

A COMMON FIXED POINT THEOREM FOR WEAKLY COMPATIBLE MAPPINGS IN NON-ARCHIMEDEAN MENGER PM-SPACES

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Abstract. In the present paper we prove a unique common fixed point theorem for four weakly compatible self maps in non-Archimedean Menger PM-spaces without using the notion of continuity. Our result generalizes and extends the results of Khan and Sumitra [M.A. Khan, Sumitra, A common fixed point theorem in non-Archimedean Menger PM-space, Novi Sad J. Math. 39 (1) (2009), 81–87] and others.

1. Introduction

Non-Archimedean probabilistic metric spaces and some topological preliminaries on them were first studied by Istrătescu and Crivăţ [9] (see also [8]). Some fixed point theorems for mappings on non-Archimedean Menger spaces have been proved by Istrătescu [6, 7] as a result of the generalizations of some of the results of Sehgal and Bharucha-Reid [16] and Sherwood [17]. Achari [1] studied the fixed points of quasi-contraction type mappings in non-Archimedean PM-spaces and generalized the results of Istrătescu [7]. Recently Khan and Sumitra [13] proved a common fixed point theorem for three pointwise R-weakly commuting mappings in complete non-Archimedean Menger PM-spaces. In the present paper we prove a unique common fixed point theorem for four weakly compatible self maps in non-Archimedean Menger PM-spaces without using the notion of continuity. Our result generalizes and extends the results of Khan and Sumitra [13] and others.

2. Preliminaries

DEFINITION 2.1. [7, 9] Let X be any non-empty set and D be the set of all left continuous distribution functions. An ordered pair (X, F) is said to be non-Archimedean probabilistic metric space (N.A. PM-space) if F is a mapping from $X \times X$ into D satisfying the following conditions, where the value of F at $(x, y) \in X \times X$ is represented by $F_{x,y}$ or $F(x, y)$ for all $x, y \in X$ such that

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- (i) $F(x, y; t) = 1$ for all $t > 0$ if only if $x = y$;
- (ii) $F(x, y; t) = F(y, x; t)$;
- (iii) $F(x, y; 0) = 0$;
- (iv) If $F(x, y; t_1) = F(y, z; t_2) = 1$ then $F(x, z; \max\{t_1, t_2\}) = 1$ for all $x, y, z \in X$.

DEFINITION 2.2. [14] A t-norm is a function $\Delta : [0, 1] \times [0, 1] \rightarrow [0, 1]$ which is associative, commutative, non-decreasing in each coordinate and $\Delta(a, 1) = a$ for all $a \in [0, 1]$.

DEFINITION 2.3. [8, 10] A non-Archimedean Menger PM-space is an ordered triplet (X, F, Δ) , where Δ is a t-norm and (X, F) is an N.A. PM-space satisfying the following condition:

$$F(x, z; \max\{t_1, t_2\}) \geq \Delta(F(x, y; t_1), F(y, z; t_2)) \text{ for all } x, y, z \in X, t_1, t_2 \geq 0.$$

For details of topological preliminaries on non-Archimedean Menger PM-spaces, we refer to Cho, Ha and Chang [3].

DEFINITION 2.4. [2, 3] An N.A. Menger PM-space (X, F, Δ) is said to be of type $(C)_g$ if there exists a $g \in \Omega$ such that $g(F(x, z; t)) \leq g(F(x, y; t)) + g(F(y, z; t))$ for all $x, y, z \in X, t \geq 0$, where $\Omega = \{g \mid g : [0, 1] \rightarrow [0, \infty) \text{ is continuous, strictly decreasing with } g(1) = 0 \text{ and } g(0) < \infty\}$.

DEFINITION 2.5. [2, 3] An N.A. Menger PM-space (X, F, Δ) is said to be of type $(D)_g$ if there exists a $g \in \Omega$ such that $g(\Delta(t_1, t_2)) \leq g(t_1) + g(t_2)$ for all $t_1, t_2 \in [0, 1]$.

REMARK 2.1. [2, 3] (i) If N.A. Menger PM-space is of type $(D)_g$ then (X, F, Δ) is of type $(C)_g$.

(ii) If (X, F, Δ) is N.A. Menger PM-space and $\Delta \geq \Delta(r, s) = \max(r + s - 1, 1)$, then (X, F, Δ) is of type $(D)_g$ for $g \in \Omega$ and $g(t) = 1 - t$.

Throughout this paper (X, F, Δ) is a complete N.A. Menger PM-space with a continuous strictly increasing t-norm Δ .

Let $\phi : [0, \infty) \rightarrow [0, \infty)$ be a function satisfying the condition

$$\phi \text{ is upper semi-continuous from the right and } \phi(t) < t \text{ for } t > 0. \quad (\Phi)$$

DEFINITION 2.6. [2, 3] A sequence $\{x_n\}$ in the N.A. Menger PM-space (X, F, Δ) converges to x if and only if for each $\epsilon > 0, \lambda > 0$ there exists $M(\epsilon, \lambda)$ such that $g(F(x_n, x; \epsilon)) < g(1 - \lambda)$ for all $n > M$.

DEFINITION 2.7. [3] A sequence $\{x_n\}$ in the N.A. Menger PM-space is a Cauchy sequence if and only if for each $\epsilon > 0, \lambda > 0$ there exists $M(\epsilon, \lambda)$ such that $g(F(x_n, x_{n+p}; \epsilon)) < g(1 - \lambda)$ for all $n > M$ and $p \geq 1$.

EXAMPLE 2.1. [3] Let X be any set with at least two elements. If we define $F(x, x; t) = 1$ for all $x \in X, t > 0$ and $F(x, y; t) = \{0 \text{ if } t \leq 1 \text{ and } 1 \text{ if } t > 1\}$,

where $x, y \in X, x \neq y$, then (X, F, Δ) is the N.A. Menger PM-space with $\Delta(a, b) = \min(a, b)$ or $(a.b)$.

EXAMPLE 2.2. [3] Let $X = R$ be the set of real numbers equipped with metric defined as $d(x, y) = |x - y|$. Set $F(x, y; t) = \frac{t}{t+d(x,y)}$. Then (X, F, Δ) is an N.A. Menger PM-space with Δ as continuous t-norm satisfying $\Delta(r, s) = \min(r, s)$ or $(r.s)$.

LEMMA 2.1. [3] *If a function $\phi : [0, \infty) \rightarrow [0, \infty)$ satisfies the condition (Φ) , then we get*

- (i) *for all $t \geq 0$, $\lim_{n \rightarrow \infty} \phi^n(t) = 0$, where $\phi^n(t)$ is the n -th iteration of $\phi(t)$,*
- (ii) *if $\{t_n\}$ is a non-decreasing sequence of real numbers and $t_{n+1} \leq \phi(t_n)$, $n = 1, 2, \dots$, then $\lim_{n \rightarrow \infty} t_n = 0$. In particular, if $t \leq \phi(t)$, for each $t \geq 0$, then $t = 0$.*

LEMMA 2.2. [3] *Let $\{y_n\}$ be a sequence in X such that $\lim_{n \rightarrow \infty} F(y_n, y_{n+1}; t) = 1$ for each $t > 0$. If $\{y_n\}$ is not a Cauchy sequence in X , then there exist $\epsilon_0 > 0$, $t_0 > 0$, and two sequences $\{m_i\}$ and $\{n_i\}$ of positive integers such that*

- (i) *$m_i > n_i + 1$ and $n_i \rightarrow \infty$ as $i \rightarrow \infty$.*
- (ii) *$F(y_{m_i}, y_{n_i}; t_0) < 1 - \epsilon_0$ and $F(y_{m_{i-1}}, y_{n_i}; t_0) \geq 1 - \epsilon_0$, $i = 1, 2, \dots$.*

DEFINITION 2.8. [10] Let $A, S : X \rightarrow X$ be mappings. A and S are said to be compatible if $\lim_{n \rightarrow \infty} g(F(ASx_n, SAx_n; t)) = 0$ for all $t > 0$, when $\{x_n\}$ is a sequence in X such that $\lim_{n \rightarrow \infty} Ax_n = z = \lim_{n \rightarrow \infty} Sx_n$ for some $z \in X$.

DEFINITION 2.9. [11, 12] Let $A, S : X \rightarrow X$ be mappings. A and S are said to be weakly compatible if they commute at coincidence points. That is, if $Ax = Sx$ implies that $ASx = SAx$, for x in X .

3. Main results

THEOREM 3.1. *Let (X, F, Δ) be a complete N.A. Menger PM-space and $A, B, S, T : X \rightarrow X$ be mappings satisfying*

- (i) $A(X) \subseteq T(X), B(X) \subseteq S(X)$,
- (ii) *the pairs $\{A, S\}$ and $\{B, T\}$ are weakly compatible and*
- (iii) $g(F(Ax, By; t)) \leq \phi[\max\{g(F(Sx, Ty; t)), g(F(Sx, Ax; t)), g(F(Ty, By; t)), \frac{1}{2}(g(F(Sx, By; t)) + g(F(Ty, Ax; t)))\}]$,

for every $x, y \in X$, where ϕ satisfies the condition (Φ) . Then A, B, S and T have a unique common fixed point in X .

Proof. Since $A(X) \subseteq T(X)$, for any $x_0 \in X$, there exists a point $x_1 \in X$ such that $Ax_0 = Tx_1$. Since $B(X) \subseteq S(X)$, for this x_1 , we can choose a point $x_2 \in X$ such that $Bx_1 = Sx_2$ and so on. Inductively, we can define a sequence $\{y_n\}$ in X such that

$$y_{2n} = Ax_{2n} = Tx_{2n+1}, \quad y_{2n+1} = Bx_{2n+1} = Sx_{2n+2} \quad \text{for } n = 1, 2, \dots \quad (1)$$

Let $M_n = g(F(Ax_n, Bx_{n+1}; t)) = g(F(y_n, y_{n+1}; t))$ for $n = 1, 2, \dots$. Then

$$\begin{aligned} M_{2n} &= g(F(Ax_{2n}, Bx_{2n+1}; t)) \\ &\leq \phi[\max\{g(F(Sx_{2n}, Tx_{2n+1}; t)), g(F(Sx_{2n}, Ax_{2n}; t)), g(F(Tx_{2n+1}, Bx_{2n+1}; t)), \\ &\quad \frac{1}{2}(g(F(Sx_{2n}, Bx_{2n+1}; t)) + g(F(Tx_{2n+1}, Ax_{2n}; t)))\}] \\ &\leq \phi[\max\{g(F(y_{2n-1}, y_{2n}; t)), g(F(y_{2n-1}, y_{2n}; t)), g(F(y_{2n}, y_{2n+1}; t)), \\ &\quad \frac{1}{2}(g(F(y_{2n-1}, y_{2n+1}; t)) + g(F(y_{2n}, y_{2n}; t)))\}] \\ &\leq \phi[\max\{g(F(y_{2n-1}, y_{2n}; t)), g(F(y_{2n-1}, y_{2n}; t)), g(F(y_{2n}, y_{2n+1}; t)), \\ &\quad \frac{1}{2}(g(F(y_{2n-1}, y_{2n}; t)) + g(F(y_{2n}, y_{2n+1}; t)))\}] \end{aligned}$$

i.e.

$$M_{2n} \leq \phi[\max\{M_{2n-1}, M_{2n-1}, M_{2n}, \frac{1}{2}(M_{2n-1} + M_{2n})\}] \tag{2}$$

If $M_{2n} > M_{2n-1}$ then by (2) $M_{2n} \geq \phi(M_{2n})$, a contradiction. If $M_{2n-1} > M_{2n}$ then by (2) $M_{2n} \leq \phi(M_{2n-1})$. So by Lemma 2.1, we have $\lim_{n \rightarrow \infty} M_{2n} = 0$, i.e.,

$$\lim_n g(F(Ax_{2n}, Bx_{2n+1}; t)) = 0 \text{ i.e. } \lim_n g(F(y_{2n}, y_{2n+1}; t)) = 0.$$

Similarly, we can show that

$$\lim_n g(F(Bx_{2n+1}, Ax_{2n+2}; t)) = 0 \text{ i.e. } \lim_n g(F(y_{2n+1}, y_{2n+2}; t)) = 0.$$

Thus we have $\lim_n g(F(Ax_n, Bx_{n+1}; t)) = 0$ for all $t > 0$, i.e.

$$\lim_n g(F(y_n, y_{n+1}; t)) = 0 \text{ for all } t > 0. \tag{3}$$

Before proceeding with the proof of the theorem, we first prove the following claim:

CLAIM. Let A, B, S and $T: X \rightarrow X$ be maps satisfying (i), (ii) and (iii) and $\{y_n\}$ be defined by (1) such that

$$\lim_n g(F(y_n, y_{n+1}; t)) = 0 \tag{4}$$

for all n . Then $\{y_n\}$ is a Cauchy sequence.

Proof of Claim. Since $g \in \Omega$, it follows that $\lim_{n \rightarrow \infty} F(y_n, y_{n+1}; t) = 1$ for each $t > 0$ if and only if $\lim_{n \rightarrow \infty} g(F(y_n, y_{n+1}; t)) = 1$ for each $t > 0$.

By Lemma 2.2, if $\{y_n\}$ is not a Cauchy sequence in X , there exists $\epsilon_0 > 0$, $t_0 > 0$ and two sequences $\{m_i\}$ and $\{n_i\}$ of positive integers such that

- (A) $m_i > n_i + 1$ and $n_i \rightarrow \infty$ as $i \rightarrow \infty$;
- (B) $g(F(y_{m_i}, y_{n_i}; t_0)) > g(1 - \epsilon_0)$ and $g(F(y_{m_i-1}, y_{n_i}; t_0)) \leq g(1 - \epsilon_0)$, $i = 1, 2, \dots$

Since $g(t) = 1 - t$, we have

$$\begin{aligned} g(1 - \epsilon_0) &< g(F(y_{m_i}, y_{n_i}; t_0)) \\ &\leq g(F(y_{m_i}, y_{m_i-1}; t_0)) + g(F(y_{m_i-1}, y_{n_i}; t_0)) \\ &\leq g(F(y_{m_i}, y_{m_i-1}; t_0)) + g(1 - \epsilon_0). \end{aligned} \tag{5}$$

As $i \rightarrow \infty$ in (5) we have

$$\lim_{n \rightarrow \infty} g(F(y_{m_i}, y_{n_i}; t_0)) = g(1 - \epsilon_0). \tag{6}$$

On the other hand, we have

$$\begin{aligned} g(1 - \epsilon_0) &< g(F(y_{m_i}, y_{n_i}; t_0)) \\ &\leq g(F(y_{n_i}, y_{n_i+1}; t_0)) + g(F(y_{m_i}, y_{n_i+1}; t_0)) \end{aligned} \tag{7}$$

Now consider $g(F(y_{m_i}, y_{n_i+1}; t_0))$ in (7) and assume that both m_i and n_i are even. Then, by (iii), we have

$$\begin{aligned} g(F(y_{m_i}, y_{n_i+1}; t_0)) &= g(F(Ax_{m_i}, Bx_{n_i+1}; t_0)) \\ &\leq \phi[\max\{g(F(Sx_{m_i}, Tx_{n_i+1}; t_0)), g(F(Sx_{m_i}, Ax_{m_i}; t_0)), g(F(Tx_{n_i+1}, Bx_{n_i+1}; t_0)), \\ &\quad \frac{1}{2}(g(F(Sx_{m_i}, Bx_{n_i+1}; t_0)) + g(F(Tx_{n_i+1}, Ax_{m_i}; t_0)))\}] \\ &\leq \phi[\max\{g(F(y_{m_i-1}, y_{n_i}; t_0)), g(F(y_{m_i-1}, y_{m_i}; t_0)), g(F(y_{n_i}, y_{n_i+1}; t_0)), \\ &\quad \frac{1}{2}(g(F(y_{m_i-1}, y_{n_i+1}; t_0)) + g(F(y_{n_i}, y_{m_i}; t_0)))\}] \end{aligned}$$

Letting $i \rightarrow \infty$ in above equation, we have

$$g(1 - \epsilon_0) \leq \phi[\max\{g(1 - \epsilon_0), 0, 0, g(1 - \epsilon_0)\}],$$

i.e. $g(1 - \epsilon_0) \leq \phi(g(1 - \epsilon_0))$, which is a contradiction. Hence the sequence $\{y_n\}$ defined by (1) is a Cauchy sequence, which concludes the proof of the claim.

Since X is complete, then the sequence $\{y_n\}$ converges to a point z in X and so the subsequences $\lim_{n \rightarrow \infty} Ax_{2n}$, $\lim_{n \rightarrow \infty} Bx_{2n+1}$, $\lim_{n \rightarrow \infty} Sx_{2n}$ and $\lim_{n \rightarrow \infty} Tx_{2n+1}$ of $\{y_n\}$ also converge to the limit z .

Since $B(X) \subseteq S(X)$, there exists a point $u \in X$ such that $z = Su$. Then, using (iii), we have

$$\begin{aligned} g(F(Au, z; t)) &\leq g(F(Au, Bx_{2n-1})) + g(F(Bx_{2n-1}, z)) \\ &\leq \phi[\max\{g(F(Su, Tx_{2n-1}; t)), g(F(Su, Au; t)), g(F(Tx_{2n-1}, Bx_{2n-1}; t)), \\ &\quad \frac{1}{2}(g(F(Su, Bx_{2n-1})) + g(F(Tx_{2n-1}, Au)))\}] \end{aligned}$$

Letting $n \rightarrow \infty$, we get

$$\begin{aligned} g(F(Au, z; t)) &\leq \phi[\max\{g(z, z; t), g(F(z, Au; t)), g(F(z, z; t)), \\ &\quad \frac{1}{2}(g(F(z, z; t)) + g(F(z, Au; t)))\}] \\ &= \phi[\max\{0, g(F(z, Au; t)), 0, \frac{1}{2}(0 + g(F(z, Au; t)))\}] \\ &\leq \phi(g(F(Au, z; t))) \end{aligned}$$

for all $t > 0$, which implies that $g(F(Au, z; t)) = 0$ for all $t > 0$ by Lemma 2.1. Therefore $Au = Su = z$. Since $A(X) \subseteq T(X)$, there exists a point v in X such that $z = Tv$. Again using (iii), we have

$$g(F(z, Bv; t)) = g(F(Au, Bv; t))$$

$$\begin{aligned}
&\leq \phi[\max\{g(Su, Tv; t), g(F(Su, Au; t)), g(F(Tv, Bv; t)), \\
&\quad \frac{1}{2}(g(F(Su, Bv; t)) + g(F(Tu, Au; t)))\}] \\
&\leq \phi[\max\{g(z, z; t), g(F(z, z; t)), g(F(z, Bv; t)), \\
&\quad \frac{1}{2}(g(F(z, Bv; t)) + g(F(z, z; t)))\}] \\
&= \phi[\max\{0, 0, g(F(z, Bv; t)), \frac{1}{2}(g(F(z, Bv; t)) + 0)\}] \\
&\leq \phi(g(F(Bv, z; t))) \text{ for all } t > 0,
\end{aligned}$$

which implies that $g(F(Bv, z; t)) = 0$ for all $t > 0$ by Lemma 2.1. Therefore $Bv = Tv = z$. Since A and S are weakly compatible mappings, $ASz = SAz$ i.e. $Az = Sz$. Now we show that z is a fixed point of A . If $Az \neq z$, then by (iii), we have

$$\begin{aligned}
g(F(Az, z; t)) &= g(F(Az, Bv; t)) \leq \phi[\max\{g(F(Sz, Tv; t)), g(F(Sz, Az; t)), \\
&\quad g(F(Tv, Bv; t)), \frac{1}{2}(g(F(Sz, Bv)) + g(F(Tv, Az)))\}] \\
&\leq \phi[\max\{g(F(Az, z; t)), 0, 0, \frac{1}{2}(g(F(Az, z)) + g(F(z, Az)))\}] \\
&\leq \phi(g(F(Az, z; t))) \text{ for all } t > 0,
\end{aligned}$$

which implies that $g(F(Az, z; t)) = 0$ for all $t > 0$ by Lemma 2.1. Therefore $Az = z$. Hence $Az = Sz = z$.

Similarly, as B and T are weakly compatible mappings, we have $Bz = Tz = z$, since by (iii), we have

$$\begin{aligned}
g(F(z, Bz; t)) &= g(F(Az, Bz; t)) \leq \phi[\max\{g(F(Sz, Tz; t)), g(F(Sz, Az; t)), \\
&\quad g(F(Tz, Bz; t)), \frac{1}{2}(g(F(Sz, Bz)) + g(F(Tz, Az)))\}] \\
&\leq \phi[\max\{g(F(z, Bz; t)), 0, 0, \frac{1}{2}(g(F(z, Bz)) + g(F(Bz, z)))\}] \\
&\leq \phi(g(F(Bz, z; t))) \text{ for all } t > 0,
\end{aligned}$$

which implies that $g(F(Bz, z; t)) = 0$ for all $t > 0$ by Lemma 2.1. Therefore $Bz = z$. Hence $Bz = Tz = z$.

Thus $Az = Bz = Sz = Tz = z$, that is, z is a common fixed point of A, B, S and T .

Finally, in order to prove the uniqueness of z , suppose that w is another common fixed point of A, B, S and T . Then by (iii), we have

$$\begin{aligned}
g(F(z, w; t)) &= g(F(Az, Bw; t)) \leq \phi[\max\{g(F(Sz, Tw; t)), g(F(Sz, Az; t)), \\
&\quad g(F(Tw, Bw; t)), \frac{1}{2}(g(F(Sz, Bw; t)) + g(Tw, Az; t))\}] \\
&\leq \phi(g(F(z, w; t))) \text{ for all } t > 0,
\end{aligned}$$

which implies that $g(F(z, w; t)) = 0$ for all $t > 0$ by Lemma 2.1. Hence $z = w$. Therefore z is a unique common fixed point of A, B, S and T . ■

COROLLARY 3.1. Let $A, S, T : X \rightarrow X$ be the mappings satisfying

- (i) $A(X) \subseteq S(X) \cap T(X)$,
- (ii) the pairs $\{A, S\}$ and $\{A, T\}$ are weakly compatible and
- (iii) $g(F(Ax, Ay; t)) \leq \phi[\max\{g(F(Sx, Ty; t)), g(F(Sx, Ax; t)), g(F(Ty, Ay; t))$
 $\frac{1}{2}(g(F(Sx, Ay; t)) + g(F(Ty, Ax; t)))\}]$,

for every $x, y \in X$, where ϕ satisfies the condition (Φ) . Then A, S and T have a unique common fixed point in X .

COROLLARY 3.2. Let $A, S : X \rightarrow X$ be the mappings satisfying

- (i) $A(X) \subseteq S(X)$,
- (ii) the pair $\{A, S\}$ is weakly compatible and
- (iii) $g(F(Ax, Ay; t)) \leq \phi[\max\{g(F(Sx, Sy; t)), g(F(Sx, Ax; t)), g(F(Sy, Ay; t))$
 $\frac{1}{2}(g(F(Sx, Ay; t)) + g(F(Sy, Ax; t)))\}]$,

for every $x, y \in X$, where ϕ satisfies the condition (Φ) . Then A and S have a unique common fixed point in X .

We can also derive the following results from Theorem 3.1.

COROLLARY 3.3. Let S and T be two continuous self-maps of a complete N.A. Menger PM-space (X, F, Δ) . Let A be a self-map satisfying

- (i) $\{A, S\}$ and $\{A, T\}$ are pointwise R -weakly commuting and $A(X) \subseteq S(X) \cap T(X)$,
- (ii) $g(F(Ax, Ay; t)) \leq \phi[\max\{g(F(Sx, Ty; t)), g(F(Sx, Ax; t)), g(F(Sx, Ay; t)),$
 $g(F(Ty, Ay; t))\}]$,

for every $x, y \in X$, where ϕ satisfies the condition (Φ) . Then A, S and T have a unique common fixed point in X .

Taking $T = S$ in Corollary 3.3 we get the following corollary unifying Vasuki's theorem [20], which in turn also generalizes the result of Pant [15].

COROLLARY 3.4. Let (X, F, Δ) be a complete N.A. Menger PM-space and S be a continuous self-mapping of X . Let A be another self-mapping of X satisfying that

- (i) $\{A, S\}$ is R -weakly commuting with $A(X) \subseteq S(X)$,
- (ii) $g(F(Ax, Ay, a; t)) \leq \phi[\max\{g(F(Sx, Sy; t)), g(F(Sx, Ax; t)), g(F(Sx, Ay; t)),$
 $g(F(Sy, Ay; t))\}]$,

for each $x, y \in X$ and ϕ satisfies the condition (Φ) . Then A and S have a unique common fixed point.

REMARK 3.1. In Theorem 3.1, if S and T are continuous and pairs $\{A, S\}$ and $\{B, T\}$ are compatible instead of condition (ii), the theorem remains true.

REMARK 3.2. In our generalization the inequality condition (iii) satisfied by the mappings A, B, S and T is stronger than that of Theorem 2 of Khan and Sumitra [13] and Theorem 1.9 of Vasuki [20].

EXAMPLE 3.1. Let $X = R$ and $A, S, T: X \rightarrow X$ be mappings such that $S(x) = 2x - 1$,

$$T(x) = \begin{cases} -1 - x, & x < 0 \\ 2x - 1, & 0 \leq x < 1 \\ \frac{x+1}{2}, & x \geq 1 \end{cases} \quad \text{and} \quad A(x) = \begin{cases} 0, & x = -1 \\ x^2, & x \neq -1 \end{cases}$$

Then we see that

- (i) $\{A, S\}$ and $\{A, T\}$ are point-wise R-weakly commuting.
- (ii) $A(X) \subseteq S(X) \cap T(X)$.
- (iii) 1 is the unique common fixed point of A, S and T .
- (iv) $g(F(Ax, Ay; t)) \leq \phi[\max\{g(F(Sx, Ty; t)), g(F(Sx, Ax; t)), g(F(Sx, Ay; t)), g(F(Ty, Ay; t))\}]$, for every $x, y \in X$ is also true.

4. An application

THEOREM 4.1. Let (X, F, Δ) be a complete N. A. Menger PM-space and A, B, S and T be mappings from the product $X \times X$ to X such that

$$\begin{aligned} A(X \times \{y\}) &\subseteq T(X \times \{y\}), & B(X \times \{y\}) &\subseteq S(X \times \{y\}), \\ g(F(A(T(x, y), y), T(A(x, y), y); t)) &\leq g(F(A(x, y), T(x, y); t)), \\ g(F(B(S(x, y), y), S(B(x, y), y); t)) &\leq g(F(B(x, y), S(x, y); t)), \end{aligned} \quad (8)$$

for all $t > 0$. If S and T are continuous with respect to their direct argument and

$$\begin{aligned} g(F(A(x, y), B(x', y'); t)) &\leq \phi[\max\{g(F(S(x, y), T(x', y'); t)), \\ &g(F(S(x, y), A(x, y); t)), g(F(T(x', y'), B(x', y'); t)), \\ &\frac{1}{2}(g(F(S(x, y), B(x', y'); t)) + g(F(T(x', y'), A(x, y); t)))\}] \end{aligned} \quad (9)$$

for all $t > 0$ and x, y, x', y' in X , then there exists only one point b in X such that

$$A(b, y) = S(b, y) = B(b, y) = T(b, y) \quad \forall y \in X.$$

Proof. By (8) and (9),

$$\begin{aligned} g(F(A(x, y), B(x', y'); t)) &\leq \phi[\max\{g(F(S(x, y), T(x', y'); t)), \\ &g(F(S(x, y), A(x, y); t)), g(F(T(x', y'), B(x', y'); t)), \\ &\frac{1}{2}(g(F(S(x, y), B(x', y'); t)) + g(F(T(x', y'), A(x, y); t)))\}] \end{aligned}$$

for all $t > 0$, therefore by Theorem 3.1, for each y in X , there exists only one $x(y)$ in X such that

$$A(x(y), y) = S(x(y), y) = B(x(y), y) = T(x(y), y) = x(y),$$

for every y, y' in X and

$$\begin{aligned} g(F(x(y), x(y'); t)) &= g(F(A(x(y), y), A(x(y'), y'); t)) \\ &\leq \phi[\max\{g(F(A(x, y), A(x', y'); t)), g(F(A(x, y), A(x, y); t)), \\ &\quad g(F(T(x', y'), A(x', y'); t)), \\ &\quad \frac{1}{2}(g(F(A(x, y), A(x', y'); t)) + g(F(A(x', y'), A(x, y); t)))\}] \\ &= g(F(x(y), x(y'); t)). \end{aligned}$$

This implies that $x(y) = x(y')$ and hence $x(\cdot)$ is some constant $b \in X$ so that

$$A(b, y) = b = T(b, y) = S(b, y) = B(b, y) \quad \forall y \in X. \quad \blacksquare$$

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