point p , the Gauss curvature $K(p, \pi)$ at p of the local surface formed by the geodesics of M which pass through p and whose tangent vector at p lies in π , has the same value for all choices of planes π at p , thus K becoming a real function on M , which by the lemma of Schur, for $n > 2$, then necessarily has to be constant). These real *space forms* $M^n(k)$, by a theorem of Beltrami, can be obtained from the locally Euclidean spaces by *projective transformations* and their class is closed under such transformations. Further, we also recall that the knowledge of the curvature tensor R is *equivalent* to the knowledge of the sectional or Riemannian curvatures K , as was shown by Cartan. Finally, as is well known, the curvature tensor R of a space of constant curvature k is given by

$$(2) \quad R(X, Y, Z, W) = k g((X \wedge_g Y)Z, W),$$

where the \wedge_g stands for the *metrical endomorphism* $(X \wedge_g Y)Z := g(Y, Z)X - g(X, Z)Y$. Thus for the real space forms $M^n(k)$, $n > 2$, there exists a *real valued* function K on M such that $R(X, Y, Z, W) = K G(X, Y, Z, W)$, where the $(0, 4)$ -tensor G is defined by $G(X, Y, Z, W) := g((X \wedge_g Y)Z, W)$.

A main interest of Riemann, Helmholtz, Lie, Klein, . . . in the spaces of constant curvature was related to the fact that these are precisely the Riemannian manifolds which satisfy the *axiom of free mobility*.

Now, similarly as proceeding from the locally Euclidean spaces to the real space forms, one can proceed from the Szabó symmetric spaces to the *pseudo-symmetric* or *Deszcz symmetric spaces* [1, 13, 22, 35]. The pseudo-symmetric spaces were defined as the manifolds M for which the $(0, 6)$ tensor $R \cdot R$ and the $(0, 6)$ *Tachibana tensor* $Q(g, R) := -\wedge_g \cdot R$, where the metrical endomorphism \wedge_g acts on the $(0, 4)$ curvature tensor R as a derivation, are proportional, say $R \cdot R = L(-\wedge_g \cdot R)$ for some real valued function L on M ;

$$\begin{aligned} Q(g, R)(X_1, X_2, X_3, X_4; X, Y) &:= -((X \wedge_g Y) \cdot R)(X_1, X_2, X_3, X_4) \\ &= R((X \wedge_g Y)X_1, X_2, X_3, X_4) + R(X_1, (X \wedge_g Y)X_2, X_3, X_4) \\ &\quad + R(X_1, X_2, (X \wedge_g Y)X_3, X_4) + R(X_1, X_2, X_3, (X \wedge_g Y)X_4). \end{aligned}$$

A classical result states that the identical vanishing of this Tachibana tensor, $Q(g, R) = 0$, characterizes the real space forms. Further, results of Mikesh, Venzi, Defever and Deszcz learn that pseudo-symmetric spaces are obtained by applying *projective transformations* to the semi-symmetric spaces and that the class of the pseudo-symmetric spaces is closed under such transformations. Two 2-planes π and $\bar{\pi}$, spanned by vectors u, v and x, y respectively, at the same point p of M , are said to be *curvature dependent* if $Q(g, R)(u, v, v, u; x, y) \neq 0$, which is independent of the choices of bases for π and $\bar{\pi}$. For such planes, the *double sectional curvature* or the *sectional curvature of Deszcz* or the *Riemann curvature of Deszcz* $L(p, \pi, \bar{\pi})$ is defined as the real number given by

$$L(p, \pi, \bar{\pi}) := \frac{(R \cdot R)(u, v, v, u; x, y)}{Q(g, R)(u, v, v, u; x, y)},$$

(which is independent of the choices of bases for π and $\bar{\pi}$); it is a scalar valued Riemannian invariant. The knowledge of the tensor $R \cdot R$ is *equivalent* to the knowledge of the sectional curvatures $L(p, \pi, \bar{\pi})$ of Deszcz. And just like the geometrical interpretation of the sectional curvatures $K(p, \pi)$ of Riemann in terms of the *parallelogramoids of Levi-Civita* [27], also the sectional curvatures $L(p, \pi, \bar{\pi})$ of Deszcz can be interpreted in these terms (in this respect, we refer to [23] and [24] where in particular such interpretations are obtained for the sectional curvatures as well as for the *Ricci* and *conformal Weyl curvatures* of *Deszcz* in terms of the *squaroids* of Levi-Civita). Finally the Deszcz symmetric spaces are characterized by the *isotropy* of the curvatures $L(p, \pi, \bar{\pi})$, i.e., by the property that at every point p of M the scalars $L(p, \pi, \bar{\pi})$ are the same for all possible pairs of curvature dependent tangent planes π and $\bar{\pi}$ at p . In the present situation however there is no lemma of Schur, which then would further force this real valued function

$L : M \rightarrow R$ automatically to be constant; therefore, Kowalski and Sekizawa called the pseudo-symmetric spaces for which *the double sectional curvature L is indeed a constant*, independent of the planes π and $\bar{\pi}$ as well as of the points p of M , the *pseudo-symmetric spaces of constant type L* [26]. By way of examples in this respect we would like to mention here that the *3-dimensional Thurston geometries* [34], which in a kind of axiomatic way originated as natural *anisotropic extensions* of the spaces of constant Riemannian curvature K with their typical free mobility, all do have *constant sectional curvature L of Deszcz* (we set $L = 0$ for E^3 since $(K = c = 0)$, S^3 ($K = c > 0$), H^3 ($K = c < 0$), $S^2 \times E^1$ and $H^2 \times E^1$; $L = 1$ for $SL(2, R)$ and for the *3-dimensional Heisenberg group H_3* ; and $L = -1$ for the Lie group Sol) [2].

A similar study concerning the geometrical meaning of *Ricci pseudo-symmetry in the sense of Deszcz*, i.e., of the manifolds M satisfying the curvature condition $R \cdot S = L_S Q(g, S) = L_S(-\wedge_g \cdot S)$, where S denotes the $(0, 2)$ *Ricci curvature tensor* and $Q(g, S) = -\wedge_g \cdot S$ the *Ricci-Tachibana tensor* of M and L_S is a real valued function on M , was carried out by Jahanara, Haesen and two of the authors in [25], (in this respect, see also [9] and [15]). As shown in [16], a 3-dimensional Riemannian manifold M is pseudo-symmetric if and only if it is *quasi-Einstein*, i.e., if its Ricci tensor S has an eigenvalue of multiplicity ≥ 2 . The class of the Riemannian manifolds M with pseudo-symmetric Ricci tensor S as such is considerably larger in general than the class of the manifolds M with pseudo-symmetric Riemann-Christoffel tensor R , (which it obviously contains as a subclass). However, as shown in [10], for manifolds of dimension 3, these two pseudo-symmetry conditions are equivalent. As is well known, Schouten and Struik showed that the 3-dimensional Riemannian manifolds M are *Einstein* if and only if they have constant curvature K . In [28] two of the authors made a study of the *pseudo-symmetry in the sense of Deszcz* of the tensors R and S of the Wintgen ideal submanifolds M^n of *dimension $n > 3$* and of *codimension 2* in the real space forms $\widetilde{M}^{n+2}(k)$. In particular, they showed that for those Wintgen ideal submanifolds these two, a priori distinct, curvature conditions are equivalent and occur if and only if those submanifolds are either *totally umbilical* or *minimal*. In comparison, the 3-dimensional case will show to offer two additional kinds of pseudo-symmetric Wintgen ideal submanifolds.

3. On the symmetry of ideal submanifolds

Let M^n be a *submanifold* of a *real space form $\widetilde{M}^{n+m}(k)$* of constant curvature k . Let g, ∇ and R , and, respectively, $\tilde{g}, \tilde{\nabla}$ and \tilde{R} , denote the *Riemannian metric*, the *Levi-Civita connection* and the *Riemann-Cristoffel $(0, 4)$ curvature tensor* of M and \tilde{M} .

The *formulae of Gauss and Weingarten* then are

$$(3) \quad \tilde{\nabla}_X Y = \nabla_X Y + h(X, Y), \quad \text{and} \quad \tilde{\nabla}_X \xi = -A_\xi X + \nabla_X^\perp \xi,$$

where h, A_ξ and ∇^\perp denote the *second fundamental form*, the *shape operator* or the *Weingarten map* with respect to ξ and the *normal connection* of M in \tilde{M} , respectively, systematically using here and hereafter X, Y , etc. for *tangent vector*

fields on M and ξ etc. for *normal vector fields* on M in \widetilde{M} , (as basic references for Riemannian submanifolds, see [5] and [7]).

From (3) it follows that $\widetilde{g}(h(X, Y), \xi) = g(A_\xi(X), Y)$, such that, for any *orthonormal local normal frame* ξ_α on M in \widetilde{M} , (α etc. running from 1 till the codimension m),

$$(4) \quad h(X, Y) = \sum_{\alpha} g(A_\alpha(X), Y) \xi_\alpha,$$

where $A_\alpha = A_{\xi_\alpha}$. The *mean curvature vector field* \vec{H} of M in \widetilde{M} is defined as $\vec{H} = \frac{1}{n} \text{trace } h$ and its length $H = \|\vec{H}\|$ is the *mean curvature* of M in \widetilde{M} . By the *equation of Ricci*, the *normal curvature tensor* R^\perp of M in \widetilde{M} is given as follows:

$$(5) \quad R^\perp(X, Y; \xi, \eta) := \widetilde{g}(R^\perp(X, Y)\xi, \eta) = g([A_\xi, A_\eta](X), Y),$$

where

$$R^\perp(X, Y) := \nabla_X^\perp \nabla_Y^\perp - \nabla_Y^\perp \nabla_X^\perp - \nabla_{[X, Y]}^\perp \text{ and } [A_\xi, A_\eta] := A_\xi A_\eta - A_\eta A_\xi.$$

The *normalized scalar normal curvature* ρ^\perp of M in \widetilde{M} is then defined by

$$\rho^\perp := \frac{2}{n(n-1)} \left\{ \sum_{i < j} \sum_{\alpha < \beta} [R^\perp(E_i, E_j; \xi_\alpha, \xi_\beta)]^2 \right\}^{1/2},$$

for any normal frame ξ_α and for any *orthonormal local tangent frame* E_i on M , (i etc. running from 1 till the dimension n).

We remark that $\rho^\perp = 0$ if and only if *the normal connection is flat*, which, as follows from (5) and as was already observed by Cartan, is equivalent to the *simultaneous diagonalizability of all shape operators* A_ξ . The *equation of Gauss* of M in \widetilde{M} is given by

$$(6) \quad R(X, Y, Z, W) = \widetilde{g}(h(Y, Z), h(X, W)) - \widetilde{g}(h(X, Z), h(Y, W)) \\ + k \{g(Y, Z) g(X, W) - g(X, Z) g(Y, W)\}.$$

Let S be the (0, 2)-*Ricci tensor* of M : $S(X, Y) = \sum_i R(E_i, X, Y, E_i)$. Then from (2), (4) and (6), we obtain that

$$(7) \quad S(X, Y) = (n-1)k g(X, Y) + \sum_{\alpha} \text{trace } A_\alpha g(A_\alpha(X), Y) \\ - \sum_{\alpha} \sum_i g(A_\alpha(X), E_i) g(A_\alpha(Y), E_i),$$

for any choice of frames E_i and ξ_α . And the *normalized scalar curvature* ρ of M is defined by

$$\rho := \frac{2}{n(n-1)} \sum_{i < j} R(E_i, E_j, E_j, E_i).$$

Choi and Lu gave the following *affirmative solution of the conjecture concerning the inequality of Wintgen for the 3-dimensional submanifolds of the real space forms*.

THEOREM 1. [8] For any M^3 in $\widetilde{M}^{3+m}(k)$, with $m \geq 3$:

$$(8) \quad \rho \leq H^2 - \rho^\perp + k,$$

and the equality holds if and only if, with respect to suitably chosen local orthonormal tangent and normal frames E_1, E_2, E_3 and ξ_1, \dots, ξ_m , the shape operators A_α of M in \widetilde{M} take the forms:

$$(9) \quad A_1 = \begin{pmatrix} c & \mu & 0 \\ \mu & c & 0 \\ 0 & 0 & c \end{pmatrix}, \quad A_2 = \begin{pmatrix} b + \mu & 0 & 0 \\ 0 & b - \mu & 0 \\ 0 & 0 & b \end{pmatrix}, \quad A_3 = \begin{pmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{pmatrix},$$

$$A_4 = \dots = A_m = 0,$$

for some real valued functions a, b, c and μ on M .

On the other hand, from the paper of De Smet, Dillen, Vrancken and one of the authors on Wintgen's inequality, we have the following.

THEOREM 2. [12] For any M^3 in $\widetilde{M}^5(k)$, (8) is satisfied and the equality holds if and only if, with respect to suitably chosen local orthonormal frames E_1, E_2, E_3 and ξ_1, ξ_2 , the shape operators A_1 and A_2 of M in \widetilde{M} are given by

$$A_1 = \begin{pmatrix} c & \mu & 0 \\ \mu & c & 0 \\ 0 & 0 & c \end{pmatrix}, \quad A_2 = \begin{pmatrix} \mu & 0 & 0 \\ 0 & -\mu & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

So, for what follows and which concerns essentially dealing with the above shape operators filled into the Gauss equation of M^3 in $\widetilde{M}^{3+m}(k)$, the latter situation ($m = 2$) is in some sense algebraically included in the former one ($m > 2$) by considering $a = b = 0$. And, in the case of codimension 1 there is no question about a normal curvature, we can carry out a general study of the 3-dimensional Wintgen ideal submanifolds M^3 in arbitrary space forms $\widetilde{M}^{3+m}(k)$, $m \geq 2$, by dealing with the forms of the shape operators as given in (9). Frames E_1, E_2, E_3 and ξ_1, \dots, ξ_m for which the corresponding shape operators A_α assume such forms which further on will be called *Choi-Lu frames* of Wintgen ideal M^3 in \widetilde{M}^{3+m} .

From (7) and (9), the (1, 1) Ricci operator S which is metrically related to the (0, 2) Ricci tensor S by $g(S(X), Y) = S(X, Y)$, with respect to Choi-Lu frames E_i and ξ_α is readily found to be given by

$$(10) \quad S = \begin{pmatrix} S_{11} & c\mu & 0 \\ c\mu & S_{22} & 0 \\ 0 & 0 & S_{33} \end{pmatrix},$$

where

$$(11) \quad \begin{aligned} S_{11} &= 2(a^2 + b^2 + c^2 + k) + \mu(b - 2\mu), \\ S_{22} &= 2(a^2 + b^2 + c^2 + k) - \mu(b + 2\mu), \\ S_{33} &= 2(a^2 + b^2 + c^2 + k). \end{aligned}$$

Hence E_3 always determines a *Ricci principal direction*, with a corresponding *Ricci curvature*

$$(12) \quad \rho_3 = 2(a^2 + b^2 + c^2 + k).$$

And, from (10) and (11), the other two *Ricci curvatures*, ρ_1 and ρ_2 , corresponding to some orthogonal eigendirections \tilde{E}_1 and \tilde{E}_2 in the plane field $E_1 \wedge E_2$, are easily derived as

$$(13) \quad \begin{aligned} \rho_1 &= \rho_3 - 2\mu^2 + |\mu|\sqrt{b^2 + c^2}, \\ \rho_2 &= \rho_3 - 2\mu^2 - |\mu|\sqrt{b^2 + c^2}. \end{aligned}$$

Since M^3 is *pseudo-symmetric* or still, *symmetric in the sense of Deszcz*, if and only if its Ricci tensor has an eigenvalue of multiplicity ≥ 2 , from (13) we have the following.

LEMMA 1. *A Wintgen ideal 3-dimensional submanifold in a real space form is Deszcz symmetric if and only if*

$$(I) \quad \mu = 0 \quad \text{or} \quad (II) \quad \mu \neq 0, \quad b = c = 0 \quad \text{or} \quad (III) \quad \mu \neq 0, \quad b^2 + c^2 = 4\mu^2.$$

Proceeding more straightforwardly, from (6) and (9) the components, with respect to Choi–Lu frames, of the $(0, 4)$ *curvature tensor* R of a Wintgen ideal M^3 in $\tilde{M}^{3+m}(k)$ are readily found to be either zero or else to be completely determined, via the algebraic symmetries of R , by the following ones:

$$(14) \quad \begin{aligned} \alpha &:= K_{12} = R_{1221} = a^2 + b^2 + c^2 - 2\mu^2 + k, \\ \beta &:= K_{13} = R_{1331} = a^2 + b^2 + c^2 + b\mu + k, \\ \gamma &:= K_{23} = R_{2332} = a^2 + b^2 + c^2 - b\mu + k, \\ \delta &:= R_{1332} = c\mu, \end{aligned}$$

($K_{ij} = K(E_i \wedge E_j)$) are the *sectional curvatures* of M for the 2-planes $E_i \wedge E_j$ determined by a Choi–Lu frame E_1, E_2, E_3 . And then also the components of the $(0, 6)$ tensors $R \cdot R$ and $\wedge_g \cdot R$ are readily computable, and turn out either to be zero “together” or, when at least a priori non-zero, they appear in pairs which are, via algebraic symmetries of both these $(0, 6)$ tensors (cf. [22]), completely determined by the following ones:

$$(15) \quad \begin{aligned} (R \cdot R)(E_1, E_3, E_1, E_3; E_1, E_2) &= -2\alpha\delta, \\ (\wedge_g \cdot R)(E_1, E_3, E_1, E_3; E_1, E_2) &= -2\delta; \\ (R \cdot R)(E_1, E_3, E_2, E_3; E_1, E_2) &= \alpha(\beta - \gamma), \\ (\wedge_g \cdot R)(E_1, E_3, E_2, E_3; E_1, E_2) &= \beta - \gamma; \\ (R \cdot R)(E_1, E_2, E_2, E_3; E_1, E_3) &= -\alpha\beta + \beta\gamma - \delta^2, \\ (\wedge_g \cdot R)(E_1, E_2, E_2, E_3; E_1, E_3) &= \gamma - \alpha. \end{aligned}$$

Then, by (14) and (15), the condition for the *pseudo-symmetry* of R , i.e., of the existence of a function $L: M \rightarrow R$ for which $R \cdot R = L(-\wedge_g \cdot R)$, for Wintgen ideal submanifolds M^3 in $\tilde{M}^{3+m}(k)$, yields, of course, the previous cases (I, II, and III)

of Lemma 1, but moreover in each case at the point p gives the *double sectional curvature function* L as stated in the following.

LEMMA 2. *We have*

$$\begin{aligned} L &= 0 && \text{in case (I),} \\ L &= a^2 + k && \text{in case (II),} \\ L &= a^2 + 2\mu^2 + k && \text{in case (III).} \end{aligned}$$

In case (I), M^3 is Einstein and thus a real space form and so, in particular, M^3 is then semi-symmetric and hence (also without calculations, one could know that) $L = 0$. In cases (II) and (III), according to the general theory in this respect, if M^3 is quasi-Einstein and has λ as an *eigenvalue of the Ricci tensor S of multiplicity 1*, then $L = \frac{\lambda}{2}$, which allows to obtain Lemma 2 also from the consideration of (12) and (13).

Now we aim to geometrically characterize the cases (I), (II), and (III). Clearly, from (9), we see that (I) corresponds to the *totally umbilical* Wintgen ideal submanifolds M^3 in real space forms $\widetilde{M}^{3+m}(k)$; such M^3 are intrinsically itself spaces of constant curvature $K = a^2 + b^2 + c^2 + k$. We recall that a submanifold M^n in a Riemannian manifold \widetilde{M}^{n+m} is said to be *pseudo-umbilical* if its *mean curvature vector field \vec{H}* determines an *umbilical* normal direction on M in \widetilde{M} . When hereafter we call a submanifold pseudo-umbilical we mean it to be *properly* pseudo-umbilical, i.e., we exclude from it the trivial cases when it is *minimal* ($\vec{H} = \vec{0}$), or when it is *totally umbilical* (i.e., when every normal direction ξ is umbilical). The mean curvature vector field \vec{H} for the submanifolds M^3 under consideration being given by $\vec{H} = c\xi_1 + b\xi_2 + a\xi_3$, it further follows from (9) that the shape operator of M in \widetilde{M} with respect to \vec{H} is given by

$$(16) \quad A_{\vec{H}} = \begin{pmatrix} a^2 + b^2 + c^2 + b\mu & c\mu & 0 \\ c\mu & a^2 + b^2 + c^2 - b\mu & 0 \\ 0 & 0 & a^2 + b^2 + c^2 \end{pmatrix}.$$

In case M is *not totally umbilical* in \widetilde{M} , i.e., in case $\mu \neq 0$, and in case M is *not minimal* in \widetilde{M} , i.e., in case not $a = b = c = 0$ (cf. (9)), then (16) shows that \vec{H} determines an *umbilical normal direction* of M in \widetilde{M} if and only if $b = c = 0$. In summary, from the above we know that cases (I) and (II) correspond to the Wintgen ideal submanifolds which are *totally umbilical* or *minimal* or *pseudo-umbilical*. Finally, we next aim for a geometrical characterisation of case (III): $b^2 + c^2 = 4\mu^2$ where $\mu \neq 0$. To simplify a bit the discussion, we will assume from now on that $\mu > 0$, which we can do without loss of generality, being always realizable in view of (9) by eventual changing orientations of ξ_α 's and orderings of E_1 and E_2). From (12) and (13) we recall that the eigenvalues of the Ricci tensor

are given by

$$(17) \quad \begin{aligned} \rho_1 &= 2(a^2 + b^2 + c^2 + k) - 2\mu^2 + \mu\sqrt{b^2 + c^2}, \\ \rho_2 &= 2(a^2 + b^2 + c^2 + k) - 2\mu^2 - \mu\sqrt{b^2 + c^2}, \\ \rho_3 &= 2(a^2 + b^2 + c^2 + k), \end{aligned}$$

where ρ_3 is the one in the E_3 -direction of M and that ρ_1 and ρ_2 are the eigenvalues corresponding to certain eigendirections in the plane $\pi = E_1 \wedge E_2$ perpendicular to E_3 and of which the special character is reflected obviously, having $\mu \neq 0$, in the form of the shape operators given in (9), and which we further will call the *Choi-Lu plane* of M^3 . Studying at present M^3 's which are not totally umbilical, in particular, these submanifolds are not Einstein, and so, at every point, they have a *smallest* Ricci curvature, which we'll denote by $\inf \text{Ric}$. From (17) it is clear this is ρ_2 :

$$\inf \text{Ric} = 2(a^2 + b^2 + c^2 + k) - 2\mu^2 - \mu\sqrt{b^2 + c^2},$$

attained by a particular direction in the Choi-Lu plane of M^3 . On the other hand, we recall from (14) that the *sectional curvature* $K_{\text{Choi-Lu}}$ of the *Choi-Lu plane* is given by

$$K_{\text{Choi-Lu}} = K_{12} = a^2 + b^2 + c^2 + k - 2\mu^2.$$

Hence $\inf \text{Ric} = 2K_{\text{Choi-Lu}}$ if and only if $-2\mu^2 - \mu\sqrt{b^2 + c^2} = -4\mu^2$, i.e., if and only if (III) holds, namely when $b^2 + c^2 = 4\mu^2$. From (14) we moreover see that, in this case,

$$\begin{aligned} K_{12} &= K_{\text{Choi-Lu}} = a^2 + 2\mu^2 + k, \\ K_{13} &= K_{\text{Choi-Lu}} + \mu(2\mu + b), \\ K_{23} &= K_{\text{Choi-Lu}} + \mu(2\mu - b), \end{aligned}$$

which implies, obviously having also that $b^2 \leq 4\mu^2$ and so, since $\mu > 0$, that

$$-2\mu \leq b \leq 2\mu,$$

and thus that as well $0 \leq 2\mu + b$ as $0 \leq 2\mu - b$, together with the equation of Gauss and (9), that in case (III) the sectional curvature K_{12} actually equals $\inf K$, the function on M giving the *minimum of the sectional curvatures* K at each point of M^3 . So, in this situation we can observe on the side that the $\delta(2)$ -curvature of Chen [7], $\delta(2) := \tau - \inf K$, where $\tau := \sum_{i < j} K_{ij}$ is the *scalar curvature* of M^3 , is given by $\delta(2) = \tau - K_{12} = K_{13} + K_{23} = \rho_3 = \rho_1$ which, in this case, is $\sup \text{Ric}$, the real valued function on M giving the maximum Ricci curvature at each point of M^3 . Once more, in accordance with the general theory of Deszcz symmetric 3-dimensional Riemannian manifolds M^3 , for the properly quasi-Einstein manifolds M^3 the sectional curvature L of Deszcz satisfies $L = \frac{\lambda}{2}$, where λ is the principal curvature with multiplicity 1, so actually $\lambda = \rho_2 = 2(a^2 + 2\mu^2 + k)$, such that

$$L = K_{\text{Choi-Lu}} = \inf K.$$

In this respect, coming back to case (II), from (14) and taking further into account (9) and the equation of Gauss, it follows that in this case, since $K_{12} = a^2 + k - 2\mu^2$,

$$L = a^2 + k = K_{23} = K_{13} = \sup K,$$

$\sup K$ denoting the *maximum of the sectional curvature function* on M , i.e., the function on M which value at each point is the maximum of all the sectional curvatures of M at this point. Taking into account at last also the case (III) of Lemma 2, in summary we can formulate the following.

THEOREM 3. *A Wintgen ideal submanifold M^3 in a real space form $\widetilde{M}^{3+m}(k)$ is Deszcz symmetric if and only if (I) M^3 is a totally umbilical submanifold with Deszcz sectional curvature $L = 0$ (M^3 then being a space of constant sectional curvature K), or, (II) M^3 is a minimal submanifold or a pseudo-umbilical submanifold, with Deszcz sectional curvature $L = \sup K$, or else, (III) M^3 is characterized by the curvature condition $\inf \text{Ric} = 2K_{\text{Choi-Lu}} = 2 \inf K$, with Deszcz sectional curvature $L = \inf K$.*

4. Further comments and remarks

(1) We would like to refer again to the references mentioned in Section 1 for explicit descriptions of several *examples* of Wintgen ideal 3-dimensional submanifolds.

(2) Referring amongst others to Berger's discussion in his "Panorama" [3] pertaining to the *extremal values of the sectional curvature function K* of Riemannian manifolds, we observe from Theorem 3 that for the nontrivial Wintgen ideal submanifolds M^3 in $\widetilde{M}^{3+m}(k)$, i.e., the nontotally umbilical ones, *the isotropic Deszcz sectional curvatures L* are either given by the maximum or by the minimum values of K at each point. The Deszcz symmetry of those submanifolds M^3 being equivalent to being quasi-Einstein, in the above nontrivial case, $L = \sup K$ or $L = \inf K$ according to the geometrical fact that *the eigendirection of the Ricci tensor whose eigenvalue has multiplicity 1 is either perpendicular to the plane of Choi-Lu of these Wintgen ideal submanifolds M^3 or belongs to this plane.*

(3) Concerning the *origin of the Ricci tensor* of 3-dimensional Riemannian manifolds and some related views on the δ -curvatures of Chen, see [25].

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