

AN EXPONENTIALLY FITTED SCHEME ON
A NON-UNIFORM MESH*

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ABSTRACT

The discretisation (6) of problem (1) is constructed on a non-uniform mesh. An exponentially fitted scheme is used and the linear convergence uniform on a small perturbation parameter ε is proved. In the case of a uniform mesh, our scheme reduces to the well known scheme of [1]. Numerical results are obtained on a special mesh, which is similar to the one in [3].

1. INTRODUCTION

In this paper we shall consider the problem

$$(1) \quad L_\varepsilon u(x) := -\varepsilon^2 u''(x) + b^2(x)u(x) = f(x), \quad x \in I = [0, 1], \\ u(0) = U_0, \quad u(1) = U_1,$$

where $b(x) \geq \beta > 0$, $x \in I$, $0 < \varepsilon \leq \varepsilon_0$, $\beta, \varepsilon, \varepsilon_0, U_0, U_1 \in \mathbb{R}$ and $b, f \in C^1(I)$. The parameter ε is a small perturbation parameter.

It is well known that there exists a unique solution $u_\varepsilon \in C^3(I)$ to problem (1). Furthermore, we have ([1], [3]):

$$(2) \quad |u^{(i)}(x)| \leq M\varepsilon^{-i}, \quad x \in I, \quad i=0,1,2,3.$$

Here, and thereafter, M will denote each positive constant independent of ε . In section 3, M will be independent of discrete

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tisation mesh as well. The dependence on ϵ will always be denoted by writing ϵ as a subscript.

The solution u_ϵ has, in general, two boundary layers near the endpoints of the interval I. Our purpose is to solve (1) numerically by the difference method on a non-uniform mesh. The reason for using a non-uniform mesh is our aim to obtain more mesh points in the region of boundary layers, those width is $O(\epsilon)$, cf. [6]. We shall use an exponentially fitted scheme, which in the case of uniform mesh reduces to the well known schemes of [1]. For such a scheme we shall prove the convergence uniform in ϵ .

2. PROPERTIES OF THE EXACT SOLUTION

A special technique was used in [2] to obtain some differentiability properties of the solution to the boundary value problem with a small parameter, containing the first derivative. We shall here use a similar technique for our problem.

THEOREM 1. *For the solution u_ϵ of (1) we have*

$$(3) \quad u_\epsilon(x) = p_\epsilon v_\epsilon(x) + z_{0,\epsilon}(x), \quad 0 \leq x \leq 1/2,$$

$$(4) \quad u_\epsilon(x) = q_\epsilon w_\epsilon(x) + z_{1,\epsilon}(x), \quad 1/2 \leq x \leq 1,$$

where

$$v_\epsilon(x) = \exp\left(-\frac{b(0)}{\epsilon} x\right),$$

$$w_\epsilon(x) = \exp\left(-\frac{b(1)}{\epsilon} (1-x)\right),$$

$$|p_\epsilon|, |q_\epsilon| \leq M \quad \text{and}$$

$$(5) \quad |z_{k,\epsilon}^{(i)}(x)| \leq M(1+\epsilon^{1-i}), \quad k=0,1,2,3, \quad i=0,1,2,3.$$

Proof. Let $x \in [0,1]$. Define

$$y_\epsilon(x) = u_\epsilon(x) - p_\epsilon v_\epsilon(x) - q_\epsilon w_\epsilon(x)$$

and take p_ϵ and q_ϵ so that $y'_\epsilon(0) = 0$, $y'_\epsilon(1) = 0$. It is easily obtained that such p_ϵ , q_ϵ exist and $|p_\epsilon|, |q_\epsilon| \leq M$. Hence, we have

$$|y_\epsilon(x)| \leq M.$$

Then we get

$$L_\epsilon y'_\epsilon(x) = g'_\epsilon(x) - (b^2(x))' y'_\epsilon(x) =: G_\epsilon(x),$$

where

$$g_\epsilon(x) = f(x) - p_\epsilon L_\epsilon v_\epsilon(x) - q_\epsilon L_\epsilon w_\epsilon(x).$$

Now it can be easily proved that, cf. [1],

$$|g'_\epsilon(x)| \leq M,$$

which implies $|G_\epsilon(x)| \leq M$. Hence, $y'_\epsilon(x)$ is a solution to the problem

$$L_\epsilon y'_\epsilon(x) = G_\epsilon(x), \quad x \in [0, 1],$$

$$y'_\epsilon(0) = y'_\epsilon(1) = 0,$$

and because of (2), it follows:

$$|y^{(i)}_\epsilon(x)| \leq M \epsilon^{1-i}, \quad i=1, 2, 3, \quad x \in [0, 1].$$

Now we can take

$$z_{0,\epsilon}(x) = y_\epsilon(x) + p_\epsilon w_\epsilon(x), \quad x \in [0, 1/2],$$

and since

$$|w_\epsilon(x)| \leq M, \quad x \in [0, 1/2],$$

we obtain (3) and (5) for $k=0$. Similarly we take

$$z_{1,\epsilon}(x) = y_\epsilon(x) + q_\epsilon w_\epsilon(x), \quad x \in [1/2, 1],$$

to complete the proof.

A similar result was obtained in [1]. For similar estimates of the derivatives of u_ϵ cf. [3].

3. THE SCHEME

We use the discretisation mesh

$$I_h = \{x_i! x_0 = 0, x_i = x_{i-1} + h_i, \quad i=1, 2, \dots, n\},$$

where $n \in \mathbb{N}$, $h_i > 0$, $i=1, 2, \dots, n$, $h_1 + h_2 + \dots + h_n = 1$. For simplicity we take $n = 2m$, $m \in \mathbb{N} \setminus \{1\}$, and $x_m = 1/2$. Let $h_i \leq h_{i+1}$, $i = 1, 2, \dots, m-1$, and $h_i \geq h_{i+1}$, $i = m+1, \dots, n$, which is a natural assumption because of boundary layers. Let $h := \max\{h_m, h_{m+1}\} \leq 1/4$.

Instead of $1/4$ we can take any fixed constant in $(0, 1/2)$, so this inequality is not a real restriction.

On the mesh I_h we form the discretisation of the problem (1):

$$(6) \quad L_{\epsilon}^h u_i := -\epsilon^2 \sigma_i D_h u_i + b^2(x_i) u_i = f(x_i), \quad i=1, 2, \dots, n-1,$$

$$u_0 = U_0, \quad u_n = U_1,$$

where

$$D_h u_i = \frac{2}{(h_1 + h_{i+1}) h_i h_{i+1}} (h_{i+1} u_{i-1} - (h_i + h_{i+1}) u_i + h_i u_{i+1}),$$

$$i=1, 2, \dots, n-1,$$

and

$$\sigma_i(\rho_o) := \frac{1}{2} \rho_o^2 \frac{h_i h_{i+1} (h_i + h_{i+1})}{h_{i+1} (e^{\rho_o h_{i-1}}) + h_i (e^{-\rho_o h_{i+1}} - 1)}, \quad i=1, 2, \dots, m-1$$

$$\sigma_i = \begin{cases} 1, & i=m \\ \sigma_i(\rho_n) := \frac{1}{2} \rho_n^2 \frac{h_i h_{i+1} (h_i + h_{i+1})}{h_{i+1} (e^{-\rho_n h_i} - 1) + h_i (e^{\rho_n h_{i+1}} - 1)} & i=m+1, \dots, n-1 \end{cases}$$

$$\rho_i = b(x_i)/\epsilon, \quad i=0, 1, \dots, n.$$

The solution of (6) is $u_h = [u_0, u_1, \dots, u_n]^T \in \mathbb{R}^{n+1}$ (here we omit the subscript ϵ). Let u_{ϵ}^h denote the restriction of u_{ϵ} to the mesh I_h : $u_{\epsilon}^h = [u_{\epsilon}(x_0), u_{\epsilon}(x_1), \dots, u_{\epsilon}(x_n)]^T \in \mathbb{R}^{n+1}$.

We use the maximum norm $\|v\| = \max_{0 \leq i \leq n} |v_i|$ for any vector

$$v = [v_0, v_1, \dots, v_n]^T \in \mathbb{R}^{n+1} \quad \text{and} \quad \|A\| = \max_{0 \leq i \leq n} \sum_{j=0}^n |a_{ij}| \quad \text{for any matrix } A = [a_{ij}] \in \mathbb{R}^{n+1, n+1}.$$

THEOREM 2. *It is valid that*

$$\|u_{\epsilon}^h - u_h\| \leq M h.$$

P r o o f. The consistency error of the operator L_ϵ^h is by definition:

$$r_i := L_\epsilon^h u_\epsilon(x_i) - (L_\epsilon u_\epsilon)_{x=x_i} = -\epsilon^2 (\sigma_i D_h u_\epsilon(x_i) - u''_\epsilon(x_i)) , \\ i = 1, 2, \dots, n-1 .$$

Let $r_h = [0, r_1, r_2, \dots, r_{n-1}, 0]^T \in \mathbb{R}^{n+1}$ and $f_h = [U_0, f(x_1), f(x_2), \dots, f(x_{n-1}), U_1]^T \in \mathbb{R}^{n+1}$. Then (6) can be written in the form

$$A_\epsilon^h u_h = f_h ,$$

where $A_\epsilon^h \in \mathbb{R}^{n+1, n+1}$ is tridiagonal matrix. Since $\sigma_i > 0$, $i=1, 2, \dots, n-1$, (see Lemma 1. below), A_ϵ^h is an L-matrix, inverse monotone and (cf. eg. [4], [5]):

$$\| (A_\epsilon^h)^{-1} \| \leq \max(1, \beta^{-2}) .$$

Now we have

$$A_\epsilon^h (u_\epsilon^h - u_h) = f_h + r_h - r_h = r_h$$

and

$$\| u_\epsilon^h - u_h \| \leq \| (A_\epsilon^h)^{-1} \| \| r_h \| \leq M \| r_h \| .$$

To complete the proof it is sufficient to show that

$$\| r_h \| \leq M h .$$

or

$$(7) \quad |r_i| \leq M h , \quad i=1, 2, \dots, n-1 .$$

First we consider $i=1, 2, \dots, n-1$. The fitting factor $\sigma_i = \sigma_i^0(\rho_0)$ is chosen so that

$$\sigma_i D_h v_\epsilon(x_i) = v''_\epsilon(x_i) ,$$

where $v_\epsilon(x)$ is given Theorem 1. This fact and (3) imply that

$$(8) \quad |r_i| = \epsilon^2 |\sigma_i D_h z_{0,\epsilon}(x_i) - z''_{0,\epsilon}(x_i)| .$$

Since there exists a point $\theta_i \in [x_{i-1}, x_{i+1}]$ such that

$$D_h z_{0,\epsilon}(x_i) = z''_{0,\epsilon}(\theta_i) ,$$

from (8) it follows that

$$|r_i| \leq \epsilon^2 |\sigma_i| |z''_{0,\epsilon}(\theta_i)| + \epsilon^2 |z''_{0,\epsilon}(\theta_i) - z''_{0,\epsilon}(x_i)| \leq \\ \leq \epsilon^2 |\sigma_i| K_2 + \epsilon^2 h_{i+1} K_3 ,$$

where

$$K_j = \max_{0 \leq x \leq 1/2} |z_{0,\epsilon}^{(j)}|, \quad j=2,3.$$

From Theorem 1. we have

$$K_j \leq M \epsilon^{1-j}, \quad j=2,3$$

and

$$|r_i| \leq M(\epsilon |1-\sigma_i| + h).$$

In Lemma 2. we shall prove that

$$\epsilon |1-\sigma_i| \leq M h_{i+1}.$$

Because of that, (7) is valid for $i=1,2,\dots,m-1$.

In the case when $i=m+1,\dots,n-1$ the proof of (7) is analogous. We use (4) and

$$\sigma_i^1(\rho_n) D_h w_\epsilon(x_i) = w_\epsilon^n(x_i).$$

When $i=m$, we have

$$|r_m| \leq \epsilon^2 h \max_{x_{m-1} \leq x \leq x_{m+1}} |u_\epsilon^{(3)}(x)|,$$

and because of Theorem 1.:

$$|r_m| \leq \epsilon^2 h M (1 + \epsilon^{-2} + \epsilon^{-3} (\exp(-\frac{b(0)}{\epsilon} x_{m-1}) + \exp(-\frac{b(1)}{\epsilon} (1 - x_{m+1})))) .$$

Since $x_{m-1} = 1/2 - h_m \geq 1/4$ and $x_{m+1} = 1/2 + h_{m+1} \leq 3/4$, we get

$$|r_m| \leq M h.$$

Here we used $\epsilon^{-1} \exp(-\frac{\beta}{4\epsilon}) \leq M$. This completes the proof of Theorem 2.

LEMMA 1. For $\rho > 0$ it is valid that $\sigma_i^0(\rho) > 0$, $i=1,2,\dots,m-1$.

P r o o f. Let $i=1,2,\dots,m-1$ and

$$g(\rho) := h_{i+1}^{ph}(e^{-\rho} - 1) + h_i(e^{-\rho h_{i+1}} - 1).$$

We have $g(0) = 0$ and $g'(\rho) > 0$ for $\rho > 0$. Now it follows that $g(\rho) > 0$ and $\sigma_i^0(\rho) > 0$, $\rho > 0$.

LEMMA 2. For $\rho > 0$ it is valid that

$$(9) \quad |1 - \sigma_i^O(\rho)| \leq h_{i+1}^{-\rho}, \quad i=1, 2, \dots, m-1.$$

P r o o f. Let $i=1, 2, \dots, m-1$ and let us denote $k = h_i$, $K_i = h_{i+1}$. First we shall prove

$$(10) \quad \sigma_i^O(\rho) \leq 1 + K \rho.$$

This inequality is equivalent with

$$(11) \quad \sum_{j=3}^{\infty} \frac{\rho^j}{j!} K(k+K) R_j \geq 0,$$

where

$$R_j = j(k+K)^{j-2} K + (k+K)^{j-1} - (j+1)K^{j-1} - \frac{1}{2} j(j-1)kK^{j-2}.$$

Now we have that $R_3 = k^2 + kK \geq 0$ and from $R_j \geq 0$, $j \geq 3$, it follows that

$$\begin{aligned} R_{j+1} &\geq (k+K)((j+1)K^{j-1} + \frac{1}{2} j(j-1)kK^{j-2}) + (k+K)^{j-1} K - \\ &\quad - (j+2)K^j - \frac{1}{2} (j+1)jkK^{j-1} \geq \\ &\geq \frac{1}{2} jkK^{j-2}((j-1)(k+K) - (j+1)K) + (j+1)kK^{j-1} = \\ &= \frac{1}{2} j(j-1)k^2 K^{j-2} + kK^{j-1} \geq 0. \end{aligned}$$

Hence, (11) is valid and so is (10). Using a similar technique we can get

$$(12) \quad \sigma_i^O(\rho) \geq 1 - \rho K.$$

The inequalities (11) and (12) imply (9).

4. SOME REMARKS

The difference scheme used in (6) has quasi-constant fitting factors in the sense of [5]. Namely, when the mesh is uniform ($h_i = h$, $i=1, 2, \dots, n$), we get the constant fitting factors from [1]:

$$\sigma_i^O(\rho_O) = (\rho_O h/2)^2 \sinh^{-2}(\rho_O h/2), \quad \sigma_i^L(\rho_n) = \sigma_i^O(\rho_n).$$

Because of the non-uniform mesh we have proved linear convergence uniform in ϵ . In [1] it is shown that on the uniform mesh the quadratic convergence uniform in ϵ can be obtained when $u_\epsilon \in C^4(I)$ and $b(0) = b(1)$.

A similar scheme with quasi-constant fitting factor was obtained in [5], but our scheme seems to be simpler.

It is possible to construct a scheme with variable fitting factors. We can take (6) with

$$\sigma_i = \begin{cases} \sigma_i^0(\rho_i), & i=1, 2, \dots, m-1 \\ 1, & i=m \\ \sigma_i^1(\rho_i), & i=m+1, \dots, n-1 \end{cases}$$

Such a scheme was also considered in [1] on the uniform mesh.

5. NUMERICAL EXAMPLE

We shall consider a simple test problem from [7], [4]:

$$-\epsilon^2 u'' + u = 1, \quad x \in I, \quad u(0) = u(1).$$

For the solution of this problem we have $u_\epsilon(1/2+x) = u_\epsilon(1/2-x)$, $x \in [0, 1/2]$ and we shall give numerical results on $[0, 1/2]$.

Let m_1 be the number of mesh points x_i in $[0, \epsilon]$ and let

$$E = \max\{|u_\epsilon(x_i) - u_i| | x_i \in (\epsilon, 1/2]\},$$

$$E_1 = \max\{|u_\epsilon(x_i) - u_i| | x_i \in [0, \epsilon]\},$$

$$P = \max\{|u_\epsilon(x_i) - u_i| / |u_\epsilon(x_i)| | x_i \in (\epsilon, 1/2]\} \cdot 100,$$

$$P_1 = \max\{|u_\epsilon(x_i) - u_i| / |u_\epsilon(x_i)| | x_i \in [0, \epsilon]\} \cdot 100.$$

It is convenient to use such a mesh which changes automatically when ϵ does. This enables us to achieve the same number of mesh points in the boundary layer whatever value ϵ takes. A special mesh of a such type was given in [3], where the mesh points are determined as values of function $\lambda_\epsilon(s)$ at equidistant points (see [4] as well). This mesh implies a convergence uniform in ϵ for the classical scheme

$$-\epsilon^2 D_h u_i + b^2(x_i) u_i = f(x_i).$$

Here we shall use a similar but simpler function $\lambda_\epsilon(s)$:

$$\lambda_\epsilon(s) = \begin{cases} \psi_\epsilon(s), & s \in [0, \alpha] \\ \psi_\epsilon(\alpha) + \psi'_\epsilon(\alpha)(s-\alpha), & s \in [\alpha, 1/2] \end{cases}$$

where $\psi_\epsilon(s) = a\epsilon s / (q-s)$, $s \in [0, q]$. q and a are fixed constants:

$q \in (0, 1/2)$ and $a > 0$, and $(\alpha, \psi_\epsilon(\alpha))$ is the point of contact of a tangent line taking the value $1/2$ at $s=1/2$, to the curve $\psi_\epsilon(s)$. We take an $\epsilon \leq q$. Then there exists unique $\alpha \in [0, q]$ and it be easily determined from

$$\psi_\epsilon(\alpha) = 1/2 + \psi'_\epsilon(\alpha)(\alpha-1/2),$$

which reduces to a quadratic equation.

We shall take mesh I_h with

$$x_i = \lambda_\epsilon(i/n), \quad i=0, 1, \dots, m,$$

and test our scheme (6).

TABLE 1. $a=1$, $q=0.4$, $m=20$

ϵ	m_1	E	E_1	P	P_1
10^{-2}	9	$1.19 \cdot 10^{-7}$	$2.09 \cdot 10^{-7}$	$1.19 \cdot 10^{-5}$	$3.23 \cdot 10^{-4}$
10^{-4}	9	$5.96 \cdot 10^{-8}$	$1.64 \cdot 10^{-7}$	$8.24 \cdot 10^{-6}$	$2.54 \cdot 10^{-4}$
10^{-6}	9	$1.79 \cdot 10^{-7}$	$2.98 \cdot 10^{-7}$	$2.47 \cdot 10^{-5}$	$3.12 \cdot 10^{-4}$
10^{-10}	9	$1.19 \cdot 10^{-7}$	$2.09 \cdot 10^{-7}$	$1.65 \cdot 10^{-5}$	$3.12 \cdot 10^{-4}$

TABLE 2. $a=0.3$, $q=0.499$, $m=20$

ϵ	m_1	E	E_1	P	P_1
10^{-2}	16	$7.75 \cdot 10^{-7}$	$2.04 \cdot 10^{-6}$	$1.10 \cdot 10^{-4}$	$1.89 \cdot 10^{-3}$
10^{-4}	16	$1.07 \cdot 10^{-6}$	$2.29 \cdot 10^{-6}$	$1.53 \cdot 10^{-4}$	$1.99 \cdot 10^{-3}$
10^{-6}	16	$1.07 \cdot 10^{-6}$	$2.40 \cdot 10^{-6}$	$1.53 \cdot 10^{-4}$	$2.04 \cdot 10^{-3}$
10^{-10}	16	$1.19 \cdot 10^{-6}$	$2.35 \cdot 10^{-6}$	$1.70 \cdot 10^{-4}$	$2.10 \cdot 10^{-3}$

With a small number of mesh points we achieve extremely

good results. The errors change slightly for different values of ϵ . A high percentage of mesh points in the boundary layer is obtained.

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REZIME

JEDNA EKSPONENCIJALNO FITOVANA ŠEMA NA
NERAVNOMERNOJ MREŽI

U radu se posmatra diskretizacija problema (1) na neravnomernoj mreži. Koristi se eksponencijalno fitovana šema (6) i

dokazuje linearna konvergencija uniformna po malom parametru ϵ . U slučaju kada je mreža ekvidistantna posmatrana šema svodi se na poznatu šemu iz [1] sa konstantnim faktorom fitovanja.

Numerički rezultati dobijeni su na specijalno konstruisanoj mreži, koja je formirana slično kao u [3].