

Related Fixed Point Theorems for Three Metric Spaces, II

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ABSTRACT. In this paper, we have proved some related fixed point theorems for three metric spaces which improve the results of Jain, Sahu and Fisher [2].

1. INTRODUCTION

The following fixed point theorem was proved by Jain, Sahu and Fisher [2].

Theorem 1. *Let (X, d) , (Y, ρ) and (Z, σ) be complete metric spaces. If T is continuous mapping of X into Y , S is a mapping of Y into Z and R is a mapping of Z into X satisfying the inequalities*

$$\begin{aligned}d(RSTx, RSTx') &\leq c \max \{d(x, x'), d(x, RSTx), d(x', RSTx'), \\&\quad \rho(Tx, Tx'), \sigma(STx, STx')\}, \\ \rho(TRSy, TRSy') &\leq c \max \{\rho(y, y'), \rho(y, TRSy), \rho(y', TRSy'), \\&\quad \sigma(sy, sy'), d(RSy, RSy')\}, \\ \sigma(STRz, STRz') &\leq c \max \{\sigma(z, z'), \sigma(z, STRz), \sigma(z', STRz') \\&\quad d(Rz, Rz'), \rho(TRz, TRz')\}\end{aligned}$$

for all x, x' in X , y, y' in Y and z, z' in Z , where $0 \leq c < 1$, then RST has a unique fixed point u in X , TRS has a unique fixed point v in Y and STR has a unique fixed point w in Z . Further, $Tu = v$, $Sv = w$, and $Rw = u$.

2. MAIN RESULTS

We now prove the following related fixed point theorem which improves Theorem 1.

2000 *Mathematics Subject Classification.* Primary: 54H25.

Key words and phrases. Complete metric space, compact metric space, related fixed point.

Theorem 2. Let (X, d) , (Y, ρ) and (Z, σ) be complete metric spaces. If T is continuous mapping of X into Y , S is a mapping of Y into Z and R is a mapping of Z into X satisfying the inequalities

$$(1) \quad \begin{aligned} d(RSTx, RSTx') \leq c \max \left\{ \frac{d(x, x')[1 + d(x, RSTx)]}{1 + d(x, x')}, \right. \\ \frac{d(x', RSTx)[1 + d(x, RSTx')]}{1 + d(x, x')}, \\ \left. \frac{d(x', RSTx')[1 + d(x, RSTx)]}{1 + d(x, x')}, \right. \\ \left. \rho(Tx, Tx'), \sigma(STx, STx') \right\}, \end{aligned}$$

$$(2) \quad \begin{aligned} \rho(TRSy, TRSy') \leq c \max \left\{ \frac{\rho(y, y')[1 + \rho(y, TRSy)]}{1 + \rho(y, y')}, \right. \\ \frac{\rho(y', TRSy)[1 + \rho(y, TRSy')]}{1 + \rho(y, y')}, \\ \left. \frac{\rho(y', TRSy')[1 + \rho(y, TRSy)]}{1 + \rho(y, y')}, \right. \\ \left. \sigma(Sy, Sy'), d(RSy, RSy') \right\}, \end{aligned}$$

$$(3) \quad \begin{aligned} \sigma(STRz, STRz') \leq c \max \left\{ \frac{\sigma(z, z')[1 + \sigma(z, STRz)]}{1 + \sigma(z, z')}, \right. \\ \frac{\sigma(z', STRz)[1 + \sigma(z, STRz')]}{1 + \sigma(z, z')}, \\ \left. \frac{\sigma(z', STRz')[1 + \sigma(z, STRz)]}{1 + \sigma(z, z')}, \right. \\ \left. d(Rz, Rz'), \rho(TRz, TRz') \right\} \end{aligned}$$

for all x, x' in X , y, y' in Y and z, z' in Z , where $0 \leq c < 1$, then RST has a unique fixed point u in X , TRS has a unique fixed point v in Y and STR has a unique fixed point w in Z . Further, $Tu = v$, $Sv = w$ and $Rw = u$.

Proof. Let x_0 be an arbitrary point in X . Define sequences $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ in X , Y and Z respectively by

$$x_n = (RST)^n x_0, \quad y_n = T x_{n-1}, \quad z_n = S y_n$$

for $n = 1, 2, \dots$

Applying inequality (2), we have

$$\begin{aligned}
 \rho(y_n, y_{n+1}) &= \rho(TRSy_{n-1}, TRSy_n) \\
 &\leq c \max \left\{ \frac{\rho(y_{n-1}, y_n)[1 + \rho(y_{n-1}, TRSy_{n-1})]}{1 + \rho(y_{n-1}, y_n)}, \right. \\
 &\quad \frac{\rho(y_n, TRSy_{n-1})[1 + \rho(y_{n-1}, TRSy_n)]}{1 + \rho(y_{n-1}, y_n)}, \\
 &\quad \frac{\rho(y_n, TRSy_n)[1 + \rho(y_{n-1}, TRSy_{n-1})]}{1 + \rho(y_{n-1}, y_n)}, \\
 &\quad \left. \sigma(Sy_{n-1}, Sy_n), d(RSy_{n-1}, RSy_n) \right\}, \\
 &\leq c \max \left\{ \rho(y_{n-1}, y_n), \sigma(z_{n-1}, z_n), d(x_{n-1}, x_n) \right\}.
 \end{aligned}
 \tag{4}$$

Using inequality (3), we have

$$\begin{aligned}
 \sigma(z_n, z_{n+1}) &= \sigma(STRz_{n-1}, STRz_n) \\
 &\leq c \max \left\{ \frac{\sigma(z_{n-1}, z_n)[1 + \sigma(z_{n-1}, STRz_{n-1})]}{1 + \sigma(z_{n-1}, z_n)}, \right. \\
 &\quad \frac{\sigma(z_n, STRz_{n-1})[1 + \sigma(z_{n-1}, STRz_n)]}{1 + \sigma(z_{n-1}, z_n)}, \\
 &\quad \frac{\sigma(z_n, STRz_n)[1 + \sigma(z_{n-1}, STRz_{n-1})]}{1 + \sigma(z_{n-1}, z_n)}, \\
 &\quad \left. d(Rz_{n-1}, Rz_n), \rho(TRz_{n-1}, TRz_n) \right\} \\
 &\leq c \max \left\{ \rho(y_{n-1}, y_n), \sigma(z_{n-1}, z_n), d(x_{n-1}, x_n) \right\},
 \end{aligned}
 \tag{5}$$

on using inequality (4).

Using inequality (1) we have

$$\begin{aligned}
 d(x_n, x_{n+1}) &= d(RSTx_{n-1}, RSTx_n) \\
 &\leq c \max \left\{ \rho(y_{n+1}, y_n), \sigma(z_{n+1}, z_n), d(x_{n+1}, x_n), d(x_{n-1}, x_n) \right\} \\
 &\leq c \max \left\{ \rho(y_{n-1}, y_n), \sigma(z_{n-1}, z_n), d(x_{n-1}, x_n) \right\},
 \end{aligned}
 \tag{6}$$

on using inequalities (4) and (5).

It follows easily by induction on using inequalities (4),(5) and (6) that

$$\begin{aligned}
 d(x_n, x_{n+1}) &\leq c^{n-1} \max \left\{ d(x_1, x_2), \rho(y_1, y_2), \sigma(z_1, z_2) \right\}, \\
 \rho(y_n, y_{n+1}) &\leq c^{n-1} \max \left\{ d(x_1, x_2), \rho(y_1, y_2), \sigma(z_1, z_2) \right\}, \\
 \sigma(z_n, z_{n+1}) &\leq c^{n-1} \max \left\{ d(x_1, x_2), \rho(y_1, y_2), \sigma(z_1, z_2) \right\}.
 \end{aligned}$$

Since $c < 1$, it follows that $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ are Cauchy sequences with limits u, v and w in X, Y and Z respectively.

Since T and S are continuous, we have

$$\begin{aligned}\lim_{n \rightarrow \infty} y_n &= \lim_{n \rightarrow \infty} Tx_n = Tu = v, \\ \lim_{n \rightarrow \infty} z_n &= \lim_{n \rightarrow \infty} Sy_n = Sv = w.\end{aligned}$$

Using inequality (1) again, we have

$$\begin{aligned}d(RSTu, x_n) &= d(RSTu, RSTx_{n-1}) \\ &\leq c \max \left\{ \frac{d(u, x_{n-1})[1 + d(u, RSTu)]}{1 + d(u, x_{n-1})}, \frac{d(x_{n-1}, RSTu)[1 + d(u, RSTx_{n-1})]}{1 + d(u, x_{n-1})}, \right. \\ &\quad \left. \frac{d(x_{n-1}, RSTx_{n-1})[1 + d(u, RSTu)]}{1 + d(u, x_{n-1})}, \rho(Tu, Tx_{n-1}), \sigma(STu, STx_{n-1}) \right\}, \\ &\leq c \max \left\{ \frac{d(u, x_{n-1})[1 + d(u, RSTu)]}{1 + d(u, x_{n-1})}, \frac{d(x_{n-1}, RSTu)[1 + d(u, x_n)]}{1 + d(u, x_{n-1})}, \right. \\ &\quad \left. \frac{d(x_{n-1}, x_n)[1 + d(u, RSTu)]}{1 + d(u, x_{n-1})}, \rho(Tu, Tx_{n-1}), \sigma(STu, STx_{n-1}) \right\}.\end{aligned}$$

Since S and T are continuous, it follows on letting $n \rightarrow \infty$ that

$$d(RSTu, u) \leq cd(RSTu, u).$$

Thus $RSTu = u$, since $c < 1$ and so u is a fixed point of RST .

We therefore have

$$TRSv = TRSTu = Tu = v$$

and so

$$STRw = STRSv = Sv = w.$$

Hence v and w are fixed points of TRS and STR respectively.

We now prove the uniqueness of the fixed point u . Suppose that RST has a second fixed point u' . Then using inequality (1), we have

$$\begin{aligned}d(u, u') &= d(RSTu, RSTu') \\ &\leq c \max \left\{ \frac{d(u, u')[1 + d(u, RSTu)]}{1 + d(u, u')}, \frac{d(u', RSTu)[1 + d(u, RSTu')]}{1 + d(u, u')}, \right. \\ &\quad \left. \frac{d(u', RSTu')[1 + d(u, RSTu)]}{1 + d(u, u')}, \rho(Tu, Tu'), \sigma(STu, STu') \right\}, \\ &\leq c \max \left\{ \frac{d(u, u')[1 + d(u, u)]}{1 + d(u, u')}, \frac{d(u', u)[1 + d(u, u')]}{1 + d(u, u')}, \right. \\ &\quad \left. \frac{d(u', u')[1 + d(u, u)]}{1 + d(u, u')}, \rho(Tu, Tu'), \sigma(STu, STu') \right\}, \\ &= c \max \left\{ \rho(Tu, Tu'), \sigma(STu, STu') \right\}.\end{aligned}$$

Further, using inequality (2), we have

$$\begin{aligned}
\rho(Tu, Tu') &= \rho(TRSTu, TRSTu') \\
&\leq c \max \left\{ \frac{\rho(Tu, Tu')[1 + \rho(Tu, TRSTu)]}{1 + \rho(Tu, Tu')}, \right. \\
&\quad \frac{\rho(Tu', TRSTu)[1 + \rho(Tu, TRSTu')]}{1 + \rho(Tu, Tu')}, \\
&\quad \frac{\rho(Tu', TRSTu')[1 + \rho(Tu, TRSTu)]}{1 + \rho(Tu, Tu')}, \\
&\quad \left. d(RSTu, RSTu'), \sigma(STu, STu') \right\}, \\
&\leq c \max \left\{ \frac{\rho(Tu, Tu')[1 + \rho(Tu, Tu)]}{1 + \rho(Tu, Tu')}, \frac{\rho(Tu', Tu)[1 + \rho(Tu, Tu')]}{1 + \rho(Tu, Tu')}, \right. \\
&\quad \left. \frac{\rho(Tu', Tu')[1 + \rho(Tu, Tu)]}{1 + \rho(Tu, Tu')}, d(u, u'), \sigma(STu, STu') \right\}, \\
&= c \max \{d(u, u'), \sigma(STu, STu')\}.
\end{aligned}$$

Hence we have

$$d(u, u') \leq c\sigma(STu, STu').$$

Finally, on using inequality (3), we have

$$\begin{aligned}
d(u, u') &\leq c\sigma(STu, STu') \\
&\leq c\sigma(STRSTu, STRSTu') \\
&\leq c^2 \max \left\{ \frac{\sigma(STu, STu')[1 + \sigma(STu, STRSTu)]}{1 + \sigma(STu, STu')}, \right. \\
&\quad \frac{\sigma(STu', STRSTu)[1 + \sigma(STu, STRSTu')]}{1 + \sigma(STu, STu')}, \\
&\quad \frac{\sigma(STu', STRSTu')[1 + \sigma(STu, STRSTu)]}{1 + \sigma(STu, STu')}, \\
&\quad \left. d(RSTu, RSTu'), \rho(TRSTu, TRSTu') \right\} \\
&= c^2 d(u, u').
\end{aligned}$$

Since $c < 1$, it follows that $u = u'$ and the uniqueness of u follows.

Similarly, it can be proved that v is the unique fixed point of TRS and w is the unique fixed point of STR .

We finally prove that we also have $Rw = u$. To do this, note that

$$Rw = R(STRw) = RST(Rw)$$

and so Rw is a fixed point of RST . Since u is the unique fixed point of RST , it follows that $Rw = u$. This completes the proof of the theorem. \square

We now prove an analogous result for compact metric spaces.

Theorem 3. *Let (X, d) , (Y, ρ) and (Z, σ) be compact metric spaces. If T is continuous mapping of X into Y , S is a continuous mapping of Y into Z and R is a continuous mapping of Z into X satisfying the inequalities*

$$(7) \quad \begin{aligned} & d(RSTx, RSTx') < \\ & < c \max \left\{ \frac{d(x, x')[1 + d(x, RSTx)]}{1 + d(x, x')}, \frac{d(x', RSTx)[1 + d(x, RSTx')]}{1 + d(x, x')}, \right. \\ & \quad \left. \frac{d(x', RSTx')[1 + d(x, RSTx)]}{1 + d(x, x')}, \rho(Tx, Tx'), \sigma(STx, STx') \right\}, \end{aligned}$$

$$(8) \quad \begin{aligned} & \rho(TRSy, TRSy') < \\ & < c \max \left\{ \frac{\rho(y, y')[1 + \rho(y, TRSy)]}{1 + \rho(y, y')}, \frac{\rho(y', TRSy)[1 + \rho(y, TRSy')]}{1 + \rho(y, y')}, \right. \\ & \quad \left. \frac{\rho(y', TRSy')[1 + \rho(y, TRSy)]}{1 + \rho(y, y')}, \sigma(Sy, Sy'), d(RSy, RSy') \right\}, \end{aligned}$$

$$(9) \quad \begin{aligned} & \sigma(STRz, STRz') < \\ & < c \max \left\{ \frac{\sigma(z, z')[1 + \sigma(z, STRz)]}{1 + \sigma(z, z')}, \frac{\sigma(z', STRz)[1 + \sigma(z, STRz')]}{1 + \sigma(z, z')}, \right. \\ & \quad \left. \frac{\sigma(z', STRz')[1 + \sigma(z, STRz)]}{1 + \sigma(z, z')}, d(Rz, Rz'), \rho(TRz, TRz') \right\} \end{aligned}$$

for all distinct x, x' in X , all distinct y, y' in Y and all distinct z, z' in Z . Then RST has a unique fixed point u in X , TRS has a unique fixed point v in Y and STR has a unique fixed point w in Z . Further, $Tu = v$, $Sv = w$ and $Rw = u$.

Proof. Let us denote the right-hand side of inequalities (7), (8) and (9) by $h(x, x')$, $k(y, y')$ and $p(z, z')$ respectively.

Suppose first of all that there exist u, u' in X such that $h(u, u') = 0$. Then it follows immediately that $u = u'$ and $RSTu = u$. Then on putting $Tu = v$, $Sv = w$, we have

$$\begin{aligned} Rsv = u & \Rightarrow TRSv = Tu = v, \\ STRSv = STRw = Sv = w & \Rightarrow Rsv = Rw = u. \end{aligned}$$

The result of the theorem therefore holds in this case.

Similarly, if there exist v, v' in Y such that $k(v, v') = 0$ or if there exist w, w' in Z such that $p(w, w') = 0$, then the results of the theorem also hold.

Now suppose that $h(x, x') \neq 0$ for all x, x' in X , $k(y, y') \neq 0$ for all y, y' in Y and $p(z, z') \neq 0$ for all z, z' in Z . Define the function f on X^2 by

$$f(x, x') = \frac{d(RSTx, RSTx')}{h(x, x')}.$$

Then f is continuous and since $X \times X$ is compact, f attains its maximum value c_1 . Because of inequality (7), $c_1 < 1$ and so

$$d(RSTx, RSTx') \leq c_1 h(x, x'),$$

for all x, x' in X .

Similarly, there exist $c_2, c_3 < 1$ such that

$$\rho(TRSy, TRSy') \leq c_2 k(y, y'),$$

for all y, y' in Y and

$$\sigma(STRz, STRz') \leq c_3 p(z, z'),$$

for all z, z' in Z . It follows that the conditions of Theorem 2 are satisfied with $c = \max(c_1, c_2, c_3)$ and so the results of the theorem are again satisfied.

The uniqueness of u, v , and w follows easily. \square

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