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# FIXED POINT THEORY IN PROBABILISTIC METRIC SPACES

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#### ABSTRACT

Most fixed point theorems for Probabilistic Metric spaces (PM-spaces) have been proved for the same subclass of PM-spaces. It is shown that this subclass is metrizable. Furthermore, the compatible metric d is related to the distribution functions by

$$d(x,y) < t$$
 if and only if  $F_{x,y}(t) > 1-t$ .

This allows an exact translation of the contraction condition, as well as other conditions studied in metric spaces, to PM-spaces. Thus, theorems follow immediately from corresponding theorems for metric spaces.

## 1. INTRODUCTION

A real-valued function defined on the set of real numbers is a <u>distribution function</u> if it is nondecreasing, left continuous and inf f = 0, sup f = 1. H denotes the distribution function defined by H(x) = 0 if  $x \le 0$ , and H(x) = 1 for x > 0.

DEFINITION 1.1. Let X be a set and F be a function on  $X \times X$  such that  $F(x,y) = F_{XY}$  is a distribution function. Consider the following conditions:

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I. 
$$F_{x,y}(0) = 0$$
 for all x, y in X.

II. 
$$F_{x,y} = H$$
 if and only if  $x = y$ .

III. 
$$F_{x,y} = F_{y,x}$$
.

IV. If 
$$F_{x,y}(\varepsilon) = 1$$
 and  $F_{y,z}(\delta) = 1$ , then  $F_{x,z}(\varepsilon+\delta) = 1$ .

$$IV_{m}$$
.  $F_{x,z}(\varepsilon+\delta) \geq T(F_{x,y}(\varepsilon), F_{y,z}(\delta))$ .

If F satisfies conditions I and II then it is called a <u>pre-probabilistic metric structure</u> (PPM-structure) on X and the pair (X,F) is called a <u>pre-probabilistic metric space</u> (PPM-space). An F satisfying condition III is said to be <u>symmetric</u>. A symmetric PPM-structure F satisfying IV is a <u>probabilistic metric structure</u> (PM-structure) and the pair (X,F) is a <u>probabilistic metric space</u> (PM-space).

DEFINITION 1.2. A Menger space is a PM-space that satisfies  ${\rm IV}_{\rm m}$ , where T is a 2-place function on the unit square satisfying:

- 1. T(0,0) = 0, T(a,1) = a,
- 2. T(a,b) = T(b,a),
- 3. if a < c, b < d, then  $T(a,b) \le T(c,d)$ ,
- 4. T(T(a,b),c) = T(a,T(b,c)).

T is called a t-norm.

Let (X,F) be a PPM-space. For  $\varepsilon,\lambda>0$  and  $x\in X$ , let  $N_{\mathbf{y}}(\varepsilon,\lambda)=\{y:F_{\mathbf{x}=\mathbf{y}}(\varepsilon)>1-\lambda\}$ .

A  $T_1$  topology  $\tau(F)$  on X is obtained as follows:  $U \in \tau(F)$  if for each  $x \in U$ , there exists  $\varepsilon > 0$  such that  $N_{\mathbf{X}}(\varepsilon,\varepsilon) \subseteq U$ . The study of fixed point theory in probabilistic metric spaces (PM-spaces) was started by Sehgal and Bharucha-Reid [10]. The following definition and theorem appeared in their paper.

DEFINITION 1.3. A mapping f of a PM-space (X,F) into itself is a contraction if there exists k, with 0 < k < 1, such that for each  $x,y \in X$ ,

$$F_{fx,fy}(kt) \ge F_{x,y}(t)$$
 for all  $t > 0$ .

THEOREM 1.1. Let (X,F,T) be a complete Menger space where  $T(a,b)=\min\{a,b\}$ . If f is any contraction, there exists a unique peX such that f(p)=p. Moreover,  $\lim_{n\to\infty} f^n(q)=p$  for each  $q\in X$ .

A little thought convinces oneself that this is a reasonable definition in this new setting. Also, if f is a contraction  $(d(fx,fy) \le k \ d(x,y))$  on a complete metric space (X,d), and one makes it into a PM-space in the natural way; that is,

$$F_{x,y}(t) = H(t-d(x,y)),$$

then  $F_{fx,fy}(kt) \ge F_{x,y}(t)$ . In [1], it was shown that the weaker condition,

$$F_{fx,fy}(kt) \ge F_{x,y}(t)$$
 whenever  $F_{x,y}(t) > 1-t$ ,

is sufficient to obtain the above theorem. As originally given, the theorem required T to be continuous and satisfy T(x,x) > x. It is easy to see that this forces  $T(a,b) = \min\{a,b\}$ .

# 2. BASIC THEOREMS

The following condition is another reasonable generalization of a contraction to PM-spaces.

(c) For 
$$t > 0$$
,  $F_{fx,fy}(kt) > 1-kt$  whenever  $F_{x,y}(t) > 1-t$ .

REMARK 1. If the metric space (X,d) is made into a PM-space as indicated above; that is,  $F_{X,Y}(t) = H(t-d(x,y))$ , then if  $d(fx,fy) \le k \ d(x,y)$ , for  $0 < k \le 1$ , we have condition (c).

Proof.  $F_{fx,fy}(kt) = H(kt-d(fx,fy)) \ge H(kt-kd(x,y)) = H(t-d(x,y)) = F_{x,y}(t)$ . Now  $F_{x,y}(t) = H(t-d(x,y)) > 1-t$  if and only if  $F_{x,y}(t) = 1$  if and only if  $F_{x,y}(t) > 1-kt$ . Condition (c) follows.

We now show that for each PM-space in a class larger than the one described in Theorem 1.1, there exists a compatible metric d such that

$$d(fx,fy) \le k d(x,y)$$
 iff (c) holds.

Then, using condition (c) as our definition of a contraction, we have Banach's theorem for PM-spaces as a consequence of Banach's theorem for metric spaces. Actually, a nicer result is obtained that allows you to translate many other fixed point theorems for metric spaces to PM-spaces. The result that makes this possible is:

$$d(x,y) < t$$
 iff  $F_{x,y}(t) > 1-t$ .

THEOREM 2.1. Let  $(\mathbf{X},\mathbf{F})$  be a symmetric PPM-space such that

$$F_{x,z}(r+s) \ge \min\{F_{x,y}(r),F_{y,z}(s)\}$$
.

$$\text{Let } d(x,y) = \left\{ \begin{array}{l} \sup\{\epsilon:y \not = N_{_{\mathbf{X}}}(\epsilon,\epsilon) \text{ , } o < \epsilon < 1\} \text{ ,} \\ 0 \text{ if } y \in N_{_{\mathbf{X}}}(\epsilon,\epsilon) \text{ for all } \epsilon > 0 \text{ .} \end{array} \right.$$

Then

- (1) d(x,y) < t if and only if  $F_{x,y}(t) > 1-t$ .
- (2) d is a compatible metric for t(F).
- (3) If f:X + X and  $0 < k \le 1$ ,
  - (c) holds if and only if  $d(fx, fy) \le k d(x, y)$ .
- (4) (X,F) is complete if and only if (X,d) is complete.

Proof. Observe that if t<r,  $N_X(t,t) \subset N_X(r,r)$ . Also,  $\bigcap \{N_X(\epsilon,\epsilon): 0 < \epsilon < 1\} = \{x\}$ . For, if  $x \neq y$ ,  $F_{x,y} \neq H$ . Thus

there exists  $\varepsilon > 0$  such that  $F_{\mathbf{x},\mathbf{y}}(\varepsilon) = \delta$  where  $0 < \delta < 1$ . Set  $\delta = 1 - \delta_1$  and let  $\varepsilon_1 = \min\{\varepsilon, \delta_1\}$ . Then  $F_{\mathbf{x},\mathbf{y}}(\varepsilon_1) \leq F_{\mathbf{x},\mathbf{y}}(\varepsilon) = \delta = 1 - \delta_1$   $\leq 1 - \varepsilon_1$  gives  $\mathbf{y} \notin N_{\mathbf{x}}(\varepsilon_1, \varepsilon_1)$ .

- (1) If 1 < t,  $d(x,y) \le 1 < t$  and also  $F_{x,y}(t) \ge 0 > 1-t$ . Suppose  $d(x,y) < t \le 1$ . Choose  $\delta$  such that  $d(x,y) < \delta < t \le 1$ . Then  $y \in N_x(\delta,\delta)$  and  $F_{x,y}(t) \ge F_{x,y}(\delta) > 1-\delta > 1-t$ . For, if we assume  $y \notin N_x(\delta,\delta)$ , then  $d(x,y) = \sup\{ \} \ge \delta$ , a contradiction. Conversely, suppose  $F_{x,y}(t) > 1-t$  where  $0 < t \le 1$ . Then  $y \in N_x(t,t)$ . If  $y \notin N_x(\epsilon,\epsilon)$  for all  $\epsilon < t$ ,  $F_{x,y}(t) = \lim_{\epsilon \to t^-} F_{x,y}(\epsilon) \le \lim_{\epsilon \to t^-} (1-\epsilon) = 1-t$ , a contradiction. Thus there exists  $0 < \epsilon < t$  such that  $y \in N_x(\epsilon,\epsilon)$ . Hence  $d(x,y) \le \epsilon < t$ .
- (2) If d satisfies the triangular inequality, it is a metric. Also, (1) shows it is compatible with t(F). We observe that  $d(x,y) < \varepsilon_1$  and  $d(y,z) < \varepsilon_2$  implies that  $d(x,z) < \varepsilon_1 + \varepsilon_2$ . For, suppose

$$F_{x,y}(\varepsilon_1) > 1 - \varepsilon_1$$
 and  $F_{y,z}(\varepsilon_2) > 1 - \varepsilon_2$ .

If  $F_{x,v}(\varepsilon_1)$  is the minimum,

$$\begin{split} & \quad \quad F_{\mathbf{x},\mathbf{z}}(\varepsilon_1 + \varepsilon_2) \geq \min\{F_{\mathbf{x},\mathbf{y}}(\varepsilon_1) \;,\; F_{\mathbf{y},\mathbf{z}}(\varepsilon_2)\} > 1 - \varepsilon_1 > 1 - (\varepsilon_1 + \varepsilon_2) \\ & \text{gives d}(\mathbf{x},\mathbf{z}) < \varepsilon_1 + \varepsilon_2. \text{ The triangular inequality follows.} \end{split}$$

(3) Suppose  $d(fx,fy) \le k \ d(x,y)$  and  $F_{x,y}(t) > 1-t$ . Then d(x,y) < t and d(fx,fy) < kt. Thus  $F_{fx,fy}(kt) > 1-kt$ . If (c) holds, let  $\varepsilon > 0$  be given. Set  $t = d(x,y) + \varepsilon$ .  $d(x,y) = t-\varepsilon < t$  gives

 $F_{x,y}(t) > 1-t$ , and  $F_{fx,fy}(kt) > 1-kt$  follows from (c). Thus  $d(fx,fy) < kt = k(d(x,y)+\epsilon) = kd(x,y)+k\epsilon$ . Since  $\epsilon > 0$  was arbitrary,  $d(fx,fy) < k \ d(x,y)$ .

REMARK 2. Assuming the conditions in Theorem 1.1, we have

$$F_{x,z}(r+s) \ge T(F_{x,y}(r),F_{y,z}(s)) = min\{F_{x,y}(r),F_{y,z}(s)\}$$

the inequality in Theorem 2.1. Also, the inequality in Theorem 2.1 does not require the existence of a t-norm. Condition (c) and the earlier definition of contraction seem to be independent for 0 < k < 1.

COROLLARY. Let (X,F) be a complete symmetric PPM-space such that

$$F_{x,y}(r+s) \ge \min\{F_{x,y}(r), F_{y,z}(s)\}$$
.

Suppose  $f:X \to X$  satisfies (c). Then f has a unique fixed point p. Also, if  $x \in X$  and  $x_n = f^n(x)$ , then

(1) 
$$p = \lim_{n \to \infty} x_n$$
, and

(2) for 
$$t \ge \frac{k^{n-1}}{1-k} d(x, fx) = \alpha_n$$
,  
 $1-F_{x_n, p}(t) \le \frac{k^{n-1}}{1-k} d(x, f(x))$ .

Proof. The theorem gives a compatible metric d such that  $d(fx,fy) \le k \ d(x,y)$ . From Banach's fixed point theorem, f has a unique fixed point p satisfying (1). Also,

$$d(x_n, p) \le \frac{k^n}{1-k} d(x, fx) < \frac{k^{n-1}}{1-k} d(x, fx) = \alpha_n$$
.

From (1) of the Theorem,

$$F_{x_n,p}(\alpha_n) > 1 - \alpha_n$$
.

For  $t \ge \alpha_n$ ,

$$F_{x_n,p}(t) \ge F_{x_n,p}(\alpha_n) > 1 - \alpha_n$$
.

REMARK 3. Note that the error bound is usable. Given  $\epsilon > 0$ , choose  $0 < \epsilon_0 < 1$  and x such that  $d(x,fx) < \epsilon_0$ ; that is,  $F_{x,fx}(\epsilon_0) > 1 - \epsilon_0$ . For  $t \geq \beta = \frac{\epsilon_0}{1-k} > \alpha_n$ ,

$$1 - F_{x_n, p}(t) \le \frac{k^{n-1}}{1-k} d(x, fx) < \frac{k^{n-1}}{1-k} \epsilon_0.$$

$$\text{If } \frac{k^{N-1}}{1-k} \ \epsilon_0 < \epsilon \text{, then } 1-F_{\kappa_n,p}(\texttt{t}) < \epsilon \text{ for all } n \geq N \text{ all } \texttt{t} \geq \beta \text{.}$$

We next consider how to translate other contractive type conditions for metric spaces to PM-spaces.

LEMMA. Let (X,F) and d be as in Theorem 2.1, and  $0 \le k \le 1$ . Let R = R(x,y) be a function such that  $d(x,y) \le R$ .

(C\*)  $F_{fx,fy}(kt) > 1-kt$  whenever  $F_{x,y}(t) > 1-t$  and t > R. Then (C\*) holds if and only if d(fx,fy) < kR.

The proof given for (3) of Theorem 2.1 Proof. will work here.

The numbering of the various contractive type conditions are those of Rhoades [9]. Conditions (1),(2) and (3) of [9] have obvious translations using Theorem 2.1. The Lemma can be used on other conditions. We illustrate this with the condition

(24): For 
$$0 < k < 1$$
,

 $d(fx,fy) < k \max\{d(x,y),d(x,fx),d(y,fy),d(x,fy),d(y,fx)\}.$ The translation is (C\*) of the lemma with  $R = Max\{---\}$ . There is a difficulty with this translation since (C\*) involves R = R(x,y). Another approach is possible. We translate condition that gives a common generalization of many of the conditions in [9]. The following theorem was proved by Hicks and Rhoades in [4].

THEOREM 2.2. Let (X,d) be a complete metric space and 0 < k < 1. Suppose f is a self map of X, and there exists an x such that

- (A)  $d(fy, f^2y) < k d(y, fy)$ for every  $y \in O(x, \infty) = \{x, f(x), f^2(x), \ldots\}$ . Then:

  - (i)  $\lim_{x \to q} exists$ . (ii)  $d(f^n x, q) \leq \frac{k^n}{1-k} d(x, fx)$ .
  - (iii) If f is continuous at q, fq=q

It was pointed out in [9], that conditions (1), (4), (5), (7), (9), (11), (18) and (19) each imply (21) and (21) is equivalent to (21).

$$(21')$$
 For  $0 < k < 1$ ,

 $d(fx,fy) \leq k \max\{d(x,y),d(x,fx),d(y,fy),\frac{d(x,fy)+d(y,fx)}{2}\}.$  It was noted in [4], that (21') implies (A) for all  $y \in X$ , and for  $0 \leq k \leq \frac{1}{2}$ , (24) implies (A). The following general theorem follows from Theorem 2.1 and 2.2.

THEOREM 2.3. Let (X,F) be as in Theorem 2.1 and f a self map of X. Suppose there exists an x such that

(A') for 
$$t > 0$$
,  $F_{fy,f^2y}(kt) > 1 - kt$  whenever 
$$F_{x,fy}(t) > 1 - t \text{ and } y \in O(x,\infty) .$$

Then:

- (i)  $\lim_{x \to q} exists$ .
- (ii) If f is continuous at q, fq = q.

(iii) For 
$$t \ge \frac{k^{n-1}}{1-k}$$
 f(x,Tx), we have 
$$1 - F_{x_n} p(t) \le \frac{k^{n-1}}{1-k} d(x,fx) .$$

Thus, for condimious f, (A') is more general than the translation of (21'). Also, (A') refers only to the distribution function. The compatible metric d satisfying d(x,y) <t if and only if  $F_{x,y}(t) > 1-t$  allows the translation of many other concepts and theorems from metric spaces to PM-spaces. The following will serve as an illustration.

Let (X,d) be a metric space and let  $\varepsilon > 0$ . X is  $\varepsilon$ -chainable if for every  $x,y \in X$ , there exists  $x_0,x_1,\ldots,x_n$  in X such that

$$d(x_i,x_{i+1}) < \varepsilon, i=0,1,...,n-1.$$

For PM-spaces the condition becomes

$$\mathbf{F}_{\mathbf{x}_{i},\mathbf{x}_{i+1}}(\varepsilon) > 1-\varepsilon, \quad i=0,1,\ldots,n-1.$$

A mapping f is called an  $(\varepsilon,\lambda)$ -local contraction if  $d(fx,fy) \le \lambda d(x,y) \text{ whenever } d(x,y) < \varepsilon.$ 

#### This becomes

$$\begin{split} & F_{fx,fy}(\lambda t) > 1 - \lambda t \text{ whenever } F_{x,y}(\epsilon) > 1 - \epsilon \quad \text{and} \\ & F_{x,y}(\lambda) > 1 - \lambda; \quad \text{that is, whenever} \\ & F_{x,y}(\alpha) > 1 - \alpha \quad \text{where } \alpha = \min\{\epsilon,\lambda\}. \end{split}$$

Edelstein's Theorem [2] for PM -spaces follows.

THEOREM 2.4. Let (X,F) be a complete  $\epsilon$ -chainable symmetric PPM-space such that

$$F_{x,y}(r+s) \ge \min\{F_{x,y}(r),F_{y,z}(s)\}.$$

Suppose  $f:X\to X$  is an  $(\epsilon,\lambda)$ -contraction, where  $0<\lambda<1$ . Then f has a unique fixed point p and  $\lim_{n\to\infty} f^nx=p$  for any x in X.

PROBLEM. Can the condition  $F_{x,z}(r+s) \ge \min\{F_{x,y}(r), F_{y,z}(s)\}$  in Theorem 2.1 be replaced by some other reasonable (weaker) conditions ?

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### REZIME

# TEORIJA NEPOKRETNE TAČKE U VEROVATNOSNIM METRIČKIM PROSTORIMA

Dokazane su teoreme o nepokretnoj tački za neke klase verovatnosnih metričkih prostora.