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WEAK CONTRACTOR DIRECTIONS AND WEAK DIRECTIONAL CONTRACTIONS FOR A SET VALUED OPERATOR WITH A CLOSED RANGE

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Abstract

The weak contractor directions and weak directional contractions for nonlinear set - valued operators are defined and used for obtaining very general solvability theorem for a class of nonlinear set - valued operator equations. The given theorems improve and generalize some important results in [1-5].

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1. Introduction

The theory of Altman's contractor directions [1] and [2] provides extremely useful and important tools for obtaining solvability theorems of nonlinear operators with closed ranges. As a further development of the general theory of contractor directions, Altman [3] introduced two new concepts: weak contractor directions and weak directional contractions and obtained a general solvability theorem which generalizes some of the known in literature.

In [5], we introduced the concepts of weak contractor directions and weak directional contractions for nonlinear set-valued operators with closed ranges and obtained general solvability theorems for nonlinear set-valued operator equations which generalize the corresponding results in [1], [2] and [3].

In this paper, we shall define weak contractor directions and weak directional contractions for nonlinear set-valued operators and allow the contractor directions to have more general nonlinear majorant functions. Using the concepts, we obtain very general solvability theorem for nonlinear set-valued operator equations. As a consequence, a solvability theorem can be obtained for a class of nonlinear set-valued operators which are called weak directional contractions. Our theorems improve and generalize some important results in [1], [2], [3], [4] and [5].

2. Preliminary definitions and lemmas

Let Y be a Banach space. CB(Y) denotes the family of all the non-empty bounded closed subsets of Y. For $y \in Y$, $A \subset Y$ $D(y,A) = \inf\{d(y,a) : a \in A\}$ and $H(\cdot,\cdot)$ denote the Hausdorff metric on CB(Y) deduced by the norm in Y.

Let \mathbf{R}_+ be the set of all the positive real numbers. We denote by F the set of all the functions $q: \mathbf{R}_+ \to \mathbf{R}_+$ such that q(t) < t for each t > 0 and $\limsup_{s \to t^+} q(s) < t$ for every t > 0. Moreover, we denote by F^* the set of all the functions $f: \mathbf{R}_+ \to \mathbf{R}_+$ which are upper semicontinuous and such that f(t) < t for each t > 0. Obviously, the inclusion $F^* \subset F$ holds and the inverse is not true (see [6]).

Lemma 2.1. Let the function $q \in F$. Then, for any $a, b \in \mathbb{R}_+$ with $0 < a \le b < \infty$, the number

$$c = \inf\{1 - \frac{q(t)}{t}: a \le t \le b\}$$

satisfies that 0 < c < 1.

Proof. Clearly,

$$\sup\{\frac{q(t)}{t}:\ a\leq t\leq b\}>0.$$

Now, we shall show that

$$\sup\{\frac{q(t)}{t}:\ a\leq t\leq b\}<1$$

for any $a, b \in \mathbf{R}_+$, $0 < a \le b < \infty$. If it is not true, we may assume that there exist $a, b \in \mathbf{R}_+$ with $0 < a \le b < \infty$ such that

$$\sup\{\frac{q(t)}{t}:\ a\leq t\leq b\}=1.$$

Thus, we easily choose a decreasing sequence $\{t_n\} \subset [a,b]$ such that $q(t_n)/t_n > 1 - 1/(n+1)$, $n = 1, 2, \ldots$ Let $t_n \to t^*$. Then we have $\limsup_{n \to \infty} q(s) \geq t^*$.

This is in contradiction with $\limsup_{s \to 0} q(s) < t^*$. Hence, we have that

$$0<\sup\{\frac{q(t)}{t}:\ a\leq t\leq b\}<1$$

for all $a, b \in \mathbf{R}_+$ with $0 < a \le b < \infty$, and so

$$0 < c = \inf\{1 - \frac{q(t)}{t} : 0 < a \le t \le b\}$$

$$= 1 - \sup\{\frac{q(t)}{t} : 0 < a \le t \le b\} < 1.\square$$

In this paper, we assume throughout that the nonlinear majorant functions of weak contractor directions and weak directional contractions belong to F.

Definition 2.1. Let X be an abstract set and $P: X \to CB(Y)$ a setvalued operator of X into CB(Y). Given a function $q \in F$. We define sets $\Gamma_X^*(P) \subset Y$ of weak contractor directions for P at x, as follows. An element $y \in Y$ is a weak contractor direction, i. e., $y \in \Gamma_X^*(P)$ if there exists a positive $\varepsilon = \varepsilon(x,y) \leq 1$ and an element $\bar{x} \in X$ such that

(1)
$$H(P\bar{x}, Px + \varepsilon y) \le \varepsilon q(\max\{||y||, D(0, Px), D(0, Px)\}),$$

where 0 is the zero element of Banach space Y. If q(t) = kt, with 0 < k < 1, then $\Gamma_X^*(P)$ is a set of contractor directions for P at x denoted by $\Gamma_X(P)$, which is also a generalization of the corresponding concepts in [1] and [2].

Lemma 2.2. Let $A, B \in CB(Y)$ and $a \in A$. Then for each real number r > 1, there exists an element $b \in B$ such that

$$||a-b|| \leq rH(A,B).$$

Lemma 2.3. ([2]) Let α be an ordinal number of the first or second class and let $\{t_{\gamma}\}_{0 \leq \gamma \leq \alpha}$ be a well-ordered sequence of real numbers provided, for ordinal numbers β of the second kind (= limit number), we have

$$t_{\beta}=\lim_{\gamma\to\beta}t_{\gamma}.$$

Then, the following equality holds,

$$t_{\alpha} = t_0 + \sum_{0 < \gamma < \alpha} (t_{\gamma+1} - t_{\gamma}).$$

Lemma 2.4. ([1]) Let alpha be an ordinal number of the first or second class and let $\{x_{\gamma}\}_{0 \leq \gamma \leq \alpha}$ be a well-ordered sequence of elements of metric space X provided

$$x_{\beta} = \lim_{\gamma \to \beta} x_{\gamma}.$$

Then,

$$d(x_{\alpha}, x_0) \leq \sum_{0 \leq \gamma < \alpha} d(x_{\gamma+1}, x_{\gamma}).$$

Lemma 2.5. Let $A, B \in CB(Y)$ and $y \in Y$. Then,

$$H(A,B) \leq H(A,B-y) + ||y||.$$

Proof. This lemma easily follows rom the definition of a Hausdorff metric. \Box

Lemma 2.6. Let α be an ordinal number of the second class and let $\{A_{\gamma}\}_{0 \leq \gamma < \alpha}$ be a well ordered sequence of elements of CB(Y) such that

$$\lim_{\gamma \to \alpha} H(A_{\gamma}, A_{\alpha}) = 0$$

where $A_{\alpha} \in CB(Y)$. If $y_{\gamma} \in A_{\gamma}$, $\forall 0 \leq \gamma < \alpha$ and $\lim_{\gamma \to \alpha} y_{\gamma} = y_{\alpha}$, then $y_{\alpha} \in A_{\alpha}$.

Proof. For all $0 \le \gamma < \alpha$, we have that

$$D(y_{\alpha}, A_{\alpha}) \leq ||y_{\gamma} - y_{\alpha}|| + H(A_{\gamma}, A_{\alpha}).$$

Letting $\gamma \to \alpha$, we obtain $D(y_{\alpha}, A_{\alpha}) = 0$. Since A_{α} is closed, therefore $y_{\alpha} \in A_{\alpha}$. \square

3. Weak contractor directions

In order to prove a solvability theorem for nonlinear set-value operator P with weak contractor directions, we shall begin with the following:

Theorem 3.1. Let X be an abstract set, Y a Banach space, $P: X \to CB(Y)$ a nonlinear set-valued operator such that $P(X) = \bigcup_{x \in X} Px$ is closed in Y and $\{Px: x \in X\}$ is closed in (CB(Y), H). If $-Px \subset \Gamma_X^*(P)$ for all $x \in X$, that the set-valued operator equation

$$0 \in Px$$

has a solution in X.

Proof. We can assume that there exists a constant k > 0 such that for all $x \in X$

$$(2) D(0, Px) > k.$$

For, if this is not a case, then there exists a sequence $\{x_n\} \subset X$ such that $D(0,Px_n) \to 0$ as $n \to \infty$. It follows that there exists $y_n \in Px_n \subset P(X)$, $n=1,2,\ldots$, such that $y_n \to 0$ as $n \to \infty$. Since P(X) is closed in Y, we have $0 \in Px$. Hence, there exists an element $x^* \in X$ such that $0 \in Px^*$, i. e., the theorem holds. Now, we denote by Λ the set of all countable ordinal numbers. That is Λ is the set f all the ordinal numbers less than Ω , the first uncountable ordinal. Now we can construct well ordered sequences of nonnegative real numbers t_{γ} , $\gamma \in \Lambda$, elements $y(t_{\gamma}) \in Y$ and sets $P(t_{\gamma}) \in \{Px: x \in X\}$ as follows. Let $t_0 = 0$ and let x_0 be an arbitrary element of X, and put $P(t_0) = Px_0$. Let $y(t_0)$ be an arbitrary element of $P(t_0)$ Suppose that t_{γ} , $P(t_{\gamma})$ and $y(t_{\gamma}) \in P(t_{\gamma})$ have been constructed for all $\gamma < \alpha$, and satisfy:

(3) (i)
$$y(t_{\gamma}) \in P(t_{\gamma}),$$

(ii) for any ordinal numbers $\gamma < \alpha$, we have that

$$||y(t_{\gamma})|| \le \exp(-ct_{\gamma})||y(t_{0})||,$$

where

(5)
$$c = \inf\{1 - \frac{q(s)}{s} : k \le s \le ||y(t_0)||\},$$

with k determinated by (2). It follows from Lemma 2.1 that 0 < c < 1. (iii) for the first ordinal numbers $\gamma + 1 < \alpha$ the following inequalities are satisfied:

(6)
$$H(P(t_{\gamma+1}), P(t_{\gamma})) \le 2||y(t_0)||(t_{\gamma+1} - t_{\gamma}) \exp(-ct_{\gamma}),$$

(7)
$$||y(t_{\gamma+1}) - y(t_{\gamma})|| \le 2||y(t_0)||(t_{\gamma+1} - t_{\gamma})\exp(-ct_{\gamma}),$$

and

$$(8) 0 < t_{\gamma+1} - t_{\gamma} \le 1.$$

(iv) for the second ordinal numbers $\gamma < \alpha$ the following relations hold:

(9)
$$t_{\alpha} = \lim_{\gamma \to \alpha} t_{\gamma}, \ y(t_{\alpha}) = \lim_{\gamma \to \alpha} y(t_{\gamma}), \ P(t_{\alpha}) = \lim_{\gamma \to \alpha} P(t_{\gamma}).$$

Then, from (6), (8), (9), Lemma 2.3 and 2.4, it follows that for arbitrary $\lambda < \gamma < \alpha$ we have

$$(10) H(P(t_{\gamma}), P(t_{\lambda})) \leq \sum_{\lambda \leq \beta < \gamma} H(P(t_{\beta+1}), P(t_{\beta}))$$

$$\leq 2||y(t_0)|| \sum_{\lambda \leq \beta < \gamma} \exp(-ct_{\beta})(t_{\beta+1} - t_{\beta})$$

$$= 2||y(t_0)|| \sum_{\lambda \leq \beta < \gamma} \exp(c(t_{\beta+1} - t_{\beta})) nonumber$$

$$\exp(-ct_{\beta})(t_{\beta+1} - t_{\beta})$$

$$\leq 2||y(t_0)|| \exp(c) \sum_{\lambda \leq \beta < \gamma} \exp(-ct_{\beta+1})(t_{\beta+1} - t_{\beta})$$

$$\leq 2||y(t_0)|| \exp(c) \sum_{\lambda \leq \beta < \gamma} \int_{t_{\beta}}^{t_{\beta+1}} \exp(-ct) dt$$

$$= 2||y(t_0)|| \exp(c) \int_{t_{\lambda}}^{t_{\gamma}} \exp(-ct) dt.$$

Similarly, from (7), (8), (9), Lemma 2.3 and 2.4, we obtain that

(12)
$$||y(t_{\gamma}) - y(t_{\lambda})|| \le 2||y(t_0)|| \exp(c) \int_{t_{\lambda}}^{t_{\beta}} \exp(-ct)dt$$

Now, assume that α is the first kind ordinal number. If $0 \in P(t_{\alpha-1})$, then the theorem holds from $P(t_{\alpha-1}) \in \{Px : x \in X\}$. Thus we may assume that $0 \notin P(t_{\alpha-1})$, and let $x \in X$ such that $P(t_{\alpha-1}) = Px$. Then, by the hypotheses of the theorem, there exist a positive $\varepsilon \leq 1$ and an element $\bar{x} \in X$ such that for all $-y \in -Px \subset \Gamma_X^*(P)$, (1) holds. Put $\varepsilon_{\alpha-1} = \varepsilon \leq 1$, and

(13)
$$t_{\alpha} = t_{\alpha-1} + \varepsilon_{\alpha-1}, \ P(t_{\alpha}) = P\bar{x}.$$

Then we obtain by using (1) and $y(t_{\alpha-1}) \in P(t_{\alpha-1})$ that

(14)
$$H(P(t_{\alpha}), P(t_{\alpha-1}) - \varepsilon y(t_{\alpha-1})) \\ \leq \varepsilon q(\max\{\|y(t_{\alpha-1})\|, D(0, P(t_{\alpha-1})), D(0, P(t_{\alpha}))\}) \\ \leq \varepsilon q(\max\{\|y(t_{\alpha-1})\|, D(0, P(t_{\alpha}))\}).$$

Now, we shall show that $D(0, P(t_{\alpha})) \leq ||y(t_{\alpha-1})||$. If $D(0, P(t_{\alpha})) > ||y(t_{\alpha-1})||$, it follows from (14) and Lemma 2.5 that

$$\begin{array}{lll} D(0,P(t_{\alpha})) & \leq & H(P(t_{\alpha}),P(t_{\alpha-1})-y(t_{\alpha-1})) \\ & = & H(P(t_{\alpha}),P(t_{\alpha-1})-\varepsilon y(t_{\alpha-1}))-(1-\varepsilon)\|y(t_{\alpha-1})\| \\ & \leq & (1-\varepsilon)\|y(t_{\alpha-1})\| \\ & + & \varepsilon q(\max\{\|y(t_{\alpha-1})\|,D(0,P(t_{\alpha-1})),D(0,P(t_{\alpha}))\}) \\ & \leq & (1-\varepsilon)D(0,P(t_{\alpha}))+q(D(0,P(t_{\alpha}))) \\ & < & (1-\varepsilon)D(0,P(t_{\alpha}))+\varepsilon D(0,P(t_{\alpha}))=D(0,P(t_{\alpha})). \end{array}$$

This is contradiction. Hence, we have

(15)
$$D(0, P(t_{\alpha})) \le ||y(t_{\alpha-1})||.$$

From 0 < c < 1 and $0 < \varepsilon \le 1$ it follows that

$$\min\left\{\frac{1}{1-c}, 1 + \frac{\varepsilon c^2}{1-c}(\frac{1}{2} - \frac{\varepsilon c}{6})\right\} > 1.$$

Let the real number b satisfy

(16)
$$1 < b < \min\{\frac{1}{1-c}, 1 + \frac{\varepsilon c^2}{1-c}(\frac{1}{2} - \frac{\varepsilon c}{6})\}.$$

By Lemma 2.2 and (15), we obtain that there exists an element $y(t_{\alpha}) \in P(t_{\alpha})$ such that

(17)
$$||y(t_{\alpha}) - (1 - \varepsilon)y(t_{\alpha-1})||$$

$$\leq bH(P(t_{\alpha}), P(t_{\alpha-1}) - \varepsilon y(t_{\alpha-1}))$$

$$\leq b\varepsilon q(\max\{||y(t_{\alpha-1})||, D(0, P(t_{\alpha-1})), D(0, P(t_{\alpha}))\})$$

$$< b\varepsilon q(||y(t_{\alpha-1})||).$$

From (17), (16), (4) and (5), it follows that

(18)
$$||y(t_{\alpha})|| \leq (1-\varepsilon)||y(t_{\alpha-1})|| + b\varepsilon q(||y(t_{\alpha-1})||)$$

$$= (1-\varepsilon)||y(t_{\alpha-1})|| + b\varepsilon \frac{q(||y(t_{\alpha-1})||)}{||y(t_{\alpha-1})||} ||y(t_{\alpha-1})||$$

$$\leq (1-\varepsilon)||y(t_{\alpha-1})|| + b\varepsilon (1-c)||y(t_{\alpha-1})||$$

$$= (1-\varepsilon(1-b(1-c)))||y(t_{\alpha-1})||$$

$$\leq (1-c\varepsilon + \frac{c^2\varepsilon^2}{2} - \frac{c^3\varepsilon^3}{6})||y(t_{\alpha-1})||$$

$$< \exp(-c\varepsilon)||y(t_{\alpha-1})||$$

$$\leq \exp(-c\varepsilon)\exp(-ct_{\alpha-1})||y(t_0)||$$

$$= \exp(-ct_{\alpha})||y(t_0)||.$$

Since $y(t_{\alpha}) \in P(t_{\alpha})$, by virtue of Lemma 2.5, (14), (15), (5), (18) and (4), we get

$$\begin{split} H(P(t_{\alpha}), P(t_{\alpha-1})) & \leq & H(P(t_{\alpha}), P(t_{\alpha-1}) - \varepsilon y(t_{\alpha-1})) + \varepsilon ||y(t_{\alpha-1})|| \\ & \leq & \varepsilon ||y(t_{\alpha-1})|| + \varepsilon q(||y(t_{\alpha-1})||) \\ & \leq & (1 + (1-c))\varepsilon ||y(t_{\alpha-1})|| \\ & \leq & 2||y(t_0)||(t_{\alpha} - t_{\alpha-1}) \exp(-ct_{\alpha-1}). \end{split}$$

Furthermore, we obtain from (17), (16), (13) and (5)

$$||y(t_{\alpha}) - y(t_{\alpha-1})|| \leq \varepsilon ||y(t_{\alpha-1})|| + b\varepsilon q(||y(t_{\alpha-1})||) \leq \varepsilon (1 + b(1 - c))||y(t_{\alpha-1})|| \leq 2||y(t_0)||(t_{\alpha} - t_{\alpha-1})\exp(-ct_{\alpha-1}).$$

Thus, induction assumptions (3_{α}) , (4_{α}) , (6_{α}) - (8_{α}) are satisfied for t_{α} .

Now, suppose that α is an ordinal number of the second kind and put $t_{\alpha} = \lim_{\gamma \to \alpha} t_{\gamma}$. Let $\{\gamma_n\}$ be an increasing sequence converging to α . It

follows from (10) and (12) that $\{P(t_{\gamma_n})\}$ and $\{y(t_{\gamma_n})\}$ are Cauchy sequences, and so are $\{P(t_{\gamma})\}$ and $\{y(t_{\gamma})\}$. Let $P(t_{\alpha}) = \lim_{\gamma \to \alpha} P(t_{\gamma})$ and $y(t_{\alpha}) = \lim_{\gamma \to \alpha} y(t_{\gamma})$. It follows from Lemma 2.6 that $y(t_{\alpha}) \in P(t_{\alpha})$. Since $y(t_{\gamma})$ satisfy (4_{γ}) , therefore $y(t_{\alpha})$ satisfies (4_{α}) . This process will terminate if $t = +\infty$, where α is of the second kind. In the case (4_{α}) yields $y(t_{\alpha}) = 0$ and so $0 \in P(t_{\alpha}) \in \{Px : x \in X\}$. The proof of theorem is completed. \square

Corollary 3.1. Let X be an abstract set, Y a Banach space, $P: X \to Y$ a nonlinear point-valued operator such that P(X) is closed in Y. If $-Px \in \Gamma_X^*$ for each $x \in X$, then equation Px = 0 has a solution in X.

Remark 3.1. Note that our definitions of nonlinear majorant functions and the set of weak contractor directions are more general that those in [3], [5]. Thus Theorem 3.1 and Corollary 3.1 improve and generalize Theorem 1.1 of [3] and Theorem 3.1 and Corollary 3.1 of [5].

Theorem 3.2. Let X be an abstract set, Y a Banach space. The function $q \in F$ and $P: X \to CB(Y)$ is such that $P(X) = \bigcup_{x \in X} Px$ is closed in Y and $Px: x \in X$ is closed in Px in Px is closed in Px is closed in Px in Px is closed in Px in Px is closed in Px in Px in Px in Px in Px is closed in Px in Px

(19)
$$H(P\bar{x}, Px + \varepsilon y) \le \varepsilon q(\max\{||y||, D(u, Px), D(u, P\bar{x})\})$$

for any $u \in Y$, then the nonlinear set-valued operator equation $u \in Px$ has a solution in X and P(X) = Y.

Proof. For an arbitrary given $u \in Y$, put $\bar{P}x = Px - u$. By (19)

$$H(\bar{P}\bar{x}, \bar{P}x + \varepsilon y) \le \varepsilon q(\max\{||y||, D(u, \bar{P}x), D(u, \bar{P}\bar{x})\}).$$

Since $\Gamma_X^*(\bar{P}) = \Gamma_X^*(P) = Y$, for all $x \in X$, it follows that $-Px \in \Gamma_X^*(\bar{P})$ for all $x \in X$. Clearly, $\bar{P}x = Px - u$ is closed in Y and $\{\bar{P}x : x \in X\} = \{Px - u : x \in X\}$ also is closed in (CB(Y), H). Hence, by Theorem 3.1, equation $0 \in \bar{P}x$ has a solution in X, and consequently, equation u = Px has a solution in X. This completes the proof. \Box

Remark 3.2. Theorem 3.2 of [1] (see also Theorem 1.2 of [2]), Theorem 1.2 of [3] and Therem 3.2 of [5] are very special cases of Theorem 3.2.

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4. Weak directional set-valued contractions

Definition 4.1. Let X be a Banach space and a function $q \in F$. A mapping $T: D(T) \to CB(Y)$ is called a weak directional set-valued contraction if for each $x \in D(T)$ and $y \in X$ there exits a positive $\varepsilon = \varepsilon(x,y) \le 1$ such that $x + \varepsilon y \in D(T)$ and

(20)
$$H(T(x+\varepsilon y),Tx) \leq \varepsilon q(\max\{||y||,D(y,x-Tx),D(y,x+\varepsilon y-T(x+\varepsilon y))\}).$$

The following global solvability theorem holds for weak directional setvalued contractions.

Theorem 4.1. Let $T:D(T) \to CB(Y)$ be a weak directional set-valued contraction. If P = I - T (I is identity mapping) is such that the set $P(D(T)) = \bigcup_{x \in D(T)} Px$ is closed in X and the set $\{Px : x \in D(T)\}$ is closed in (CB(X), H), then for each $y \in X$, set-valued operator equation $y \in Px$ has a solution in D(T). Furthermore, we have X = P(D(T)).

Proof. Since P = I - T, by (20), we have

$$H(P(x+\varepsilon y), Px + \varepsilon y) = H(x + \varepsilon y - T(x + \varepsilon y), x - Tx + \varepsilon y)$$

$$= H(T(x + \varepsilon y), Tx)$$

$$< \varepsilon q(\max\{||y||, D(y, Px), D(y, P(x + \varepsilon y))\}).$$

It is easy to check that the hypotheses of Theorem 3.2 are satisfied and the proof is completed. \Box

Remark 4.1. Theorem 4.1 is the improvement and generalization of Theorem 2.1 of [3].

Corollary 4.1. Let X and q satisfy the hypotheses in Theorem 4.1. Suppose that $T: D(T) \subset X \to CB(X)$ such that for each $x \in D(X)$ and $y \in X$, there exist a positive $\varepsilon = \varepsilon(x,y) \le 1$ such satisfying: $x + \varepsilon y \in D(T)$ and

(21)
$$H(T(x+\varepsilon y),Tx) \le \varepsilon q(||y||).$$

If P = I - T is such that P(D(T)) is closed in X and $\{Px : x \in X\}$ is closed in (CB(X), H). Then for $y \in X$, equation $y \in Px$ has a solution in D(T) and so P(D(T)) = X. Specially, T has a fixed point in D(T).

Remark 4.2. Letting $\varepsilon(x,y) = 1$ or all $x \in D(T)$ and $y \in X$, Corollary 4.1 is the set-valued generalization of the theorem of Boyd and Wong [4].

5. Weak directional set-valued contractions in a narrow sense

Definition 5.1. Let W be a convex subset of a Banach space X and a function $q \in F$. A mapping $T: W \subset X \to CB(W)$ is called a weak directional set-valued contraction in a narrow sense if for each $x \in W$ there exits a positive $\varepsilon = \varepsilon(x) \le 1$ such that for each $y \in Tx - x$

$$(22)H(T(x+\varepsilon y),Tx)\leq \varepsilon q(\max\{\|y\|,D(x,Tx),D(x+\varepsilon y,T(x+\varepsilon y))\}).$$

Theorem 5.1. Let $T: W \subset X \to CB(W)$ be a weak directional set-valued contraction in a narrow sense. If P = I - T is such that $P(W) = \bigcup_{x \in W} Px$ is closed in X and $\{Px: x \in W\}$ is closed in (CB(X), H), then T has a fixed point in W.

Proof. By P = I - T and (22), for each $x \in W$ and $y \in Tx - x$, we have

$$\begin{array}{lll} H(P(x+\varepsilon y),Px+\varepsilon y) & = & H(x+\varepsilon y-T(x+\varepsilon y),x-Tx+\varepsilon y) \\ & = & H(T(x+\varepsilon y),Tx) \\ & \leq & \varepsilon q(\max\{\|y\|,D(0,Px),D(0,T(x+\varepsilon y))\}). \end{array}$$

Since $\bar{x} = x + \varepsilon y \in x + \varepsilon (Tx - x) = (1 - \varepsilon)x + \varepsilon Tx \subset W$ and $Tx - x \subset \Gamma_X^*(P)$, i. e. $-Px = Tx - x \subset \Gamma_X^*(P)$ for all $x \in W$. From Theorem 3.1 it follows that there exists an element $x^* \in W$ such that $0 \in Px^* = x^* - Tx^*$ and hence $x^* \in Tx^*$. This completes the proof. \Box

Corollary 5.1. Let W be a convex subset of a Banach space X and a function $q \in F$. Suppose that $T: W \subset X \to W$ satisfies that for each $x \in W$, there exists a positive $\varepsilon = \varepsilon(x) \le 1$ such that for each y = Tx - x,

$$||T(x+\varepsilon y)-Tx|| \le \varepsilon q(\max\{||y||,||x-Tx||,||x+\varepsilon y-T(x+\varepsilon y)||\}).$$

If the range (I-T)(W) is closed in X, then T has a fixed point in W.

Remark 5.1. Theorem 5.1 and Corollary 5.1 are generalizations of Theorem 3.4 of [3].

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REZIME

SLABE DIREKCIONE KONTRAKCIJE I SLABI PRAVCI KONTRAKCIJE ZA SKUPOVNE OPERATORE

Slabi pravci kontrakcije i slabe direkcione kontrakcije za nelinearne skupovne operatore su definisani i korišćeni za dobijanje vrlo opštih teorema o rešenju za jednu klasu nelinearnih skupovnih operatorskih jednačina. Date teoreme poboljšavaju i uopštavaju neke vrlo važne rezultate u [1-5].

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