

ON COINCIDENCE POINTS IN METRIC AND
PROBABILISTIC METRIC SPACES WITH A CONVEX STRUCTURE

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ABSTRACT

The notion of the convexity in metric spaces is introduced by Takahashi in [14] and some fixed point theorems in convex metric spaces are proved in [8],[9],[14].

In this paper we shall prove some theorems on the existence of a coincidence point in metric and probabilistic metric spaces with a convex structure.

1. INTRODUCTION

In [2] B.Fisher proved the following generalization of the contraction principle.

THEOREM A *Let (X,d) be a complete metric space and S,T continuous mappings from X into X . Mappings S and T have a common fixed point if and only if there exists a mapping $A:X \rightarrow SX \cap TX$ which commutes with S and T and :*

$$d(Ax,Ay) \leq q d(Sx,Ty) \quad , \quad \text{for every } x,y \in X$$

where $q \in [0,1)$.

In this paper we investigate the existence of a common fixed point for mappings A and S if :

$$d(Ax,Ay) \leq d(Sx,Sy) \quad , \text{for every } x,y \in X$$

where (X,d) is a convex metric space in the sense of Takahashi.

The obtained results are closely related to the well known result of Göhde , if $S = Id$ [3].

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THEOREM B *Let M be a star-shaped subset of a Banach space and $F:M \rightarrow M$ be a nonexpansive mapping with a compact attractor. Then F has a fixed point .*

We investigate also the problem of the existence of a coincidence point for A, S and T where A is a multivalued mapping and :

$H(Ax, Ay) \leq d(Sx, Ty)$, for every $x, y \in X$ and A is (α, S) or (α, T) densifying.

In part 4. of this paper we prove a common fixed point theorem in probabilistic metric spaces with a convex structure.

2. NOTATIONS AND DEFINITIONS

In [14] Takahashi introduced the notion of the convexity in metric spaces .

DEFINITION 1. *Let (X, d) be a metric space . A mapping $W: X \times X \times [0, 1] \rightarrow X$ is said to be a convex structure if for every $(x, y, \lambda) \in X \times X \times [0, 1]$:*

$$d(u, W(x, y, \lambda)) \leq \lambda d(u, x) + (1-\lambda)d(u, y) \text{ , for every } u \in X .$$

A metric space with a convex structure will be called a convex metric space .

There are many convex metric spaces which cannot be imbedded in any Banach space [14] .

DEFINITION 2. *A convex metric space X satisfies condition II if for all $(x, y, z, \lambda) \in X \times X \times X \times [0, 1]$:*

$$d(W(x, z, \lambda), W(y, z, \lambda)) \leq \lambda d(x, y) \text{ ([9])} .$$

DEFINITION 3. *Let X be a convex metric space, $x_0 \in X$ and $S: X \rightarrow X$. The mapping S is said to be (W, x_0) -convex if for every $z \in X$ and every $\lambda \in (0, 1)$:*

$$W(Sz, x_0, \lambda) = S(W(z, x_0, \lambda)) .$$

REMARK If X is a Banach space and $W(x, y, \lambda) = \lambda x + (1-\lambda)y$ for every $(x, y, \lambda) \in X \times X \times [0, 1]$ then every homogeneous mapping $S: X \rightarrow X$ is $(W, 0)$ -convex.

By α we shall denote the Kuratowski measure of noncompactness . If (X, d) is a metric space then $H(A, B)$ is the Hausdorff metric , where $A, B \in CB(X)$ (the family of all bounded and closed subsets of X). By 2^X we shall denote the family of all nonempty subsets of X and if $T: X \rightarrow 2^X$, we say that T is a closed mapping if from $y_n \in T x_n$ ($x_n \in X, n \in \mathbb{N}$) and $\lim_{n \rightarrow \infty} x_n = x$, $\lim_{n \rightarrow \infty} y_n = y$ it follows

that $y \in Tx$. A set $M \subset X$ is an attractor for a mapping $F: X \rightarrow X$ if for every $x \in X$: $\bigcup_{n=1}^{\infty} F^n(x) \cap M \neq \emptyset$.

DEFINITION 4. Let (X, d) be a metric space, $B(X)$ the family of all bounded subsets of X , $K \subseteq X$ and A and S mappings from X into 2^X . If for every $M \subseteq K$ such that $S(M), A(M) \in B(X)$ the implication : $\alpha(S(M)) < \alpha(A(M)) \Rightarrow \bar{M}$ is compact holds, A is said to be (α, S) -densifying on K .

3. COMMON FIXED POINT THEOREMS IN METRIC SPACES

THEOREM 1. Let (X, d) be a convex, complete metric space which satisfies condition II, $S, A: X \rightarrow X$ continuous, commutative mappings such that $AX \subseteq SX$, AX a bounded set, $x_0 \in X$, $S(W, x_0)$ -convex and $d(Ax, Ay) < d(Sx, Sy)$, for every $x, y \in X$.

If M is a nonempty subset of X such that SM is an attractor for the mapping A and A is (α, S) -densifying on M then there exists $x \in X$ such that $Ax = Sx$.

P r o o f : Let $\{k_n\}_{n \in \mathbb{N}}$ be a sequence of real numbers from the interval $(0, 1)$ such that $\lim_{n \rightarrow \infty} k_n = 1$ and for every $n \in \mathbb{N}$ let $A_n x = W(Ax, x_0, k_n)$, for every $x \in X$. We shall prove that all the conditions of the Theorem from [2] are satisfied for A_n ($n \in \mathbb{N}$), S and $Tx = Sx$, for every $x \in X$. Thus, let us show that for every $n \in \mathbb{N}$, $A_n X \subseteq SX$ and $A_n Sx = SA_n x$, for every $x \in X$ and for every $x, y \in X$:

$$d(A_n x, A_n y) < k_n d(Sx, Sy) .$$

For every $x, y \in X$ and every $n \in \mathbb{N}$ we obtain from condition II that :

$$d(A_n x, A_n y) = d(W(Ax, x_0, k_n), W(Ay, x_0, k_n)) < k_n d(Ax, Ay) < k_n d(Sx, Sy) .$$

Since $AX \subseteq SX$ for every $x \in X$ there exists $z_x \in X$ such that

$Ax = Sz_x$ and so from (W, x_0) -convexity of the mapping S we obtain that:

$$A_n x = W(Ax, x_0, k_n) = W(Sz_x, x_0, k_n) = S(W(z_x, x_0, k_n)) \in SX$$

for every $n \in \mathbb{N}$. Furthermore, A_n and S commute for every $n \in \mathbb{N}$ since:

$$A_n Sx = W(ASx, x_0, k_n) = W(SAx, x_0, k_n) = S(W(Ax, x_0, k_n)) = SA_n x$$

for every $x \in X$. From the Theorem proved in [2] it follows that for every $n \in \mathbb{N}$ there exists $x_n \in X$ such that $x_n = A_n x_n = Sx_n$.

Since the set AX is bounded there exists $D \in \mathbb{R}$ such that $D = \sup_{x \in X} d(Ax, x_0)$. Then for every $n \in \mathbb{N}$ we have that:

$$\begin{aligned} d(x_n, Ax_n) &= d(W(Ax_n, x_0, k_n), Ax_n) < k_n d(Ax_n, Ax_n) + \\ &+ (1-k_n) d(Ax_n, x_0) < D(1-k_n). \end{aligned}$$

Since SM is an attractor for the mapping A it follows that:

$$(1) \quad \overline{\bigcup_{m=1}^{\infty} A^m(x_n)} \cap SM \neq \emptyset, \quad \text{for every } n \in \mathbb{N}.$$

From (1) we conclude that for every $n \in \mathbb{N}$ there exists $y_n \in M$ such that:

$$(2) \quad Sy_n \in \overline{\bigcup_{m=1}^{\infty} A^m(x_n)}.$$

Relation (2) implies that for every $n \in \mathbb{N}$ there exists $m_n \in \mathbb{N}$ such that:

$$(3) \quad d(Sy_n, A^{m_n} x_n) < 1 - k_n.$$

Then we have:

$$\begin{aligned} d(Sy_n, Ay_n) &< d(Sy_n, A^{m_n} x_n) + d(A^{m_n} x_n, A^{m_n+1} x_n) + \\ &+ d(A^{m_n+1} x_n, Ay_n) < (1-k_n) + D(1-k_n) + d(A^{m_n} x_n, Sy_n) < (1-k_n)(D+2) \end{aligned}$$

since:

$$(4) \quad d(A^k x_n, A^{k+1} x_n) < d(x_n, Ax_n), \quad \text{for every } n \in \mathbb{N} \text{ and } k \in \mathbb{N}.$$

The relation (4) can be proved by induction. For $k=1$ and every $n \in \mathbb{N}$ we have:

$$d(Ax_n, A^2 x_n) < d(Sx_n, Ax_n) = d(x_n, Ax_n)$$

and let us suppose that for some $k \in \mathbb{N}$ and every $n \in \mathbb{N}$:

$$d(A^k x_n, A^{k+1} x_n) < d(x_n, Ax_n).$$

Then we have:

$$\begin{aligned} d(A^{k+1}x_n, A^{k+2}x_n) &< d(S(A^kx_n), S(A^{k+1}x_n)) = \\ &= d(A^k(Sx_n), A^{k+1}(Sx_n)) = d(A^kx_n, A^{k+1}x_n) < d(x_n, Ax_n) . \end{aligned}$$

From $\lim_{n \rightarrow \infty} k_n = 1$ we obtain that $\lim_{n \rightarrow \infty} d(Sy_n, Ay_n) = 0$. Let $C = \{y_n \mid n \in \mathbb{N}\}$. Then for every $\varepsilon > 0$ there exists $n_0(\varepsilon) \in \mathbb{N}$ such that:

$$S(\{y_n \mid n > n_0(\varepsilon)\}) \subseteq \bigcup_{y \in AC} L(y, \varepsilon)$$

and so [9]:

$$\alpha(SC) = \alpha(S(\{y_n \mid n > n_0(\varepsilon)\})) < \alpha(AC) + 2\varepsilon .$$

Since ε is an arbitrary positive number we have that $\alpha(SC) < \alpha(AC)$. The mapping A is (α, S) -densifying and so it follows that the set C is relatively compact. Suppose that $\lim_{k \rightarrow \infty} y_{n_k} = y$. Since A and S are continuous from $\lim_{n \rightarrow \infty} d(Sy_n, Ay_n) = 0$ we obtain that $Sy = Ay$.

In [4] we proved the following coincidence theorem.

THEOREM C Let (X, d) be a complete metric space, S and T continuous mappings from X into X , $A: X \rightarrow CB(SX \cap TX)$ a closed mapping such that the following conditions are satisfied:

1. $H(Ax, Ay) < q d(Sx, Ty)$, for every $x, y \in X$
where $q \in [0, 1)$.
2. For every $x \in X, ATx = \bigcup_{u \in Ax} Tu$ and $ASx = \bigcup_{v \in Ax} Sv$.

Then there exists a sequence $\{x_n\}_{n \in \mathbb{N}}$ from X such that :

- a) $Sx_{2n+1} \in Ax_{2n}$, $Tx_{2n} \in Ax_{2n-1}$,
for every $n \in \mathbb{N}$ and $z = \lim_{n \rightarrow \infty} Tx_{2n} = \lim_{n \rightarrow \infty} Sx_{2n+1}$.
- b) $Tz \in Az$, $Sz \in Az$.

THEOREM 2. Let (X, d) be a complete convex metric space, $x_0 \in X$, S and T continuous (W, x_0) -convex mappings from X into X , $A: X \rightarrow 2_C^{SX \cap TX}$ (the family of nonempty, closed subsets of $SX \cap TX$) a closed mapping such that \overline{AX} is compact and W satisfy condition II. Further, let

$$\bigcup_{z \in Ax} Sz = ASx, \quad \bigcup_{v \in Ax} Tv = ATx, \quad \text{for every } x \in X.$$

If for every $x, y \in X$:

$$H(Ax, Ay) < d(Sx, Ty)$$

and A is (α, S) or (α, T) densifying on X then there exists $z \in X$ such that $Sz \in Az$ and $Tz \in Az$.

P r o o f. Let us prove that all the conditions of the Theorem C are satisfied for A_n, S and T , for every $n \in \mathbb{N}$, where $\lim_{n \rightarrow \infty} k_n = 1$ ($k_n \in (0, 1)$, $n \in \mathbb{N}$) and $A_n x = \bigcup_{z \in Ax} W(z, x_0, k_n)$ ($x \in X$).

We have that:

$$\begin{aligned} A_n Sx &= \bigcup_{z \in ASx} W(z, x_0, k_n) = \bigcup_{z \in SAx} W(z, x_0, k_n) = \\ &= \{W(Sy, x_0, k_n) \mid y \in Ax\} = \{S(W(y, x_0, k_n)) \mid y \in Ax\} = SA_n x \end{aligned}$$

and similarly $A_n Tx = TA_n x$ ($n \in \mathbb{N}$) for every $x \in X$.

Further, if $u \in A_n x$ then there exists $y \in Ax$ such that $u = W(y, x_0, k_n)$. Since $Ax \subseteq SX \cap TX$ it follows that there exists $z_y \in X$ so that $y = Sz_y$ which implies that:

$$u = W(y, x_0, k_n) = W(Sz_y, x_0, k_n) = S(W(z_y, x_0, k_n)).$$

Thus we have that $A_m X \subseteq SX \cap TX$, for every $m \in \mathbb{N}$. Since Ax is closed and \overline{AX} is compact, from the continuity of the mapping W in the first variable we have that $A_n x$ is compact (for every $n \in \mathbb{N}$) and so $A_n x \in CB(SX \cap TX)$. Let us prove that the mapping A_n is closed for every $n \in \mathbb{N}$. Let $y_n \in A_m x_n$ ($n \in \mathbb{N}$), $\lim_{n \rightarrow \infty} x_n = x$ and

$\lim_{n \rightarrow \infty} y_n = y$. From $A_m x_n = \bigcup_{z \in Ax_n} W(z, x_0, k_m)$ it follows that $y_n = W(z_n, x_0, k_m)$, where $z_n \in Ax_n$, $n \in \mathbb{N}$. Since \overline{AX} is compact it follows

that there exists a convergent subsequence $\{z_{n_k}\}_{k \in \mathbb{N}}$ and let

$\lim_{k \rightarrow \infty} z_{n_k} = z$. From the closedness of the mapping A we obtain that

$y = W(z, x_0, k_m)$, where $z \in Ax$. Hence $y \in A_m x$ which means that the

mapping A_m is closed. From :

$$H(A_m x, A_m y) = H\left(\bigcup_{z \in Ax} W(z, x_0, k_m), \bigcup_{z \in Ay} W(z, x_0, k_m)\right)$$

$$< k_m H(Ax, Ay) < k_m d(Sx, Ty), \quad \text{for every } x, y \in X$$

it follows that all the conditions of the Theorem C are satisfied. and so, for every $m \in \mathbb{N}$ there exists $x_m \in X$ such that $Sx_m \in A_m x_m$ and $Tx_m \in A_m x_m$. Let $Sx_m = y_m = W(u_m, x_0, k_m)$, $Tx_m = z_m = W(v_m, x_0, k_m)$, where $u_m \in Ax_m$ and $v_m \in Ax_m$.

Then:

$$d(Sx_m, u_m) = d(W(u_m, x_0, k_m), u_m) < (1-k_m)d(u_m, x_0)$$

and since $\{u_m | m \in \mathbb{N}\} \subseteq AX$ we obtain that $\lim_{m \rightarrow \infty} d(Sx_m, u_m) = 0$.

Similarly we can prove that $\lim_{m \rightarrow \infty} d(Tx_m, v_m) = 0$ and let $L = \{x_n | n \in \mathbb{N}\}$. Suppose that A is (α, S) -densifying. From $\lim_{m \rightarrow \infty} d(Sx_m, u_m) = 0$ it follows that:

$$(5) \quad \alpha(SL) < \alpha(\{u_m | m \in \mathbb{N}\})$$

and since $\{u_m | m \in \mathbb{N}\} \subseteq AL$, using (5) we conclude that:

$$(6) \quad \alpha(SL) < \alpha(AL) .$$

The relation (6) implies that the set $\{x_n | n \in \mathbb{N}\}$ is relatively compact, since the mapping A is (α, S) -densifying. Suppose that $\lim_{k \rightarrow \infty} x_{n_k} = x$. Then from the continuity of the mapping S we obtain that $\lim_{k \rightarrow \infty} u_{n_k} = Sx$. Since $u_{n_k} \in Ax_{n_k}$ ($k \in \mathbb{N}$) and the mapping A is closed we conclude that $Sx \in Ax$. Similarly, from $\lim_{k \rightarrow \infty} v_{n_k} = Tx$ and $v_{n_k} \in Ax_{n_k}$ ($k \in \mathbb{N}$) it follows that $Tx \in Ax$. (*)

3. A COMMON FIXED POINT THEOREM IN PROBABILISTIC METRIC SPACES WITH A CONVEX STRUCTURE

First, let us give some notations and definitions from the theory of probabilistic metric spaces. Some fixed point theorems in probabilistic metric spaces are proved in [5], [6] and [12].

A triplet (S, F, t) is a Menger space if and only if S is a nonempty set, $F: S \times S \rightarrow \Delta$, where Δ denotes the set of all distribution functions F , and t is a T -norm [11] so that the following conditions are satisfied ($F(p, q) = F_{p, q}$, for every $p, q \in S$):

(*) From the proof it is obvious that in the case of a normed space X it is enough to suppose that for every $x \in X$, Ax is a closed and bounded subset of $SX \cap TX$, instead of the compactness of \overline{Ax} .

1. $F_{p,q}(x) = 1$, for every $x \in \mathbb{R}^+$ if and only if $p = q$.
2. $F_{p,q}(0) = 0$, for every $p, q \in S$.
3. $F_{p,q} = F_{q,p}$, for every $p, q \in S$.
4. $F_{p,r}(u+v) \geq t(F_{p,q}(u), F_{q,r}(v))$, for every $p, q, r \in S$ and every $u, v \in \mathbb{R}^+$.

The (ε, λ) -topology is introduced by the (ε, λ) -neighbourhoods of $v \in S$:

$$U_v(\varepsilon, \lambda) = \{u \mid u \in S, F_{u,v}(\varepsilon) > 1 - \lambda\}, \quad \varepsilon > 0, \quad \lambda \in (0, 1).$$

DEFINITION 5. Let (S, F, t) be a Menger space. A mapping $W: S \times S \times [0, 1] \rightarrow S$ is said to be a convex structure if for every $(u, x, y, \lambda) \in S \times S \times S \times (0, 1)$:

$$F_{u, W(x, y, \lambda)}(2\varepsilon) \geq t(F_{u, x}(\frac{\varepsilon}{\lambda}), F_{u, y}(\frac{\varepsilon}{1-\lambda})), \quad \text{for every } \varepsilon \in \mathbb{R}^+ \text{ and } W(x, y, 0) = y, W(x, y, 1) = x.$$

It is well known that a Menger space is a probabilistic metric space. Every random normed space [13] is a probabilistic metric space with a convex structure $W(x, y, \lambda) = \lambda x + (1-\lambda)y$ since for every $\varepsilon > 0$:

$$\begin{aligned} F_{u, W(x, y, \lambda)}(2\varepsilon) &= F_{u - \lambda x - (1-\lambda)y}(2\varepsilon) = F_{\lambda u + (1-\lambda)u - \lambda x - (1-\lambda)y}(2\varepsilon) = \\ &= F_{\lambda(u-x) + (1-\lambda)(u-y)}(2\varepsilon) \geq t(F_{\lambda(u-x)}(\varepsilon), F_{(1-\lambda)(u-y)}(\varepsilon)) = \\ &= t(F_{u-x}(\frac{\varepsilon}{\lambda}), F_{u-y}(\frac{\varepsilon}{1-\lambda})), \quad \text{for every } \lambda \in (0, 1). \end{aligned}$$

The following definition is a generalization of Definition 2.

DEFINITION 6. A probabilistic metric space (S, F, t) with a convex structure W satisfies condition PII if for all $(x, y, z, \lambda) \in S \times S \times S \times (0, 1)$:

$$F_{W(x, z, \lambda), W(y, z, \lambda)}(\lambda\varepsilon) \geq F_{x, y}(\varepsilon), \quad \text{for every } \varepsilon \in \mathbb{R}^+.$$

It is easy to see that every random normed space satisfies condition PII.

If (S, F, t) is a Menger space with a convex structure W and $x_0 \in S$, we say that $T: S \rightarrow S$ is (W, x_0) -convex if, as in Definition 3, $W(Tz, x_0, \lambda) = T(W(z, x_0, \lambda))$ for every $\lambda \in (0, 1)$ and every $z \in S$. In the next Theorem we suppose that condition PII is satisfied.

THEOREM 3. Let (X, F, t) be a probabilistic metric space with a convex structure W and continuous T norm t , A and S continuous, commutative mappings from X into X such that AX is probabilistic bounded subset of SX , $x_0 \in X$ and $S(W, x_0)$ -convex so that:

$$F_{Ax, Ay}(\epsilon) > F_{Sx, Sy}(\epsilon) \quad , \text{ for every } x, y \in X \quad \text{ and every } \epsilon \in \mathbb{R}^+$$

If there exists a compact set $M \subseteq X$ such that SM is an attractor for A , then there exists $z \in X$ such that $Az = Sz$.

P r o o f. Let $k_n \in (0, 1)$ ($n \in \mathbb{N}$) , $\lim_{n \rightarrow \infty} k_n = 1$ and for every $x \in X$, $A_n x = W(Ax, x_0, k_n)$ ($n \in \mathbb{N}$). Similarly as in Theorem 1 it follows that all the conditions of Theorem 2 from [5] are satisfied for A_n, S and $I_X = T$ and so there exists $x_n \in X$ such that $x_n = A_n x_n = Sx_n$, for every $n \in \mathbb{N}$. Further, we have for every $n \in \mathbb{N}$ and every $\epsilon > 0$ that:

$$\begin{aligned} F_{x_n, Ax_n}(\epsilon) &= F_{A_n x_n, Ax_n}(\epsilon) = F_{W(Ax_n, x_0, k_n), Ax_n}(\epsilon) > \\ &> t(F_{Ax_n, Ax_n}(\frac{\epsilon}{2k_n}), F_{Ax_n, x_0}(\frac{\epsilon}{2(1-k_n)})) = t(1, F_{Ax_n, x_0}(\frac{\epsilon}{2(1-k_n)})) = \\ &= F_{Ax_n, x_0}(\frac{\epsilon}{2(1-k_n)}) \end{aligned}$$

Since $\bigcup_{m \in \mathbb{N}} A^m(x_n) \cap SM \neq \emptyset$ for every $n \in \mathbb{N}$, it follows that there exists $y_n \in M$ ($n \in \mathbb{N}$) such that $Sy_n \in \bigcup_{m \in \mathbb{N}} A^m(x_n)$. Let us prove that for every $\epsilon > 0$: $\lim_{n \rightarrow \infty} F_{Sy_n, Ay_n}(\epsilon) = 1$. Let $\epsilon > 0$ and $\lambda \in (0, 1)$. We have to prove that there exists $n(\epsilon, \lambda) \in \mathbb{N}$ so that

$$F_{Sy_n, Ay_n}(\epsilon) > 1 - \lambda \quad , \text{ for every } n \geq n(\epsilon, \lambda) \quad .$$

As in [5] it can be proved that for every n and every k from \mathbb{N} :

$$F_{A^k x_n, A^{k+1} x_n}(\epsilon) > F_{x_n, Ax_n}(\epsilon) \quad , \text{ for every } \epsilon > 0.$$

Since t is continuous there exists $\eta \in (0, 1)$ so that

$$x, y, z \geq \eta \Rightarrow t(x, t(y, z)) > 1 - \lambda.$$

Further, for every $\varepsilon > 0$ and every $k \in \mathbb{N}$:

$$\begin{aligned} F_{S_{Y_n}, A_{Y_n}}(\varepsilon) &> t(F_{S_{Y_n}, A_{kX_n}}(\frac{\varepsilon}{3}), t(F_{A_{kX_n}, A_{k+1}X_n}(\frac{\varepsilon}{3}), \\ &\quad , F_{A_{k+1}X_n, A_{Y_n}}(\frac{\varepsilon}{3}))) > \\ &> t(F_{S_{Y_n}, A_{kX_n}}(\frac{\varepsilon}{3}), t(F_{A_{X_n}, X_0}(\frac{\varepsilon}{6(1-k_n)}), F_{A_{kX_n}, S_{Y_n}}(\frac{\varepsilon}{3}))) . \end{aligned}$$

Since $S_{Y_n} \in \bigcup_{m \in \mathbb{N}} A_{X_n}^m$, for every $n \in \mathbb{N}$ there exists $m_n \in \mathbb{N}$ such that:

$$F_{S_{Y_n}, A_{m_n X_n}}(\frac{\varepsilon}{3}) > \eta, \text{ for every } n \in \mathbb{N}.$$

Further, the set AX is probabilistic bounded, which means that $\sup_x D_{AX}(x) = 1$, where:

$$D_{AX}(x) = \sup_{t < x} \inf_{p, q \in AX} F_{p, q}(t) = 1.$$

Let us prove that there exists $n_0(\varepsilon, \eta) \in \mathbb{N}$ such that

$$(7) \quad F_{A_{X_n}, X_0}(\frac{\varepsilon}{6(1-k_n)}) > \eta, \text{ for every } n \geq n_0(\varepsilon, \eta).$$

For every $z \in X$ we have that:

$$F_{A_{X_n}, X_0}(\frac{\varepsilon}{6(1-k_n)}) > t(F_{A_{X_n}, A_z}(\frac{\varepsilon}{12(1-k_n)}), F_{A_z, X_0}(\frac{\varepsilon}{12(1-k_n)}))$$

and since $\lim_{n \rightarrow \infty} k_n = 1$ and AX is probabilistic bounded it follows that there exists $n_0(\varepsilon, \eta) \in \mathbb{N}$ so that (7) holds. Then from:

$$\begin{aligned} F_{S_{Y_n}, A_{Y_n}}(\varepsilon) &> t(F_{S_{Y_n}, A_{m_n X_n}}(\frac{\varepsilon}{3}), t(F_{A_{X_n}, X_0}(\frac{\varepsilon}{6(1-k_n)}), \\ &\quad , F_{A_{m_n X_n}, S_{Y_n}}(\frac{\varepsilon}{3}))) > t(\eta, t(\eta, \eta)), \text{ for every } n \geq n_0(\varepsilon, \eta) \end{aligned}$$

we obtain that:

$$F_{S_{Y_n}, A_{Y_n}}(\varepsilon) > 1 - \lambda, \text{ for every } n \geq n_0(\varepsilon, \eta)$$

and so:

$$\lim_{n \rightarrow \infty} F_{S_{Y_n}, A_{Y_n}}(\varepsilon) = 1, \text{ for every } \varepsilon > 0.$$

Since $\{y_n\}_{n \in \mathbb{N}} \subseteq M$ and the set M is compact there exists a convergent subsequence $\{y_{n_k}\}_{k \in \mathbb{N}}$ and let $\lim_{k \rightarrow \infty} y_{n_k} = z$. We shall prove that $Az = Sz$. This follows from the inequality:

$$F_{Az, Sz}(\varepsilon) \geq t(F_{Az, Ay_{n_k}}(\frac{\varepsilon}{3}), t(F_{Ay_{n_k}, Sy_{n_k}}(\frac{\varepsilon}{3}), F_{Sy_{n_k}, Sz}(\frac{\varepsilon}{3})))$$

($k \in \mathbb{N}$, $\varepsilon > 0$) since A and S are continuous and $t(1, t(1, 1)) = 1$.

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REZIME

O TAČKAMA KOINCIDENCIJE U METRIČKIM
I VEROVATNOSNIM METRIČKIM PROSTORIMA SA KONVEKSNOM
STRUKTUROM

Pojam konveksnosti u metričkim prostorima je uveo Takahashi u [14] i neke teoreme o nepokretnoj tački u konveksnim metričkim prostorima su dokazane u [8], [9], [14].

U ovom radu su dokazane teoreme o postojanju tačke koincidencije u metričkim i verovatnosnim metričkim prostorima sa konveksnom strukturom.