ON ALMOST PSEUDO m-PROJECTIVELY SYMMETRIC MANIFOLDS

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Abstract. The object of the present paper is to study almost pseudo m-projectively symmetric manifolds. Some geometric properties of almost pseudo m-projectively symmetric manifolds have been studied under certain curvature conditions. Finally the existence of almost pseudo m-projectively symmetric manifolds is shown by examples.

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1. Introduction

In 1926, Cartan [4] studied certain class of Riemannian spaces and he introduced the notion of a symmetric space. Accoding to Cartan, an *n*-dimensional Riemannian manifold M is said to be locally symmetric if it has constant curvature, i.e if the curvature tensor satisfies $R_{hijk,l} = 0$, where ',' denotes the covariant differentiation with respect to the metric tensor and R_{hijk} are the components of the curvature tensor. Later, symmetric manifolds have been studied by many authors such as: recurrent manifolds introduced by Walker [23], conformally symmetric manifolds by Chaki and Gupta [6], conformally recurrent manifolds by Adati and Miyazawa [1], pseudo symmetric manifolds introduced by Chaki [5], almost pseudo symmetric and almost pseudo conformally symmetric manifolds by De and Gazi [11, 12] etc.

The notion of weakly symmetric manifolds was introduced by Tamassy and Binh [22] in 1989. A non-flat Riemannian manifold (M^n, g) , (n > 2) is called weakly symmetric if the curvature tensor \tilde{R} of type (1,3) satisfies the condition:

$$\nabla_X \tilde{R}(Y, Z)W = A(X)\tilde{R}(Y, Z)W + B(Y)\tilde{R}(X, Z)W + D(Z)\tilde{R}(Y, X)W + E(W)\tilde{R}(Y, Z)X + g(\tilde{R}(Y, Z)W, X)P,$$

where ∇ denotes the Levi-Civita connection on (M^n, g) and A, B, D, E and P are 1-forms and a vector field respectively which are non-zero simultaneously.

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Such a manifold is denoted by $(WS)_n$. Weakly symmetric manifolds have been studied by several authors ([3], [10], [2], [17], [18] and many others).

In 1987, Chaki [5] studied a type of non-flat Riemannian manifold whose curvature tensor satisfies

(1.1)
$$R_{hijk,l} = 2\lambda_l R_{hijk} + \lambda_h R_{lijk} + \lambda_i R_{hljk} + \lambda_j R_{hilk} + \lambda_k R_{hijl},$$

where λ_l is a non-zero covariant vector. A manifold whose curvature tensor satisfies the above equation is called a pseudo symmetric manifold [5]. It is to be noted that (1.1) was already obtained by Sen and Chaki [20] when they studied certain kind of a conformally flat Riemannian space. A pseudo symmetric manifold is denoted by $(PS)_n$.

In index-free notation equation (1.1) is given by

$$(\nabla_X \tilde{R})(Y, Z)W = 2A(X)\tilde{R}(Y, Z)W + A(Y)\tilde{R}(X, Z)W + A(Z)\tilde{R}(Y, X)W$$

(1.2)
$$+ A(W)\tilde{R}(Y, Z)X + g(\tilde{R}(Y, Z)W, X)P,$$

where \tilde{R} is a Riemannian curvature tensor of type (1,3), ∇ denotes the Levi-Civita connection, A is a non-zero 1-form and P is a vector field defined by

$$g(X,P) = A(X),$$

for all X.

In 2008 De and Gazi [11] introduced a type of Riemannian manifold which is a generalization of pseudo symmetric manifolds. Such manifold is called an almost pseudo symmetric manifold and is denoted by $(APS)_n$. A Riemannian manifold (M^n, g) , (n > 2) is said to be almost pseudo symmetric [11] if its curvature tensor R of type (0, 4) satisfies the condition:

(
$$\nabla_X R$$
)(Y, Z, U, V) = $[A(X) + B(X)]R(Y, Z, U, V)$
+ $A(Y)R(X, Z, U, V) + A(Z)R(Y, X, U, V)$
+ $A(U)R(Y, Z, X, V) + A(V)R(Y, Z, U, X),$

where A, B are non-zero 1-forms defined by

$$g(X, P) = A(X), g(X, Q) = B(X),$$

for all vector fields X. In the papers ([12], [13]) it was mentioned that $(PS)_n$ is a particular case of an $(APS)_n$, $but(WS)_n$ is not a particular case of an $(APS)_n$.

In 1971, Pokhariyal and Mishra [16] introduced a new curvature tensor of type (1,3) in an *n*-dimensional Riemannian manifold (M^n, g) , n > 2 denoted by \tilde{M} and defined by

(1.4)

$$\tilde{M}(Y,Z)U = \tilde{R}(Y,Z)U - \frac{1}{2(n-1)}[S(Z,U)Y - S(Y,U)Z] + g(Z,U)LY - g(Y,U)LZ],$$

where \tilde{R} and L denote the Riemannian curvature tensor of type (1,3) and the Ricci operator defined by g(LX, Y) = S(X, Y), respectively. Such a tensor \tilde{M} is known as an *m*-projective curvature tensor. The *m*-projective curvature tensor have been studied by J.P. Singh [21], S.K. Chaubey and R.H. Ojha [8], S.K. Chaubey [7], and many others.

From (1.4) we can define a (0,4) type *m*-projective curvature tensor *M* as follows:

(1.5)
$$M(Y, Z, U, V) = R(Y, Z, U, V) - \frac{1}{2(n-1)} [S(Z, U)g(Y, V) - S(Y, U)g(Z, V) + S(Y, V)g(Z, U) - S(Z, V)g(Y, U)],$$

where R denotes the Riemannian curvature tensor of type (0,4) defined by

$$R(Y, Z, U, V) = g(R(Y, Z)U, V),$$

and

$$M(Y, Z, U, V) = g(\tilde{M}(Y, Z)U, V),$$

where \hat{R} is the Riemannian curvature tensor of type (1,3) and S denotes the Ricci tensor of type (0,2) respectively.

The *m*-projective curvature tensor satisfies the properties of the Riemannian curvature tensor. The object of the present paper is to study a type of non-flat Riemannian manifold $(M^n, g), (n > 2)$ whose *m*-projective curvature tensor *M* of type (0,4) satisfies the condition:

(
$$\nabla_X M$$
)(Y, Z, U, V) = $[A(X) + B(X)]M(Y, Z, U, V)$
+ $A(Y)M(X, Z, U, V) + A(Z)M(Y, X, U, V)$
+ $A(U)M(Y, Z, X, V) + A(V)M(Y, Z, U, X).$

Such a manifold shall be called an almost pseudo *m*-projectively symmetric manifold and an *n*-dimensional manifold of this kind shall be denoted by $(APMPS)_n$. In a recent paper De and Mallick [9] studied almost pseudo concircularly symmetric manifolds and Prajjwal Pal [15] studied almost pseudo conharmonically symmetric manifolds. Motivated by the above studies, in the present paper we have studied a type of non-flat Riemannian manifold.

This paper is organized as follows: After preliminaries in Section 2, we obtain a necessary and sufficient condition for constant scalar curvature of a $(APMPS)_n, (n > 2)$. In Section 4 we study $(APMPS)_n, (n > 2)$ satisfying Codazzi type of Ricci tensor. The next section is devoted to the study of Einstein $(APMPS)_n$. In Section 6, we study Ricci symmetric $(APMPS)_n, (n > 2)$ and we proved that the scalar curvature of a Ricci symmetric $(APMPS)_n$ is constant. Finally, non-trivial examples of $(APMPS)_n$ have been constructed.

2. Preliminaries

Let S and r denote the Ricci tensor of type (0, 2) and the scalar curavture respectively and L denotes the symmetric tensor of type (1, 1) corresponding to the Ricci tensor S, that is,

$$g(LX,Y) = S(X,Y).$$

In this section, some formulas useful while studying $(APMPS)_n$ are derived. Let $\{e_i\}$ be an orthonormal basis of the tangent space at each point of the manifold, where $1 \leq i \leq n$. From (1.4) we can easily verify that the tensor M satisfies the following property

(2.1)
$$\tilde{M}(Y,Z)U = -\tilde{M}(Z,Y)U,$$
$$\tilde{M}(Y,Z)U + \tilde{M}(Z,U)Y + \tilde{M}(U,Y)Z = 0.$$

From (1.5) and (2.1) it follows that

$$\begin{array}{ll} (i) & M(Y,Z,U,V) = -M(Z,Y,U,V), \\ (ii) & M(Y,Z,U,V) = -M(Y,Z,V,U), \\ (iii) & M(Y,Z,U,V) = M(U,V,Y,Z), \\ (2.2) & (iv) & M(Y,Z,U,V) + M(Z,U,Y,V) + M(U,Y,Z,V) = 0. \end{array}$$

Also from the equation (1.5) we have

(2.3)
$$\sum_{i=1}^{n} M(Y, Z, e_i, e_i) = 0 = \sum_{i=1}^{n} M(e_i, e_i, U, V)$$

and

(2.4)
$$\sum_{i=1}^{n} M(e_i, Z, U, e_i) = \sum_{i=1}^{n} M(Z, e_i, e_i, U) \\ = \frac{n}{2(n-1)} [S(Z, U) - \frac{r}{n} g(Z, U)],$$

where $r = \sum_{i=1}^{n} \epsilon_i S(e_i, e_i)$ is the scalar curvature.

3. $(APMPS)_n, (n > 2)$ with constant scalar curvature

From (1.5) we have,

$$(\nabla_X M)(Y, Z, U, V) = (\nabla_X R)(Y, Z, U, V) -\frac{1}{2(n-1)} [(\nabla_X S)(Z, U)g(Y, V) - (\nabla_X S)(Y, U)g(Z, V) + (\nabla_X S)(Y, V)g(Z, U) - (\nabla_X S)(Z, V)g(Y, U)].$$
(3.1)

From (1.6) and (3.1) we obtain

Contracting (3.2) over Y and V we get

$$(\nabla_X S)(Z,U) = \frac{n}{2(n-1)} [A(X) + B(X)] [S(Z,U) - \frac{r}{n}g(Z,U)] + A(\tilde{M}(X,Z)U) + \frac{n}{2(n-1)} A(Z) [S(X,U) - \frac{r}{n}g(X,U)] + \frac{n}{2(n-1)} A(U) [S(Z,X) - \frac{r}{n}g(Z,X)] + A(\tilde{M}(X,U)Z) + \frac{1}{2(n-1)} [(n-2)(\nabla_X S)(Z,U) + dr(X)g(Z,U)].$$
(3.3)

Again contracting (3.3) over Z and U we get

$$\frac{2n}{(n-1)}[A(LX) - \frac{r}{n}A(X)] = 0.$$

Since n > 2, the above expression implies that

(3.4)
$$A(LX) - \frac{r}{n}A(X) = 0.$$

We have Bianchi's second identity for (0,4) Riemannian curvature tensor ${\cal R}$ as follows:

$$(3.5)(\nabla_X R)(Y, Z, U, V) + (\nabla_Y R)(Z, X, U, V) + (\nabla_Z R)(X, Y, U, V) = 0.$$

Using (3.2) and (3.5) we get

$$\begin{split} [-A(X) + B(X)]M(Y, Z, U, V) + [-A(Y) + B(Y)]M(Z, X, U, V) \\ + [-A(Z) + B(Z)]M(X, Y, U, V) \\ + A(U)[M(Y, Z, X, V) + M(Z, X, Y, V) + M(X, Y, Z, V)] \\ + A(V)[M(Y, Z, U, X) + M(Z, X, U, Y) + M(X, Y, U, Z)] \\ + \frac{1}{2(n-1)}[(\nabla_X S)(Z, U)g(Y, V) - (\nabla_X S)(Y, U)g(Z, V) \\ + (\nabla_X S)(Y, V)g(Z, U) - (\nabla_X S)(Z, V)g(Y, U) \\ + (\nabla_Y S)(X, U)g(Z, V) - (\nabla_Y S)(Z, U)g(X, V) \\ + (\nabla_Y S)(Z, V)g(X, U) - (\nabla_Y S)(X, V)g(Z, U) \\ + (\nabla_Z S)(Y, U)g(X, V) - (\nabla_Z S)(X, U)g(Y, V) \\ + (\nabla_Z S)(X, V)g(Y, U) - (\nabla_Z S)(Y, V)g(X, U)] = 0. \end{split}$$

Making use of (2.2) in the equation (3.6) we get

$$\begin{split} [-A(X) + B(X)]M(Y, Z, U, V) + [-A(Y) + B(Y)]M(Z, X, U, V) \\ + [-A(Z) + B(Z)]M(X, Y, U, V) \\ + \frac{1}{2(n-1)} \Big[(\nabla_X S)(Z, U)g(Y, V) - (\nabla_X S)(Y, U)g(Z, V) \\ + (\nabla_X S)(Y, V)g(Z, U) - (\nabla_X S)(Z, V)g(Y, U) \\ + (\nabla_Y S)(X, U)g(Z, V) - (\nabla_Y S)(Z, U)g(X, V) \\ + (\nabla_Y S)(Z, V)g(X, U) - (\nabla_Y S)(X, V)g(Z, U) \\ + (\nabla_Z S)(Y, U)g(X, V) - (\nabla_Z S)(X, U)g(Y, V) \\ + (\nabla_Z S)(X, V)g(Y, U) - (\nabla_Z S)(Y, V)g(X, U) \Big] = 0. \end{split}$$

Contracting (3.7) over Y and V we get

$$n[-A(X) + B(X)] \left[S(Z,U) - \frac{r}{n} g(Z,U) \right] + 2(n-1) \left[-A(\tilde{M}(Z,X)U) + B(\tilde{M}(Z,X)U) \right] - n[-A(Z) + B(Z)] \left[S(X,U) - \frac{r}{n} g(X,U) \right] + (n-3) \left\{ (\nabla_X S)(Z,U) - (\nabla_Z S)(X,U) \right\} + \frac{1}{2} \left\{ dr(X)g(Z,U) - dr(Z)g(X,U) \right\} = 0.$$
(3.8)

Again contracting (3.8) over Z and U we get

$$(3.2n[A(LX) - \frac{r}{n}A(X)] - 2n[B(LX) - \frac{r}{n}B(X)] + (n-2)dr(X) = 0.$$

Combining the equations (3.4) and (3.9), we obtain

(3.10)
$$B(LX) - \frac{r}{n}B(X) = \frac{(n-2)}{2n}dr(X).$$

Thus we can state the following:

Theorem 3.1. The scalar curvature r of an almost pseudo m-projectively symmetric manifold is constant if and only if

(3.11)
$$B(LX) - \frac{r}{n}B(X) = 0$$

holds for all vector fields.

4. $(APMPS)_n, (n > 2)$ with Codazzi type of Ricci tensor

In 1978, Gray [14] introduced two classes of Riemannian manifolds. The class A consisting of all Riemannian manifolds whose Ricci tensor S satisfies,

$$(\nabla_X S)(Y,Z) + (\nabla_Y S)(Z,X) + (\nabla_Z S)(X,Y) = 0,$$

and the class B consisting of all Riemannian manifolds whose Ricci tensor is a Codazzi tensor, that is,

$$(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) = 0.$$

Suppose that the Ricci tensor of the $(APMPS)_n$ is a Codazzi type tensor, that is,

(4.1)
$$(\nabla_X S)(Y,Z) = (\nabla_Y S)(X,Z).$$

Now from (3.1) we get

$$(\nabla_X M)(Y, Z, U, V) = (\nabla_X R)(Y, Z, U, V) -\frac{1}{2(n-1)} [(\nabla_X S)(Z, U)g(Y, V) - (\nabla_X S)(Y, U)g(Z, V) + (\nabla_X S)(Y, V)g(Z, U) - (\nabla_X S)(Z, V)g(Y, U)].$$
(4.2)

By (4.2) we obtain

$$\begin{split} (\nabla_X M)(Y,Z,U,V) + (\nabla_Y M)(Z,X,U,V) + (\nabla_Z M)(X,Y,U,V) \\ &= [(\nabla_X R)(Y,Z,U,V) + (\nabla_Y R)(Z,X,U,V) + (\nabla_Z R)(X,Y,U,V)] \\ &- \frac{1}{2(n-1)} [(\nabla_X S)(Z,U)g(Y,V) - (\nabla_X S)(Y,U)g(Z,V) \\ &+ (\nabla_X S)(Y,V)g(Z,U) - (\nabla_X S)(Z,V)g(Y,U) \\ &+ (\nabla_Y S)(X,U)g(Z,V) - (\nabla_Y S)(Z,U)g(X,V) \\ &+ (\nabla_Y S)(Z,V)g(X,U) - (\nabla_Y S)(X,V)g(Z,U) \\ &+ (\nabla_Z S)(Y,U)g(X,V) - (\nabla_S)(X,U)g(Y,V) \\ &+ (\nabla_Z S)(X,V)g(Y,U) - (\nabla_Z S)(Y,V)g(X,U)]. \end{split}$$
(4.3)

Using (4.1) and (3.5) in (4.3) we get

$$(4(\mathbf{A})_X M)(Y, Z, U, V) + (\nabla_Y M)(Z, X, U, V) + (\nabla_Z M)(X, Y, U, V) = 0.$$

Hence we have the following theorem.

Theorem 4.1. In an $(APMPS)_n$, (n > 2) satisfying Codazzi type of Ricci tensor, the m-projective curvature tensor satisfies Bianchi's second identity.

5. Einstein $(APMPS)_n, (n > 2)$

If a $(APMPS)_n$, (n > 2) is an Einstein manifold, then the Ricci tensor satisfies

(5.1)
$$S(Y,Z) = \frac{r}{n}g(Y,Z)$$

Therefore,

(5.2)
$$(\nabla_X S)(Y, Z) = 0,$$

and

$$dr(X) = 0$$

Using (5.1) and (5.2) we get from (1.5)

(5.4)
$$(\nabla_X M)(Y, Z, U, V) = (\nabla_X R)(Y, Z, U, V),$$

which yields

$$\begin{aligned} [A(X) + B(X)]M(Y, Z, U, V) + A(Y)M(X, Z, U, V) \\ &+ A(Z)M(Y, X, U, V) + A(U)M(Y, Z, X, V) \\ &+ A(V)M(Y, Z, U, X) = [A(X) + B(X)]R(Y, Z, U, V) \\ &+ A(Y)R(X, Z, U, V) + A(Z)R(Y, X, U, V) \\ &+ A(U)R(Y, Z, X, V) + A(V)R(Y, Z, U, X). \end{aligned}$$

In light of the equation (5.1), the equation (1.5) assumes the following form

(5.6)
$$M(Y, Z, U, V) = R(Y, Z, U, V) - \frac{r}{n(n-1)} [g(Z, U)g(Y, V) - g(Y, U)g(Z, V)].$$

Now using (5.6) in (5.5) we get

$$\begin{aligned} \frac{r}{n(n-1)} [\{A(X) + B(X)\}\{g(Z,U)g(Y,V) - g(Y,U)g(Z,V)\} \\ &+ A(Y)\{g(Z,U)g(X,V) - g(X,U)g(Z,V)\} \\ &+ A(Z)\{g(X,U)g(Y,V) - g(Y,U)g(X,V)\} \\ &+ A(U)\{g(Z,X)g(Y,V) - g(Y,X)g(Z,V)\} \\ &+ A(V)\{g(Z,U)g(Y,X) - g(Y,U)g(Z,X)\} = 0, \end{aligned}$$

which implies

$$r[\{A(X) + B(X)\}\{g(Z,U)g(Y,V) - g(Y,U)g(Z,V)\} + A(Y)\{g(Z,U)g(X,V) - g(X,U)g(Z,V)\} + A(Z)\{g(X,U)g(Y,V) - g(Y,U)g(X,V)\} + A(U)\{g(Z,X)g(Y,V) - g(Y,X)g(Z,V)\} + A(V)\{g(Z,U)g(Y,X) - g(Y,U)g(Z,X)\} = 0.$$
(5.7)

Now contracting (5.7) over Y and V we get

$$\begin{split} r[(n-1)\big[A(X)+B(X)\big]g(Z,U)+A(X)g(Z,U)\\ -A(Z)g(X,U)+(n-1)\big[A(Z)g(X,U)+A(U)g(Z,X)\big]\\ +A(X)g(Z,U)-A(U)g(Z,X)=0, \end{split}$$

which implies

(5.8)
$$r[\{(n+1)A(X) + (n-1)B(X)\}g(Z,U) + (n-2)\{A(Z)g(X,U) + A(U)g(Z,X)\}] = 0.$$

Again contracting (5.8) over Z and U we get

$$r[n(n+1)A(X) + n(n-1)B(X) + 2(n-2)A(X)] = 0,$$

which, in turn implies

$$r(n-1)[(n+4)A(X) + nB(X)] = 0,$$

which implies

(5.9)
$$r[(n+4)A(X) + nB(X)] = 0.$$

Again contracting (5.8) over Z and X, we get

$$r[(n+1)A(U) + (n-1)B(U) + (n-2)A(U) + n(n-2)A(U)] = 0,$$

which implies

(5.10)
$$r[(n+1)A(U) + B(U)] = 0.$$

Replacing U by X we get

(5.11)
$$r[(n+1)A(X) + B(X)] = 0.$$

Again contracting (5.8) over X and U we get

$$r[(n+1)A(Z) + (n-1)B(Z) + n(n-2)A(Z) + (n-2)A(Z)] = 0,$$

which implies

(5.12)
$$r[(n+1)A(Z) + B(Z)] = 0.$$

Replacing Z by X we get

(5.13)
$$r[(n+1)A(X) + B(X)] = 0.$$

Adding (5.9), (5.11) and (5.13) yields

$$r[(3n+6)A(X) + (n+2)B(X)] = 0,$$

which implies

$$r(n+2)[3A(X) + B(X)] = 0.$$

Therefore, either r = 0 or 3A(X) + B(X) = 0. Thus, we can state the following theorem:

Theorem 5.1. If an Einstein $(APMPS)_n$, (n > 2) is an almost pseudo symmetric manifold, then the scalar curvature of the manifold vanishes provided $3A(X) + B(X) \neq 0$.

Again, if in an $(APMPS)_n r = 0$, then using (1.6) and (5.6) in (5.4), we get

$$\begin{aligned} (\nabla_X R)(Y, Z, U, V) &= & [A(X) + B(X)]R(Y, Z, U, V) \\ &+ & A(Y)R(X, Z, U, V) + A(Z)R(Y, X, U, V) \\ &+ & A(U)R(Y, Z, X, V) + A(V)R(Y, Z, U, X) \end{aligned}$$

Hence we have the following theorem:

Theorem 5.2. If in an Einstein $(APMPS)_n$, (n > 2) the scalar curvature vanishes, then it is an almost pseudo symmetric manifold.

Now, Let ρ be a vector field defined by

$$g(X,\rho) = \alpha(X),$$

where $\alpha(X) = A(X) - B(X)$.

Further, we suppose that in an Einstein $(APMPS)_n$, the vector field ρ defined above is parallel. Then we have

(5.14)
$$\nabla_X \rho = 0$$

for all X. By Ricci identity and (5.4) we get

(5.15)
$$R(X, Y, \rho, U) = 0,$$

which implies

$$(5.16) S(Y,\rho) = 0.$$

Using (5.1) in (5.16) we get

$$rg(Y,\rho) = 0.$$

Thus, either r = 0 or $\|\rho\|^2 \neq 0$. If r = 0 then using (1.6) and (5.6) in (5.4), it follows that the manifold is an almost pseudo symmetric manifold. Thus we have:

Theorem 5.3. If the vector field defined by $g(X, \rho) = A(X) - B(X)$ is a parallel vector field in an Einstein $(APMPS)_n$, (n > 2), then it is an almost pseudo symmetric manifold provided $|| \rho || \neq 0$.

6. Examples of $(APMPS)_n$

Example1

Let us consider a Lorentzian metric g on \mathbb{R}^4 defined by

(6.1)
$$ds^2 = g_{ij}dx^i dx^j = x^1 (dx^1)^2 + x^1 (dx^2)^2 + x^1 (dx^3)^2 - (dx^4)^2$$

where i, j = 1, 2, 3, 4. Then the only non-vanishing components of the Christoffel symbols, the Riemannian curvature tensors and the Ricci tensor are

$$\Gamma_{22}^1 = \Gamma_{33}^1 = -\frac{1}{2x^1}, \quad \Gamma_{11}^1 = \Gamma_{12}^2 = \Gamma_{13}^3 = \frac{1}{2x^1},$$

$$R_{1221} = R_{1331} = -\frac{1}{2x^1}, \quad R_{2332} = \frac{1}{4x^1},$$

and

$$S_{22} = S_{33} = -\frac{1}{4(x^1)^2}, \quad S_{11} = -\frac{1}{(x^1)^2}, \quad S_{44} = 0$$

And the scalar curvature of the resulting manifold (R^4, g) is

$$r = -\frac{3}{2(x^1)^3}.$$

Now, the non vanishing components of m-projective curvature tensor and their covariant derivatives are:

$$M_{1221} = M_{1331} = -\frac{7}{24x^1}, \qquad M_{2332} = \frac{1}{3x^1},$$

$$M_{1221,1} = M_{2332,1} = \frac{7}{24x^2}, \qquad M_{2332,1} = -\frac{1}{3x^2},$$

where ',' denotes the covariant derivative with respect to the metric tensor.

Let us choose the associated 1-forms as follows:

$$A_i(x) = \begin{cases} 0, & for \ i = 1\\ x^1, & otherwise, \end{cases}$$

(6.2)

$$B_i(x) = \begin{cases} -\frac{1}{x^1}, & for \ i = 1\\ -x^1, & otherwise, \end{cases}$$

(6.3)

at any point $x \in \mathbb{R}^4$. To verify the relation (1.6), it is sufficient to check the following equations:

$$M_{1221,1} = \begin{bmatrix} A_1 + B_1 \end{bmatrix} M_{1221} + A_1 M_{1221} + A_2 M_{1121} + A_2 M_{1211} + A_1 M_{1221},$$
(6.4)

and

$$M_{2332,1} = \begin{bmatrix} A_1 + B_1 \end{bmatrix} M_{2332} + A_2 M_{1332} + A_3 M_{2132} + A_3 M_{2312} + A_2 M_{2331}.$$
(6.5)

Since for the other cases (1.5) holds trivially. By (6.2) and (6.3) we get

$$R.H.S. of (6.4) = [A_1 + B_1] M_{1221} + A_1 M_{1221} + A_1 M_{1221}$$

= $[3A_1 + B_1] M_{1221}$
= $3(0) \left(-\frac{7}{24x^1} \right) + \left(-\frac{1}{x^1} \right) \left(-\frac{7}{24x^1} \right)$
= $\frac{7}{24x^2}$
= $M_{1212,1}$
= $L.H.S. of (6.4).$

By a similar argument it can be shown that (6.5) is also true. So $(\mathbb{R}4, g)$ is a $(APMPS)_n$.

Example2

Consider a Riemannian space V_n , $(n \ge 4)$ with the metric is given by

(6.6)
$$ds^{2} = \phi (dx^{1})^{2} + K_{\alpha\beta} dx^{\alpha} dx^{\beta} + 2dx^{1} dx^{n},$$

where $[K_{\alpha\beta}]$ is a symmetric and non singular matrix consisting of constants and ϕ is a function of $x^1, x^2, ..., x^{n-1}$ and independent of x^n , and $1 < \alpha, \beta < n$. In the metric considered, the only non-vanishing components of Christoffel symbols, Riemannian curvature tensor and Ricci tensor are [19]

$$\Gamma_{11}^{\beta} = -\frac{1}{2}K^{\alpha\beta}\phi_{.\alpha}, \quad \Gamma_{11}^{n} = \frac{1}{2}\phi_{.1}, \quad ,\Gamma_{1\alpha}^{n} = \frac{1}{2}\phi_{.\alpha},$$

(6.7)
$$R_{1\alpha\beta1} = \frac{1}{2}\phi_{.\alpha\beta}, \qquad S_{11} = \frac{1}{2}K^{\alpha\beta}\phi_{.\alpha\beta},$$

where '.' denotes the partial differentiation with respect to the coordinates and $K^{\alpha\beta}$ are the elements of the matrix inverse to $[K_{\alpha\beta}]$. Here we consider $K_{\alpha\beta}$ as Kronecker symbol $\delta_{\alpha\beta}$ and

$$\phi = (M_{\alpha\beta} + \delta_{\alpha\beta})x^{\alpha}x^{\beta}e^{(x^{1})^{2}},$$

where $M_{\alpha\beta}$ are constant and satisfy the relations

$$M_{\alpha\beta} = 0, \text{ for } \alpha \neq \beta,$$

$$\neq 0, \text{ for } \alpha = \beta,$$

$$\sum_{\alpha=1}^{n-1} M_{\alpha\alpha} = 0.$$

This is to be noted that the metric with this form of ϕ was considered by De and Gazi [12]. Thus we have

$$\phi_{\alpha\beta} = 2(M_{\alpha\beta} + \delta_{\alpha\beta})e^{(x^{1})^{2}}, \qquad \delta_{\alpha\beta}\delta^{\alpha\beta} = n - 2,$$
$$\delta^{\alpha\beta}M_{\alpha\beta} = \sum_{\alpha=1}^{n-1}M_{\alpha\alpha} = 0.$$

Therefore

$$\delta^{\alpha\beta}\phi_{\alpha\beta} = 2(\delta^{\alpha\beta}M_{\alpha\beta} + \delta^{\alpha\beta}\delta_{\alpha\beta})e^{(x^1)^2} = 2(n-2)e^{(x^1)^2}.$$

Since $\phi_{\alpha\beta}$ vanishes for $\alpha \neq \beta$, the only non-zero components of the Riemannian curvature tensor and Ricci tensor by virtue of (6.7) are

$$R_{1\alpha\alpha1} = \frac{1}{2}\phi_{.\alpha\alpha} = (1+M_{\alpha\alpha})e^{(x^1)^2},$$
$$S_{11} = \frac{1}{2}\phi_{.\alpha\beta}\delta^{\alpha\beta} = (n-2)e^{(x^1)^2}.$$

Also, the scalar curvature r = 0.

Hence the only non-zero components of the m-projective curvature tensor, and their covariant derivatives are

$$M_{1\alpha\alpha1} = (1 + M_{\alpha\alpha})e^{(x^{1})^{2}} + \frac{n-2}{2(n-1)}e^{(x^{1})^{2}}$$
$$= (1 + \frac{n}{2(n-1)}M_{\alpha\alpha})e^{(x^{1})^{2}},$$

$$M_{1\alpha\alpha 1,1} = 2x^{1} \left(1 + \frac{n}{2(n-1)} M_{\alpha\alpha}\right) e^{(x^{1})^{2}}$$
$$= 2x^{1} M_{1\alpha\alpha 1},$$

where ',' denotes the covariant derivative with respect to the metric tensor.

Let us choose the associated 1-forms as follows:

$$A_i(x) = \begin{cases} x^1, & for \ i = 1\\ 0, & otherwise, \end{cases}$$

(6.8)

$$B_i(x) = \begin{cases} -x^1, & for \ i = 1\\ 0, & otherwise, \end{cases}$$

at any point $x \in V_n$. To verify the relation (1.6), it is sufficient to check the following equation:

(6.9)
$$M_{1\alpha\alpha1,1} = (3A_1 + B_1)M_{\alpha11\alpha}$$

$$R.H.S. of (6.9) = (3A_1 + B_1)M_{1\alpha\alpha 1}$$

= $(3x^1 - x^1)M_{1\alpha\alpha 1}$
= $2x^1M_{1\alpha\alpha 1}$
= $M_{1\alpha\alpha 1,1}$
= $L.H.S. of (6.9).$

So V_n is a $(APMPS)_n$.

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