

SCREEN PSEUDO-SLANT LIGHTLIKE SUBMANIFOLDS OF INDEFINITE KAEHLER MANIFOLDS

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Abstract. In this paper we introduce the notion of screen pseudo-slant lightlike submanifolds of indefinite Kaehler manifolds giving characterization theorem with some non-trivial examples of such submanifolds. Integrability conditions of distributions D_1 , D_2 and $RadTM$ on screen pseudo-slant lightlike submanifolds of an indefinite Kaehler manifold have been obtained. Further, we obtain necessary and sufficient conditions for foliations determined by above distributions to be totally geodesic.

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1. Introduction

The theory of lightlike submanifolds of a semi-Riemannian manifold was introduced by Duggal and Bejancu [3]. In [2], B.Y. Chen defined slant immersions in complex geometry as a natural generalization of both holomorphic immersions and totally real immersions. In [5], A. Lotta introduced the concept of slant immersion of a Riemannian manifold into an almost contact metric manifold. A. Carriazo defined and studied bi-slant submanifolds of almost Hermitian and almost contact metric manifolds and further gave the notion of pseudo-slant submanifolds [1]. On other hand, the theory of invariant, screen slant, screen real, screen Cauchy-Riemann lightlike submanifolds have been studied in [4]. Thus motivated sufficiently, we introduce the notion of screen pseudo-slant lightlike submanifolds of indefinite Kaehler manifolds. This new class of lightlike submanifolds of an indefinite Kaehler manifold includes invariant, screen slant, screen real, screen Cauchy-Riemann lightlike submanifolds as its sub-cases. The paper is arranged as follows. There are some basic results in section 2. In section 3, we study screen pseudo-slant lightlike submanifolds of an indefinite Kaehler manifold, giving some examples. Section 4 is devoted to the study of foliations determined by distributions on screen pseudo-slant lightlike submanifolds of indefinite Kaehler manifolds.

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2. Preliminaries

A submanifold (M^m, g) immersed in a semi-Riemannian manifold $(\overline{M}^{m+n}, \overline{g})$ is called a lightlike submanifold [3] if the metric g induced from \overline{g} is degenerate and the radical distribution $RadTM$ is of rank r , where $1 \leq r \leq m$. Let $S(TM)$ be a screen distribution which is a semi-Riemannian complementary distribution of $RadTM$ in TM , that is

$$(2.1) \quad TM = RadTM \oplus_{orth} S(TM).$$

Now consider a screen transversal vector bundle $S(TM^\perp)$, which is a semi-Riemannian complementary vector bundle of $RadTM$ in TM^\perp . Since for any local basis $\{\xi_i\}$ of $RadTM$, there exists a local null frame $\{N_i\}$ of sections with values in the orthogonal complement of $S(TM^\perp)$ in $[S(TM)]^\perp$ such that $\overline{g}(\xi_i, N_j) = \delta_{ij}$ and $\overline{g}(N_i, N_j) = 0$, it follows that there exists a lightlike transversal vector bundle $ltr(TM)$ locally spanned by $\{N_i\}$. Let $tr(TM)$ be complementary (but not orthogonal) vector bundle to TM in $T\overline{M}|_M$. Then

$$(2.2) \quad tr(TM) = ltr(TM) \oplus_{orth} S(TM^\perp),$$

$$(2.3) \quad T\overline{M}|_M = TM \oplus tr(TM),$$

$$(2.4) \quad T\overline{M}|_M = S(TM) \oplus_{orth} [RadTM \oplus ltr(TM)] \oplus_{orth} S(TM^\perp).$$

Following are four cases of a lightlike submanifold $(M, g, S(TM), S(TM^\perp))$:

- Case.1 r-lightlike if $r < \min(m, n)$,
- Case.2 co-isotropic if $r = n < m, S(TM^\perp) = \{0\}$,
- Case.3 isotropic if $r = m < n, S(TM) = \{0\}$,
- Case.4 totally lightlike if $r = m = n, S(TM) = S(TM^\perp) = \{0\}$.

The Gauss and Weingarten formulae are given as

$$(2.5) \quad \overline{\nabla}_X Y = \nabla_X Y + h(X, Y),$$

$$(2.6) \quad \overline{\nabla}_X V = -A_V X + \nabla_X^t V,$$

for all $X, Y \in \Gamma(TM)$ and $V \in \Gamma(tr(TM))$, where $\nabla_X Y, A_V X$ belong to $\Gamma(TM)$ and $h(X, Y), \nabla_X^t V$ belong to $\Gamma(tr(TM))$. ∇ and ∇^t are linear connections on M and on the vector bundle $tr(TM)$, respectively. The second fundamental form h is a symmetric $F(M)$ -bilinear form on $\Gamma(TM)$ with values in $\Gamma(tr(TM))$ and the shape operator A_V is a linear endomorphism of $\Gamma(TM)$. From (2.5) and (2.6), for any $X, Y \in \Gamma(TM), N \in \Gamma(ltr(TM))$ and $W \in \Gamma(S(TM^\perp))$, we have

$$(2.7) \quad \overline{\nabla}_X Y = \nabla_X Y + h^l(X, Y) + h^s(X, Y),$$

$$(2.8) \quad \overline{\nabla}_X N = -A_N X + \nabla_X^l N + D^s(X, N),$$

$$(2.9) \quad \bar{\nabla}_X W = -A_W X + \nabla_X^s W + D^l(X, W),$$

where $h^l(X, Y) = L(h(X, Y))$, $h^s(X, Y) = S(h(X, Y))$, $D^l(X, W) = L(\nabla_X^t W)$, $D^s(X, N) = S(\nabla_X^t N)$. L and S are the projection morphisms of $tr(TM)$ on $ltr(TM)$ and $S(TM^\perp)$, respectively. ∇^l and ∇^s are linear connections on $ltr(TM)$ and $S(TM^\perp)$ called the lightlike connection and screen transversal connection on M , respectively.

Now by using (2.5), (2.7)-(2.9) and metric connection $\bar{\nabla}$, we obtain

$$(2.10) \quad \bar{g}(h^s(X, Y), W) + \bar{g}(Y, D^l(X, W)) = g(A_W X, Y),$$

$$(2.11) \quad \bar{g}(D^s(X, N), W) = \bar{g}(N, A_W X).$$

Denote the projection of TM on $S(TM)$ by \bar{P} . Then from the decomposition of the tangent bundle of a lightlike submanifold, for any $X, Y \in \Gamma(TM)$ and $\xi \in \Gamma(RadTM)$, we have

$$(2.12) \quad \nabla_X \bar{P}Y = \nabla_X^* \bar{P}Y + h^*(X, \bar{P}Y),$$

$$(2.13) \quad \nabla_X \xi = -A_\xi^* X + \nabla_X^{*t} \xi,$$

By using above equations, we obtain

$$(2.14) \quad \bar{g}(h^l(X, \bar{P}Y), \xi) = g(A_\xi^* X, \bar{P}Y),$$

$$(2.15) \quad \bar{g}(h^*(X, \bar{P}Y), N) = g(A_N X, \bar{P}Y),$$

$$(2.16) \quad \bar{g}(h^l(X, \xi), \xi) = 0, \quad A_\xi^* \xi = 0.$$

It is important to note that in general ∇ is not a metric connection. Since $\bar{\nabla}$ is a metric connection, by using (2.7), we get

$$(2.17) \quad (\nabla_X g)(Y, Z) = \bar{g}(h^l(X, Y), Z) + \bar{g}(h^l(X, Z), Y).$$

An indefinite almost Hermitian manifold $(\bar{M}, \bar{g}, \bar{J})$ is a $2m$ -dimensional semi-Riemannian manifold \bar{M} with semi-Riemannian metric \bar{g} of constant index q , $0 < q < 2m$ and a $(1, 1)$ tensor field \bar{J} on \bar{M} such that following conditions are satisfied:

$$(2.18) \quad \bar{J}^2 X = -X,$$

$$(2.19) \quad \bar{g}(\bar{J}X, \bar{J}Y) = \bar{g}(X, Y),$$

for all $X, Y \in \Gamma(T\bar{M})$.

An indefinite almost Hermitian manifold $(\bar{M}, \bar{g}, \bar{J})$ is called an indefinite Kaehler manifold if \bar{J} is parallel with respect to $\bar{\nabla}$, i.e.,

$$(2.20) \quad (\bar{\nabla}_X \bar{J})Y = 0,$$

for all $X, Y \in \Gamma(T\bar{M})$, where $\bar{\nabla}$ is Levi-Civita connection with respect to \bar{g} .

3. Screen Pseudo-Slant Lightlike Submanifolds

In this section, we introduce the notion of screen pseudo-slant lightlike submanifolds of indefinite Kaehler manifolds. At first, we state the following Lemma for later use:

Lemma 3.1. *Let M be a $2q$ -lightlike submanifold of an indefinite Kaehler manifold \overline{M} of index $2q$ such that $2q < \dim(M)$. Then the screen distribution $S(TM)$ of lightlike submanifold M is Riemannian.*

The proof of above Lemma follows as in Lemma 3.1 of [6], so we omit it.

Definition 1. Let M be a $2q$ -lightlike submanifold of an indefinite Kaehler manifold \overline{M} of index $2q$ such that $2q < \dim(M)$. Then we say that M is a screen pseudo-slant lightlike submanifold of \overline{M} if the following conditions are satisfied:

- (i) $RadTM$ is invariant with respect to \overline{J} , i.e. $\overline{J}(RadTM) = RadTM$,
- (ii) there exists non-degenerate orthogonal distributions D_1 and D_2 on M such that $S(TM) = D_1 \oplus_{orth} D_2$,
- (iii) the distribution D_1 is anti-invariant, i.e. $\overline{J}D_1 \subset S(TM^\perp)$,
- (iv) the distribution D_2 is slant with angle $\theta (\neq \pi/2)$, i.e. for each $x \in M$ and each non-zero vector $X \in (D_2)_x$, the angle θ between $\overline{J}X$ and the vector subspace $(D_2)_x$ is a constant ($\neq \pi/2$), which is independent of the choice of $x \in M$ and $X \in (D_2)_x$.

This constant angle θ is called the slant angle of distribution D_2 . A screen pseudo-slant lightlike submanifold is said to be proper if $D_1 \neq \{0\}$, $D_2 \neq \{0\}$ and $\theta \neq 0$.

From the above definition, we have the following decomposition

$$(3.1) \quad TM = RadTM \oplus_{orth} D_1 \oplus_{orth} D_2.$$

In particular, we have

- (i) if $D_1 = 0$, then M is a screen slant lightlike submanifold,
- (ii) if $D_2 = 0$, then M is a screen real lightlike submanifold,
- (iii) if $D_1 = 0$ and $\theta = 0$, then M is an invariant lightlike submanifold,
- (iv) if $D_1 \neq 0$ and $\theta = 0$, then M is a screen CR-lightlike submanifold.

Thus the above new class of lightlike submanifolds of an indefinite Kaehler manifold includes invariant, screen slant, screen real, screen Cauchy-Riemann lightlike submanifolds as its sub-cases which have been studied in [4].

Let $(\mathbb{R}_{2q}^{2m}, \overline{g}, \overline{J})$ denote the manifold \mathbb{R}_{2q}^{2m} with its usual Kaehler structure given by

$$\overline{g} = \frac{1}{4}(-\sum_{i=1}^q dx^i \otimes dx^i + dy^i \otimes dy^i + \sum_{i=q+1}^m dx^i \otimes dx^i + dy^i \otimes dy^i),$$

$$\overline{J}(\sum_{i=1}^m (X_i \partial x_i + Y_i \partial y_i)) = \sum_{i=1}^m (Y_i \partial x_i - X_i \partial y_i),$$

where (x^i, y^i) are the cartesian coordinates on \mathbb{R}_{2q}^{2m} . Now, we construct some examples of screen pseudo-slant lightlike submanifolds of an indefinite Kaehler manifold.

Example 1. Let $(\mathbb{R}_2^{12}, \bar{g}, \bar{J})$ be an indefinite Kaehler manifold, where \bar{g} is of signature $(-, +, +, +, +, +, -, +, +, +, +, +)$ with respect to the canonical basis $\{\partial x_1, \partial x_2, \partial x_3, \partial x_4, \partial x_5, \partial x_6, \partial y_1, \partial y_2, \partial y_3, \partial y_4, \partial y_5, \partial y_6\}$.

Suppose M is a submanifold of \mathbb{R}_2^{12} given by $x^1 = y^2 = u_1, x^2 = -y^1 = u_2, x^3 = u_3 \cos \beta, y^3 = u_3 \sin \beta, x^4 = u_4 \sin \beta, y^4 = u_4 \cos \beta, x^5 = u_5 \cos \theta, y^5 = u_6 \cos \theta, x^6 = u_6 \sin \theta, y^6 = u_5 \sin \theta$.

The local frame of TM is given by $\{Z_1, Z_2, Z_3, Z_4, Z_5, Z_6\}$, where

$$\begin{aligned} Z_1 &= 2(\partial x_1 + \partial y_2), & Z_2 &= 2(\partial x_2 - \partial y_1), \\ Z_3 &= 2(\cos \beta \partial x_3 + \sin \beta \partial y_3), & Z_4 &= 2(\sin \beta \partial x_4 + \cos \beta \partial y_4), \\ Z_5 &= 2(\cos \theta \partial x_5 + \sin \theta \partial y_6), & Z_6 &= 2(\sin \theta \partial x_6 + \cos \theta \partial y_5). \end{aligned}$$

Hence $RadTM = span\{Z_1, Z_2\}$ and $S(TM) = span\{Z_3, Z_4, Z_5, Z_6\}$.

Now $ltr(TM)$ is spanned by $N_1 = -\partial x_1 + \partial y_2, N_2 = -\partial x_2 - \partial y_1$. $S(TM^\perp)$ is spanned by

$$\begin{aligned} W_1 &= 2(\sin \beta \partial x_3 - \cos \beta \partial y_3), & W_2 &= 2(\cos \beta \partial x_4 - \sin \beta \partial y_4), \\ W_3 &= 2(\sin \theta \partial x_5 - \cos \theta \partial y_6), & W_4 &= 2(\cos \theta \partial x_6 - \sin \theta \partial y_5). \end{aligned}$$

It follows that $\bar{J}Z_1 = Z_2$ and $\bar{J}Z_2 = -Z_1$, which implies that $RadTM$ is invariant, i.e. $\bar{J}RadTM = RadTM$. On the other hand, we can see that $D_1 = span\{Z_3, Z_4\}$ such that $\bar{J}Z_3 = W_1$ and $\bar{J}Z_4 = W_2$, which implies that D_1 is anti-invariant with respect to \bar{J} and $D_2 = span\{Z_5, Z_6\}$ is a slant distribution with slant angle 2θ . Hence M is a screen pseudo-slant 2-lightlike submanifold of \mathbb{R}_2^{12} .

Example 2. Let $(\mathbb{R}_2^{12}, \bar{g}, \bar{J})$ be an indefinite Kaehler manifold, where \bar{g} is of signature $(-, +, +, +, +, +, -, +, +, +, +, +)$ with respect to the canonical basis $\{\partial x_1, \partial x_2, \partial x_3, \partial x_4, \partial x_5, \partial x_6, \partial y_1, \partial y_2, \partial y_3, \partial y_4, \partial y_5, \partial y_6\}$.

Suppose M is a submanifold of \mathbb{R}_2^{12} given by $x^1 = u_1, y^1 = -u_2, x^2 = -u_1 \cos \alpha - u_2 \sin \alpha, y^2 = -u_1 \sin \alpha + u_2 \cos \alpha, x^3 = y^4 = u_3, x^4 = y^3 = u_4, x^5 = u_5 \cos u_6, y^5 = u_5 \sin u_6, x^6 = \cos u_5, y^6 = \sin u_5$.

The local frame of TM is given by $\{Z_1, Z_2, Z_3, Z_4, Z_5, Z_6\}$, where

$$\begin{aligned} Z_1 &= 2(\partial x_1 - \cos \alpha \partial x_2 - \sin \alpha \partial y_2), \\ Z_2 &= 2(-\partial y_1 - \sin \alpha \partial x_2 + \cos \alpha \partial y_2), \\ Z_3 &= 2(\partial x_3 + \partial y_4), & Z_4 &= 2(\partial x_4 + \partial y_3), \\ Z_5 &= 2(\cos u_6 \partial x_5 + \sin u_6 \partial y_5 - \sin u_5 \partial x_6 + \cos u_5 \partial y_6), \\ Z_6 &= 2(-u_5 \sin u_6 \partial x_5 + u_5 \cos u_6 \partial y_5). \end{aligned}$$

Hence $RadTM = span\{Z_1, Z_2\}$ and $S(TM) = span\{Z_3, Z_4, Z_5, Z_6\}$.

Now $ltr(TM)$ is spanned by $N_1 = -\partial x_1 - \cos \alpha \partial x_2 - \sin \alpha \partial y_2, N_2 = \partial y_1 - \sin \alpha \partial x_2 + \cos \alpha \partial y_2$. $S(TM^\perp)$ is spanned by

$$\begin{aligned} W_1 &= 2(\partial x_3 - \partial y_4), & W_2 &= 2(\partial x_4 - \partial y_3), \\ W_3 &= 2(\cos u_6 \partial x_5 + \sin u_6 \partial y_5 + \sin u_5 \partial x_6 - \cos u_5 \partial y_6), \\ W_4 &= 2(u_5 \cos u_5 \partial x_6 + u_5 \sin u_5 \partial y_6). \end{aligned}$$

It follows that $\bar{J}Z_1 = Z_2$ and $\bar{J}Z_2 = -Z_1$, which implies that $RadTM$ is invariant, i.e. $\bar{J}RadTM = RadTM$. On the other hand, we can see that $D_1 = span\{Z_3, Z_4\}$ such that $\bar{J}Z_3 = W_2$ and $\bar{J}Z_4 = W_1$, which implies that D_1 is anti-invariant with respect to \bar{J} and $D_2 = span\{Z_5, Z_6\}$ is a slant distribution with slant angle $\pi/4$. Hence M is a screen pseudo-slant 2-lightlike submanifold of \mathbb{R}_2^{12} .

Now, for any vector field X tangent to M , we put $\bar{J}X = PX + FX$, where PX and FX are tangential and transversal parts of $\bar{J}X$, respectively. We denote the projections on $RadTM$, D_1 and D_2 in TM by P_1 , P_2 and P_3 , respectively. Similarly, we denote the projections of $tr(TM)$ on $ltr(TM)$, $\bar{J}(D_1)$ and D' by Q_1 , Q_2 and Q_3 , respectively, where D' is non-degenerate orthogonal complementary subbundle of $\bar{J}(D_1)$ in $S(TM^\perp)$. Then, for any $X \in \Gamma(TM)$, we get

$$(3.2) \quad X = P_1X + P_2X + P_3X.$$

Now applying \bar{J} to (3.2), we have

$$(3.3) \quad \bar{J}X = \bar{J}P_1X + \bar{J}P_2X + \bar{J}P_3X,$$

which gives

$$(3.4) \quad \bar{J}X = \bar{J}P_1X + \bar{J}P_2X + fP_3X + FP_3X,$$

where fP_3X (resp. FP_3X) denotes the tangential (resp. transversal) component of $\bar{J}P_3X$. Thus we get $\bar{J}P_1X \in \Gamma(RadTM)$, $\bar{J}P_2X \in \Gamma(\bar{J}(D_1)) \subset \Gamma(S(TM^\perp))$, $fP_3X \in \Gamma(D_2)$ and $FP_3X \in \Gamma(D')$. Also, for any $W \in \Gamma(tr(TM))$, we have

$$(3.5) \quad W = Q_1W + Q_2W + Q_3W.$$

Applying \bar{J} to (3.5), we obtain

$$(3.6) \quad \bar{J}W = \bar{J}Q_1W + \bar{J}Q_2W + \bar{J}Q_3W,$$

which gives

$$(3.7) \quad \bar{J}W = \bar{J}Q_1W + \bar{J}Q_2W + BQ_3W + CQ_3W,$$

where BQ_3W (resp. CQ_3W) denotes the tangential (resp. transversal) component of $\bar{J}Q_3W$. Thus we get $\bar{J}Q_1W \in \Gamma(ltr(TM))$, $\bar{J}Q_2W \in \Gamma(D_1)$, $BQ_3W \in \Gamma(D_2)$ and $CQ_3W \in \Gamma(D')$.

Now, by using (2.20), (3.4), (3.7) and (2.7)-(2.9) and identifying the components on $RadTM$, D_1 , D_2 , $ltr(TM)$, $\bar{J}(D_1)$ and D' , we obtain

$$(3.8) \quad \begin{aligned} \nabla_X^* \bar{J}P_1Y + P_1(\nabla_X fP_3Y) &= P_1(A_{FP_3Y}X) + P_1(A_{\bar{J}P_2Y}X) \\ &\quad + \bar{J}P_1\nabla_X Y, \end{aligned}$$

$$(3.9) \quad \begin{aligned} P_2(A_{\bar{J}P_1Y}^*X) + P_2(A_{\bar{J}P_2Y}X) + P_2(A_{FP_3Y}X) &= P_2(\nabla_X fP_3Y) \\ &\quad - \bar{J}Q_2h^s(X, Y), \end{aligned}$$

$$(3.10) \quad \begin{aligned} P_3(A_{\bar{J}P_1Y}^*X) + P_3(A_{\bar{J}P_2Y}X) + P_3(A_{FP_3Y}X) &= P_3(\nabla_X fP_3Y) \\ &\quad - fP_3(\nabla_X Y) - BQ_3h^s(X, Y), \end{aligned}$$

$$(3.11) \quad \begin{aligned} h^l(X, \bar{J}P_1Y) + D^l(X, \bar{J}P_2Y) + h^l(X, fP_3Y) + D^l(X, FP_3Y) \\ = \bar{J}h^l(X, Y), \end{aligned}$$

$$(3.12) \quad Q_2 \nabla_X^s \bar{J} P_2 Y + Q_2 \nabla_X^s F P_3 Y = \bar{J} P_2 \nabla_X Y - Q_2 h^s(X, \bar{J} P_1 Y) - Q_2 h^s(X, f P_3 Y),$$

$$(3.13) \quad Q_3 \nabla_X^s \bar{J} P_2 Y + Q_3 \nabla_X^s F P_3 Y - F P_3 \nabla_X Y = C Q_3 h^s(X, Y) - Q_3 h^s(X, f P_3 Y) - Q_3 h^s(X, \bar{J} P_1 Y).$$

Theorem 3.2. *Let M be a $2q$ -lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then M is a screen pseudo-slant lightlike submanifold of \bar{M} if and only if*

- (i) $ltr(TM)$ is invariant and D_1 is anti-invariant with respect to \bar{J} ,
- (ii) there exists a constant $\lambda \in (0, 1]$ such that $P^2 X = -\lambda X$.

Moreover, there also exists a constant $\mu \in [0, 1)$ such that $BFX = -\mu X$, for all $X \in \Gamma(D_2)$, where D_1 and D_2 are non-degenerate orthogonal distributions on M such that $S(TM) = D_1 \oplus_{orth} D_2$ and $\lambda = \cos^2 \theta$, θ is slant angle of D_2 .

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then D_1 is anti-invariant and $RadTM$ is invariant with respect to \bar{J} . For any $N \in \Gamma(ltr(TM))$ and $X \in \Gamma(S(TM))$, using (2.19) and (3.4), we obtain $\bar{g}(\bar{J}N, X) = -\bar{g}(N, \bar{J}X) = -\bar{g}(N, \bar{J}P_2 X + f P_3 X + F P_3 X) = 0$. Thus $\bar{J}N$ does not belong to $\Gamma(S(TM))$. For any $N \in \Gamma(ltr(TM))$ and $W \in \Gamma(S(TM^\perp))$, from (2.19) and (3.7), we have $\bar{g}(\bar{J}N, W) = -\bar{g}(N, \bar{J}W) = -\bar{g}(N, \bar{J}Q_2 W + BQ_3 W + CQ_3 W) = 0$. Hence, we conclude that $\bar{J}N$ does not belong to $\Gamma(S(TM^\perp))$.

Now suppose that $\bar{J}N \in \Gamma(RadTM)$. Then $\bar{J}(\bar{J}N) = \bar{J}^2 N = -N \in \Gamma(ltrTM)$, which contradicts that $RadTM$ is invariant. Thus $ltr(TM)$ is invariant with respect to \bar{J} . Now for any $X \in \Gamma(D_2)$ we have $|PX| = |\bar{J}X| \cos \theta$, which implies

$$(3.14) \quad \cos \theta = \frac{|PX|}{|\bar{J}X|}.$$

In view of (3.14), we get $\cos^2 \theta = \frac{|PX|^2}{|\bar{J}X|^2} = \frac{g(PX, PX)}{g(\bar{J}X, \bar{J}X)} = \frac{g(X, P^2 X)}{g(X, \bar{J}^2 X)}$, which gives

$$(3.15) \quad g(X, P^2 X) = \cos^2 \theta g(X, \bar{J}^2 X).$$

Since M is a screen pseudo-slant lightlike submanifold, $\cos^2 \theta = \lambda(\text{constant}) \in (0, 1]$ and therefore from (3.15), we get $g(X, P^2 X) = \lambda g(X, \bar{J}^2 X) = g(X, \lambda \bar{J}^2 X)$, which implies

$$(3.16) \quad g(X, (P^2 - \lambda \bar{J}^2)X) = 0.$$

Since $(P^2 - \lambda \bar{J}^2)X \in \Gamma(D_2)$ and the induced metric $g = g|_{D_2 \times D_2}$ is non-degenerate (positive definite), from (3.16), we have $(P^2 - \lambda \bar{J}^2)X = 0$, which implies

$$(3.17) \quad P^2 X = \lambda \bar{J}^2 X = -\lambda X.$$

Now, for any vector field $X \in \Gamma(D_2)$, we have

$$(3.18) \quad \bar{J}X = PX + FX,$$

where PX and FX are tangential and transversal parts of $\bar{J}X$, respectively. Applying \bar{J} to (3.18) and taking tangential component, we get

$$(3.19) \quad -X = P^2X + BFX.$$

From (3.17) and (3.19), we get

$$(3.20) \quad BFX = -\mu X, \quad \forall X \in \Gamma(D_2),$$

where $1 - \lambda = \mu(\text{constant}) \in [0, 1]$. This proves (ii).

Conversely suppose that conditions (i) and (ii) are satisfied. We can show that $RadTM$ is invariant in similar way that $ltr(TM)$ is invariant. From (3.19), for any $X \in \Gamma(D_2)$, we get

$$(3.21) \quad -X = P^2X - \mu X,$$

which implies

$$(3.22) \quad P^2X = -\lambda X,$$

where $1 - \mu = \lambda(\text{constant}) \in (0, 1]$.

Now $\cos \theta = \frac{g(\bar{J}X, PX)}{|\bar{J}X||PX|} = -\frac{g(X, \bar{J}PX)}{|\bar{J}X||PX|} = -\frac{g(X, P^2X)}{|\bar{J}X||PX|} = -\lambda \frac{g(X, \bar{J}^2X)}{|\bar{J}X||PX|} = \lambda \frac{g(\bar{J}X, \bar{J}X)}{|\bar{J}X||PX|}$.

From above equation, we get

$$(3.23) \quad \cos \theta = \lambda \frac{|\bar{J}X|}{|PX|}.$$

Therefore (3.14) and (3.23) give $\cos^2 \theta = \lambda(\text{constant})$.

Hence M is a screen pseudo-slant lightlike submanifold. □

Corollary 3.1. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} with slant angle θ , then for any $X, Y \in \Gamma(D_2)$, we have*

- (i) $g(PX, PY) = \cos^2 \theta g(X, Y)$,
- (ii) $g(FX, FY) = \sin^2 \theta g(X, Y)$.

The proof of above Corollary follows by using similar steps as in proof of Corollary 3.2 of [6].

Theorem 3.3. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then $RadTM$ is integrable if and only if*

- (i) $Q_2h^s(Y, \bar{J}P_1X) = Q_2h^s(X, \bar{J}P_1Y)$,
- (ii) $Q_3h^s(Y, \bar{J}P_1X) = Q_3h^s(X, \bar{J}P_1Y)$,
- (iii) $P_3A_{\bar{J}P_1X}^*Y = P_3A_{\bar{J}P_1Y}^*X$, for all $X, Y \in \Gamma(RadTM)$.

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Let $X, Y \in \Gamma(\text{Rad}TM)$. From (3.12), we have $Q_2h^s(X, \overline{J}P_1Y) = \overline{J}P_2\nabla_X Y$, which gives $Q_2h^s(X, \overline{J}P_1Y) - Q_2h^s(Y, \overline{J}P_1X) = \overline{J}P_2[X, Y]$. In view of (3.13), we get $Q_3h^s(X, \overline{J}P_1Y) = CQ_3h^s(X, Y) + FP_3\nabla_X Y$, which implies $Q_3h^s(X, \overline{J}P_1Y) - Q_3h^s(Y, \overline{J}P_1X) = FP_3[X, Y]$. Also from (3.10), we have $P_3A_{\overline{J}P_1Y}^*X = fP_3\nabla_X Y + BQ_3h^s(X, Y)$, which gives $P_3A_{\overline{J}P_1Y}^*X - P_3A_{\overline{J}P_1X}^*Y = fP_3[X, Y]$. Thus, we obtain the required results. \square

Theorem 3.4. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Then D_1 is integrable if and only if*

- (i) $P_1A_{\overline{J}P_2X}Y = P_1A_{\overline{J}P_2Y}X$ and $P_3A_{\overline{J}P_2X}Y = P_3A_{\overline{J}P_2Y}X$,
- (ii) $Q_3(\nabla_X^s \overline{J}P_2X) = Q_3(\nabla_X^s \overline{J}P_2Y)$, for all $X, Y \in \Gamma(D_1)$.

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Let $X, Y \in \Gamma(D_1)$. From (3.8), we have $P_1A_{\overline{J}P_2Y}X = -\overline{J}P_1\nabla_X Y$, which gives $P_1A_{\overline{J}P_2X}Y - P_1A_{\overline{J}P_2Y}X = \overline{J}P_1[X, Y]$. In view of (3.10), we obtain $P_3A_{\overline{J}P_2Y}X + BQ_3h^s(X, Y) = -fP_3\nabla_X Y$, which implies $P_3A_{\overline{J}P_2X}Y - P_3A_{\overline{J}P_2Y}X = fP_3[X, Y]$. Also from (3.13), we get $Q_3(\nabla_X^s \overline{J}P_2Y) + CQ_3h^s(X, Y) = -FP_3\nabla_X Y$, which gives $Q_3(\nabla_X^s \overline{J}P_2X) - Q_3(\nabla_X^s \overline{J}P_2Y) = FP_3[X, Y]$. This proves the theorem. \square

Theorem 3.5. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Then D_2 is integrable if and only if*

- (i) $P_1(\nabla_X fP_3Y - \nabla_Y fP_3X) = P_1(A_{FP_3Y}X - A_{FP_3X}Y)$,
 - (ii) $Q_2(\nabla_X^s fP_3Y - \nabla_Y^s fP_3X) = Q_2(h^s(Y, fP_3X) - h^s(X, fP_3Y))$,
- for all $X, Y \in \Gamma(D_2)$.

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Let $X, Y \in \Gamma(D_2)$. In view of (3.8), we get $P_1(\nabla_X fP_3Y) = P_1(A_{FP_3Y}X) + \overline{J}P_1\nabla_X Y$, thus $P_1(\nabla_X fP_3Y) - P_1(\nabla_Y fP_3X) - P_1(A_{FP_3Y}X) + P_1(A_{FP_3X}Y) = \overline{J}P_1[X, Y]$. From (3.12), we get $Q_2\nabla_X^s fP_3Y + Q_2h^s(X, fP_3Y) = \overline{J}P_2\nabla_X Y$, which implies $Q_2\nabla_X^s fP_3Y - Q_2\nabla_Y^s fP_3X + Q_2h^s(X, fP_3Y) - Q_2h^s(Y, fP_3X) = \overline{J}P_2[X, Y]$. This concludes the theorem. \square

Theorem 3.6. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Then the induced connection ∇ is a metric connection if and only if*

- (i) $\overline{J}Q_2h^s(X, Y) = 0$ and $BQ_3h^s(X, Y) = 0$,
- (ii) A_Y^* vanishes on $\Gamma(TM)$, for all $X \in \Gamma(TM)$ and $Y \in \Gamma(\text{Rad}TM)$.

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Then the induced connection ∇ on M is a metric connection if and only if $\text{Rad}TM$ is a parallel distribution with respect to ∇ [6]. From (2.7), (2.13) and (2.20), for any $X \in \Gamma(TM)$ and $Y \in \Gamma(\text{Rad}TM)$, we have $\overline{\nabla}_X \overline{J}Y = \overline{J}\nabla_X^* Y - \overline{J}A_Y^*X + \overline{J}h^l(X, Y) + \overline{J}Q_2h^s(X, Y) + \overline{J}Q_3h^s(X, Y)$. On comparing tangential components of both sides of the above equation, we get $\nabla_X \overline{J}Y = \overline{J}\nabla_X^* Y - \overline{J}A_Y^*X + \overline{J}Q_2h^s(X, Y) + BQ_3h^s(X, Y)$, which completes the proof. \square

4. Foliations Determined by Distributions

In this section, we obtain necessary and sufficient conditions for foliations determined by distributions on a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold to be totally geodesic.

Definition 2. A screen pseudo-slant lightlike submanifold M of an indefinite Kaehler manifold \overline{M} is said to be a mixed geodesic screen pseudo-slant lightlike submanifold if its second fundamental form h satisfies $h(X, Y) = 0$, for all $X \in \Gamma(D_1)$ and $Y \in \Gamma(D_2)$. Thus M is mixed geodesic screen pseudo-slant lightlike submanifold if $h^l(X, Y) = 0$ and $h^s(X, Y) = 0$, for all $X \in \Gamma(D_1)$ and $Y \in \Gamma(D_2)$.

Theorem 4.1. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Then $RadTM$ defines a totally geodesic foliation if and only if $\overline{g}(D^l(X, P_2Z) + D^l(X, FP_3Z), \overline{J}Y) = -\overline{g}(h^l(X, fP_3Z), \overline{J}Y)$, for all $X, Y \in \Gamma(RadTM)$ and $Z \in \Gamma(S(TM))$.*

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . To prove the distribution $RadTM$ defines a totally geodesic foliation, it is sufficient to show that $\nabla_X Y \in \Gamma(RadTM)$, for all $X, Y \in \Gamma(RadTM)$. Since $\overline{\nabla}$ is a metric connection, using (2.7), (2.19), (2.20) and (3.4), for any $X, Y \in \Gamma(RadTM)$ and $Z \in \Gamma(S(TM))$, we get $\overline{g}(\nabla_X Y, Z) = -\overline{g}(\overline{\nabla}_X(\overline{J}P_2Z + fP_3Z + FP_3Z), \overline{J}Y)$, which gives $\overline{g}(\nabla_X Y, Z) = -\overline{g}(D^l(X, \overline{J}P_2Z) + h^l(X, fP_3Z) + D^l(X, FP_3Z), \overline{J}Y)$. This completes the proof. □

Theorem 4.2. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Then D_1 defines a totally geodesic foliation if and only if*

- (i) $\overline{g}(h^s(X, fZ), \overline{J}Y) = -\overline{g}(\nabla_X^s FZ, \overline{J}Y)$,
- (ii) $D^s(X, \overline{J}N)$ has no component in $\overline{J}(D_1)$,

for all $X, Y \in \Gamma(D_1)$, $Z \in \Gamma(D_2)$ and $N \in \Gamma(ltr(TM))$.

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . It is easy to see that the distribution D_1 defines a totally geodesic foliation if and only if $\nabla_X Y \in \Gamma(D_1)$, for all $X, Y \in \Gamma(D_1)$. Since $\overline{\nabla}$ is a metric connection, using (2.7), (2.19) and (2.20), for any $X, Y \in \Gamma(D_1)$ and $Z \in \Gamma(D_2)$, we obtain $\overline{g}(\nabla_X Y, Z) = -\overline{g}(\overline{\nabla}_X \overline{J}Z, \overline{J}Y)$, which gives $\overline{g}(\nabla_X Y, Z) = \overline{g}(h^s(X, fZ) + \nabla_X^s FZ, \overline{J}Y)$. Now, from (2.7), (2.19) and (2.20), for all $X, Y \in \Gamma(D_1)$ and $N \in \Gamma(ltr(TM))$, we get $\overline{g}(\nabla_X Y, N) = -\overline{g}(\overline{J}Y, \overline{\nabla}_X \overline{J}N)$, which implies $\overline{g}(\nabla_X Y, N) = -\overline{g}(\overline{J}Y, D^s(X, \overline{J}N))$. Thus, the theorem is completed. □

Theorem 4.3. *Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \overline{M} . Then D_2 defines a totally geodesic foliation if and only if*

- (i) $\overline{g}(fY, A_{\overline{J}Z}X) = \overline{g}(FY, \nabla_X^s \overline{J}Z)$,
- (ii) $\overline{g}(fY, A_{\overline{J}N}X) = \overline{g}(FY, D^s(X, \overline{J}N))$,

for all $X, Y \in \Gamma(D_2)$, $Z \in \Gamma(D_1)$ and $N \in \Gamma(ltr(TM))$.

Proof. Let M be a screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then the distribution D_2 defines a totally geodesic foliation if and only if $\nabla_X Y \in \Gamma(D_2)$, for all $X, Y \in \Gamma(D_2)$. Since $\bar{\nabla}$ is a metric connection, using (2.7), (2.19) and (2.20), for any $X, Y \in \Gamma(D_2)$ and $Z \in \Gamma(D_1)$, we get $\bar{g}(\nabla_X Y, Z) = -\bar{g}(\bar{J}Y, \bar{\nabla}_X \bar{J}Z)$, which gives $\bar{g}(\nabla_X Y, Z) = \bar{g}(fY, A_{\bar{J}Z} X) - \bar{g}(FY, \nabla_X^s \bar{J}Z)$. In view of (2.7), (2.19) and (2.20), for any $X, Y \in \Gamma(D_2)$ and $N \in \Gamma(\text{ltr}(TM))$, we obtain $\bar{g}(\nabla_X Y, N) = -\bar{g}(\bar{J}Y, \bar{\nabla}_X \bar{J}N)$, which implies $\bar{g}(\nabla_X Y, N) = \bar{g}(fY, A_{\bar{J}N} X) - \bar{g}(FY, D^s(X, \bar{J}N))$. Thus, we obtain the required results. \square

Theorem 4.4. *Let M be a mixed geodesic screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then D_1 defines a totally geodesic foliation if and only if $\nabla_X^s FZ$ and $D^s(X, \bar{J}N)$ have no components in $\bar{J}(D_1)$, for all $X \in \Gamma(D_1)$, $Z \in \Gamma(D_2)$ and $N \in \Gamma(\text{ltr}(TM))$.*

Proof. Let M be a mixed geodesic screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then the distribution D_1 defines a totally geodesic foliation if and only if $\nabla_X Y \in \Gamma(D_1)$, for all $X, Y \in \Gamma(D_1)$. Since $\bar{\nabla}$ is a metric connection, using (2.7), (2.19) and (2.20), for any $X, Y \in \Gamma(D_1)$ and $Z \in \Gamma(D_2)$, we get $\bar{g}(\nabla_X Y, Z) = -\bar{g}(\bar{J}Y, \bar{\nabla}_X \bar{J}Z)$, which gives $\bar{g}(\nabla_X Y, Z) = -\bar{g}(\nabla_X^s FZ + h^s(X, fZ), \bar{J}Y)$. Now, from (2.7), (2.19) and (2.20), for any $X, Y \in \Gamma(D_1)$ and $N \in \Gamma(\text{ltr}(TM))$, we obtain $\bar{g}(\nabla_X Y, N) = -\bar{g}(\bar{J}Y, \bar{\nabla}_X \bar{J}N)$, which implies $\bar{g}(\nabla_X Y, N) = -\bar{g}(\bar{J}Y, D^s(X, \bar{J}N))$. This concludes the theorem. \square

Theorem 4.5. *Let M be a mixed geodesic screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then the induced connection ∇ on $S(TM)$ is a metric connection if and only if*

$$(i) \bar{g}(fW, A_{\bar{J}\xi}^* Z) = \bar{g}(FW, h^s(Z, \bar{J}\xi)),$$

$$(ii) h^s(X, \bar{J}\xi) \text{ has no component in } \bar{J}(D_1),$$

for all $X \in \Gamma(D_1)$, $Z, W \in \Gamma(D_2)$ and $\xi \in \Gamma(\text{Rad}TM)$.

Proof. Let M be a mixed geodesic screen pseudo-slant lightlike submanifold of an indefinite Kaehler manifold \bar{M} . Then $h^l(X, Z) = 0$, for all $X \in \Gamma(D_1)$ and $Z \in \Gamma(D_2)$. Since $\bar{\nabla}$ is a metric connection, using (2.7), (2.19) and (2.20), for any $X, Y \in \Gamma(D_1)$ and $\xi \in \Gamma(\text{Rad}TM)$, we obtain $\bar{g}(h^l(X, Y), \xi) = -g(\bar{J}Y, \bar{\nabla}_X \bar{J}\xi)$, which implies $\bar{g}(h^l(X, Y), \xi) = -g(\bar{J}Y, h^s(X, \bar{J}\xi))$. In view of (2.7), (2.19) and (2.20), for any $Z, W \in \Gamma(D_2)$ and $\xi \in \Gamma(\text{Rad}TM)$, we get $\bar{g}(h^l(Z, W), \xi) = -\bar{g}(fW, \nabla_Z \bar{J}\xi) - \bar{g}(FW, h^s(Z, \bar{J}\xi))$, thus $\bar{g}(h^l(Z, W), \xi) = \bar{g}(fW, A_{\bar{J}\xi}^* Z) - \bar{g}(FW, h^s(Z, \bar{J}\xi))$. This completes the proof.

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