ON A SPECIAL TYPE OF RIEMANNIAN MANIFOLD ADMITTING A TYPE OF SEMI-SYMMETRIC METRIC CONNECTION

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Abstract. The objective of the present paper is to study a type of semi-symmetric metric connection on a special Riemannian manifold.

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1. Introduction

H. A. Hayden [12] introducted semi-symmetric linear connection on a Riemannian manifold and this was further developed by K. Yano [16], M. Prvanović [13], M. C. Chaki and A. Konar [5], J. A. Schouten [14], U. C. De and S. C Biswas [9], U. C. De ([6], [7]), U. C. De and B. K. De [8], T. Q. Binh [2] and many others.

Let M be an n-dimensional Riemannian manifold of class C^{∞} endowed with the Riemannian metric g and D be the Levi-Civita connection on (M^n, g) .

A linear connection ∇ defined on (M^n, g) is said to be semi-symmetric [11] if its torsion tensor T is of the form

(1.1)
$$T(X,Y) = \pi(Y)X - \pi(X)Y$$

where π is a 1-form and ρ is a vector field given by

(1.2)
$$\pi(X) = g(X, \rho),$$

for all vector fields $X \in \chi(M^n)$, $\chi(M^n)$ is the set of all differentiable vector fields on M^n .

A semi-symmetric connection ∇ is called a semi-symmetric metric connection [12] if it further satisfies

(1.3)
$$\nabla g = 0.$$

A relation between the semi-symmetric metric connection ∇ and the Levi-Civita connection D on (M^n, g) has been obtained by K. Yano [16], which is given by

(1.4)
$$\nabla_X Y = D_X Y + \pi(Y) X - g(X, Y) \rho.$$

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We also have

(1.5)
$$(\nabla_X \pi) Y = (D_X \pi) Y - \pi(X) \pi(Y) + \pi(\rho) g(X, Y).$$

Further, a relation between the curvature tensor R of the semi-symmetric metric connection ∇ and the curvature tensor K of the Levi-Civita connection D is given by [16] (1.6)

$$R(X,Y)Z = K(X,Y)Z + \alpha(X,Z)Y - \alpha(Y,Z)X + g(X,Z)QY - g(Y,Z)QX,$$

where α is a tensor field of type (0,2) and Q is a tensor field of type (1,1) given by

(1.7)
$$\alpha(Y,Z) = g(QY,Z) = (D_Y\pi)(Z) - \pi(Y)\pi(Z) + \frac{1}{2}\pi(\rho)g(Y,Z).$$

From (1.6) and (1.7), we obtain

(1.8)

$$\tilde{R}(X,Y,Z,W) = \tilde{K}(X,Y,Z,W) - \alpha(Y,Z)g(X,W) + \alpha(X,Z)g(Y,W) - g(Y,Z)\alpha(X,W) + g(X,Z)\alpha(Y,W),$$

where

(1.9)
$$\tilde{R}(X,Y,Z,W) = g(R(X,Y)Z,W), \quad \tilde{K}(X,Y,Z,W) = g(K(X,Y)Z,W).$$

In 1967, R. N. Sen and M. C. Chaki [15] studied certain curvature restrictions on a certain kind of conformally flat space of class one and they obtained the following expression of the covariant derivative of the curvature tensor:

(1.10)
$$K_{ijk,l}^{h} = 2\lambda_{l}K_{ijk}^{h} + \lambda_{i}K_{ljk}^{h} + \lambda_{j}K_{ilk}^{h} + \lambda_{k}K_{ijl}^{h} + \lambda^{h}K_{lijk},$$

where K_{ijk}^h are the components of the curvature tensor K,

$$K_{ijkl} = g_{hl} K^h_{ijk},$$

 λ_i is a non-zero covariant vector and "," denotes covariant differentiation with respect to the metric tensor g_{ij} .

Later in 1987, M. C. Chaki [4] called a manifold whose curvature tensor satisfies (1.10), as a pseudo symmetric manifold. In the index-free notation this can be stated as follows: A non-flat Riemannian manifold $(M^n, g), n \ge 2$ is said to be a pseudo symmetric manifold [4] if its curvature tensor K satisfies the condition

$$(D_X K)(Y, Z)W = 2A(X)K(Y, Z)W + A(Y)K(X, Z)W + A(Z)K(Y, X)W + A(W)K(Y, Z)X + g(K(Y, Z)W, X)U,$$
(1.11)

where A is a non-zero 1-form and U is a vector field defined by

(1.12)
$$A(X) = g(X, U), \quad for \ all \ X,$$

and D denotes the operator of covariant differentiation with respect to the metric tensor g. The 1-form A is called the associated 1-form of the manifold. If A = 0, then the manifold reduces to a symmetric manifold in the sense of E. Cartan [3]. An *n*-dimensional pseudo symmetric manifold is denoted by $(PS)_n$.

In a recent paper, U. C. De and A. K. Gazi [10] introduced a type of non-flat Riemannian manifold (M^n, g) , $n \ge 2$ whose curvature tensor K of type (1,3) satisfies the condition

$$(D_X K)(Y, Z)W = [A(X) + B(X)]K(Y, Z)W + A(Y)K(X, Z)W + A(Z)K(Y, X)W + A(W)K(Y, Z)X + g(K(Y, Z)W, X)U,$$
(1.13)

$$g(K(Y, Z)W, X)U,$$

where A, U and D have the meaning already mentioned and B is a non-zero 1-form and V is a vector field defined by

$$(1.14) B(X) = g(X, V), for all X.$$

Such a manifold was called an almost pseudo-symmetric manifold and it was denoted by $(APS)_n$.

If B = A, then from the definitions it follows that $(APS)_n$ reduces to a $(PS)_n$. In the same paper, the authors constructed two non-trivial examples of $(APS)_n$.

A non-flat Riemannian manifold (M^n, g) , (n > 3), is called an almost pseudo-Ricci symmetric monifold [5] if its Ricci tensor \tilde{S} of type (0, 2) is not identically zero and satisfies the condition

(1.15)
$$(D_X \tilde{S})(Y, Z) = [A(X) + B(X)]\tilde{S}(Y, Z) + A(Y)\tilde{S}(X, Z) + A(Z)\tilde{S}(Y, X),$$

where A and B are two 1-forms and D denotes the operator of covariant differentiation with respect to the metric tensor g. In such a case A and B are called the associated 1-form and an n-dimensional manifold of this kind is denoted by $A(PRS)_n$.

In 1981, M. C. Chaki and A. Konar [5] studied a Riemannian manifold which admits a type of semi-symmetric metric connection whose curvature tensor Rvanishes and torsion tensor T is recurrent with respect to ∇ , that is,

(1.16)
$$R(X,Y)Z = 0,$$

and

(1.17)
$$(\nabla_X T)(Y,Z) = \pi(X)T(Y,Z),$$

where π is a non-zero 1-form.

In the present paper we prove the following:

Theorem 2.1. If an almost pseudo-symmetric manifold admits a semisymmetric metric connection ∇ whose curvature tensor R vanishes and torsion tensor T is recurrent, then

(i) the 1-form π is closed,

(ii) the vector field ρ is irrotational,

(iii) the integral curves of the vector field ρ are geodesic provided ρ is a unit vector field,

(iv) the manifold is an almost pseudo-Ricci symmetric manifold provided the 1-form A and 1-form π are equal.

Theorem 2.2. If an almost pseudo-symmetric manifold of dimension (n > 3) admits a semi-symmetric metric connection ∇ whose curvature tensor R vanishes, the torsion tensor T is recurrent and 1-form π and 1-form A are equal, then the vector field ρ is a proper concircular vector field.

Theorem 2.3. If an almost pseudo-symmetric manifold admits a semisymmetric metric connection ∇ whose curvature tensor R vanishes, the torsion tensor T is recurrent and 1-form π and 1-form A are equal, then the manifold is a subprojective manifold in the sense of Adati.

2. Proof of the main result

Theorem 2.1. If an almost pseudo-symmetric manifold admits a semi-symmetric metric connection ∇ whose curvature tensor R vanishes and torsion tensor T is recurrent, then

(i) the 1-form π is closed,

(ii) the vector field ρ is irrotational,

(iii) the integral curves of the vector field ρ are geodesic provided ρ is a unit vector field,

(iv) the manifold is an almost pseudo-Ricci symmetric manifold provided the 1-form A and 1-form π are equal.

Proof. From (1.1), we have

(2.1)
$$(C_1^1 T)(Y) = (n-1)\pi(Y),$$

where C_1^1 denotes the operator of contraction.

From (2.1), it follows that

(2.2)
$$(\nabla_X C_1^1 T)(Y) = (n-1)(\nabla_X \pi)(Y).$$

From (1.17), we obtain

(2.3)
$$(\nabla_X C_1^1 T)(Y) = \pi(X)(C_1^1 T)(Y).$$

From (2.1) and (2.3), we get

(2.4)
$$(\nabla_X C_1^1 T)(Y) = (n-1)\pi(X)\pi(Y).$$

From (2.2) and (2.4), we have

(2.5)
$$(\nabla_X \pi)(Y) = \pi(X)\pi(Y).$$

Combining (1.5) and (2.5), it follows that

(2.6)
$$(D_X \pi)(Y) = 2\pi(X)\pi(Y) - \pi(\rho)g(X,Y).$$

Therefore,

(2.7)
$$(D_X \pi)(Y) - (D_Y \pi)(X) = 0,$$

which implies that π is closed.

From (2.7), we obtain

(2.8)
$$g(Y, \nabla_X \rho) = g(X, \nabla_Y \rho),$$

which implies that the vector field corresponding to the 1-form π of the semi-symmetric metric connection is irrotational.

From (2.8) it follows that if ρ is a unit vector field, then

$$\nabla_{\rho}\rho = 0,$$

which implies that the integral curves of the vector field ρ are geodesic. Substituting (2.6) in (1.7), we get

(2.9)
$$\alpha(X,Y) = \pi(X)\pi(Y) - \frac{1}{2}\pi(\rho)g(X,Y).$$

So,

(2.10)
$$QX = \pi(X)\rho - \frac{1}{2}\pi(\rho)X.$$

Therefore,

(2.11)

$$R(X,Y)Z = K(X,Y)Z + \pi(X)[\pi(Z)Y - g(Y,Z)\rho] - \pi(Y)[\pi(Z)X - g(X,Z)\rho] + \pi(\rho)[g(Y,Z)X - g(X,Z)Y].$$

Since R = 0 by hypothesis, we have

(2.12)

$$K(X,Y)Z = \pi(X)[g(Y,Z)\rho) - \pi(Z)Y] + \pi(Y)[\pi(Z)X - g(X,Z)\rho] - \pi(\rho)[g(Y,Z)X - g(X,Z)Y].$$

Contracting X, it follows that

(2.13)
$$\tilde{S}(Y,Z) = -(n-2)\pi(\rho)g(Y,Z) + (n-2)\pi(Y)\pi(Z).$$

In (2.13) we put $Y = Z = e_i$, where $\{e_i\}, 1 \le i \le n$ is an orthonormal basis of the tangent space at any point of the manifold M^n and then summing over i, we obtain

(2.14)
$$\tilde{r} = -(n-1)(n-2)\pi(\rho).$$

Putting $Z = \rho$ in (2.13), we obtain

(2.15)
$$\tilde{S}(Y,\rho) = 0.$$

Again from (2.12), we get

$$(2.16) K(X,Y)\rho = 0.$$

Therefore,

$$K(X, Y, \rho, Z) = 0$$

That is,

(2.17)
$$\ddot{K}(X, Y, Z, \rho) = 0.$$

or,

(2.18)
$$\pi(K(X,Y)Z) = 0.$$

Suppose the 1-form A and 1-form π are equal, that is,

From (1.13), we obtain by contraction

(D_X
$$\tilde{S}$$
)(Y, Z) = [A(X) + B(X)] \tilde{S} (Y, Z) + A(Y) \tilde{S} (X, Z) +
(2.20) A(Z) \tilde{S} (Y, X) + A(K(X, Y)Z) + A(K(X, Z)Y).

From (2.18) and (2.19), it follows that A(K(X,Y)Z) = 0. Therefore (2.20) becomes

(2.21)
$$(D_X \tilde{S})(Y, Z) = [A(X) + B(X)]\tilde{S}(Y, Z) + A(Y)\tilde{S}(X, Z) + A(Z)\tilde{S}(Y, X).$$

Hence the manifold under consideration is an almost pseudo Ricci-symmetric manifold.

This completes the proof.

It is known that [16] if a Riemannian manifold (M^n, g) admits a semisymmetric metric connection ∇ whose curvature tensor vanishes, then the manifold is conformally flat.

Hence we can state the following corollary:

Corollary 2.1. If an almost pseudo-symmetric manifold of dimension (n > 3) admits a semi-symmetric metric connection ∇ whose curvature tensor R vanishes and torsion tensor T is recurrent, then the almost pseudo-symmetric manifold is conformally flat.

Theorem 2.2. If an almost pseudo-symmetric manifold of dimension (n > 3) admits a semi-symmetric metric connection ∇ whose curvature tensor R vanishes, the torsion tensor T is recurrent and 1-form π and 1-form A are equal, then the vector field ρ is a proper concircular vector field.

Proof. Let \hat{L} denotes the symmetric endomorphism of the tangent space at each point of almost pseudo-symmetric manifold corresponding to the Ricci tensor, that is,

for every vector fields X and Y.

Then from (2.13), we get

(2.23)
$$\tilde{L}(X) = -(n-2)\pi(\rho)X + (n-2)\pi(X)\rho.$$

Now,

(2.24)
$$(D_X \tilde{S})(Y, Z) = D_X \tilde{S}(Y, Z) - \tilde{S}(D_X Y, Z) - \tilde{S}(Y, D_X Z).$$

Putting $Z = \rho$ and combining relations (2.15) and (2.24), we get

$$(2.25) \quad (D_X\tilde{S})(Y,\rho) = D_X\tilde{S}(Y,\rho) - \tilde{S}(D_XY,\rho) - \tilde{S}(Y,D_X\rho) = -\tilde{S}(Y,D_X\rho).$$

Now putting $Z = \rho$ and $A = \pi$ in (2.21) and substituting (2.15), we obtain

(2.26)
$$(D_X \tilde{S})(Y, \rho) = \pi(\rho) \tilde{S}(Y, X).$$

Combining (2.25) and (2.26), it follows that

(2.27)
$$-\tilde{S}(Y, D_X \rho) = \pi(\rho)\tilde{S}(Y, X).$$

Combining relations (2.22) in (2.27), we get

(2.28)
$$-\tilde{L}(D_X\rho) = \pi(\rho)\tilde{L}(X).$$

Now from (2.23) and (2.28), we have

(2.29)
$$\pi(\rho)(D_X\rho) - \pi(D_X\rho)\rho = -[\pi(\rho)]^2 X + \pi(\rho)\pi(X)\rho.$$

Or,

(2.30)
$$D_X \rho = -\pi(\rho)X + \omega(X)\rho,$$

where

$$\omega(X) = \pi(X) + \frac{\pi(D_X \rho)}{\pi(\rho)},$$

from which it follows that π is closed. Hence ω is closed.

From (2.30), we conclude that ρ is a proper concircular vector field [15]. Hence the proof of Theorem is completed.

Theorem 2.3. If an almost pseudo-symmetric manifold admits a semi-symmetric metric connection ∇ whose curvature tensor R vanishes, the torsion tensor T is recurrent and 1-form π and 1-form A are equal, then the manifold is a subprojective manifold in the sense of Adati.

Proof. It is known that [16] if conformally flat manifold $(M^n, g)(n > 3)$ admits a proper concircular vector field, then the manifold is a subprojective manifold in the sense of Adati [1].

Since almost pseudo-symmetric manifold under consideration is conformally flat and admits a proper concircular vector field ρ .

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