# Oscillation criteria for second-order delay dynamic equations with a sub-linear neutral term on time scales 

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#### Abstract

This paper addresses the oscillatory behavior of the solutions of second-order dynamic equations with a sublinear neutral term. Using Riccati transformation and comparison principles, we obtain new oscillation criteria. The obtained results essentially improve, complement, and simplify some of the previous ones in the literature. Some examples have been provided herein to illustrate our main results.


## 1. Introduction

The paper aims to study the oscillation problem of the class of second-order nonlinear dynamic equations with a sublinear neutral term

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) x^{\beta}(\delta(t))=0, \quad t \geq t_{0} \tag{1}
\end{equation*}
$$

where $z(t):=x(t)+p(t) x^{\alpha}(\tau(t))$. Throughout, the following assumptions are satisfied
(H1) $0<\alpha \leq 1, \beta$ are ratios of odd positive integers;
(H2) $r, p, q \in C_{r d}\left(\left[t_{0}, \infty\right)_{\mathbb{T}},[0, \infty)\right)$ and $q(t)$ is not eventually zero for sufficiently large $t$ and $\lim _{t \rightarrow \infty} p(t)=0$, $R(t)=\int_{t_{0}}^{t} \frac{\Delta s}{r(s)} ;$
(H3) $\tau, \delta \in C_{r d}\left(\left[t_{0}, \infty\right)_{\mathbb{T}}, \mathbb{T}\right), \tau(t) \leq t, \delta(t) \leq t$ and $\lim _{t \rightarrow \infty} \tau(t)=\lim _{t \rightarrow \infty} \delta(t)=\infty$.
Herein, we consider

$$
\begin{equation*}
\int_{t_{0}}^{\infty} \frac{\Delta s}{r(s)}=\infty \tag{2}
\end{equation*}
$$

By a solution of (1), we mean a function $x \in C_{r d}\left[T_{x}, \infty\right)_{\mathbb{T}}, T_{x} \in\left[t_{0}, \infty\right)_{\mathbb{T}}$ which has the property $r\left(z^{\Delta}\right) \in C_{r d}^{1}\left[T_{x}, \infty\right)_{\mathbb{T}}$ and satisfies (1) on $\left[T_{x}, \infty\right)_{\mathbb{T}}$. We consider only those solutions $x$ of (1) which satisfy $\sup |x(t)|: t \in\left[T_{x}, \infty\right)_{\mathbb{T}}>0$ for all $T \in\left[T_{x}, \infty\right)_{\mathbb{T}}$. We assume that (1) possesses such solutions. A solution of

[^0](1) is called oscillatory if it is neither eventually positive nor eventually negative; otherwise, it is termed nonoscillatory. Dynamic equations on time scales have an enormous potential for applications fields such as in biology, engineering, economics, physics, neural networks, and social sciences [6].

Within the final two decades, there are numerous thinks about studying oscillatory behavior of solutions of nonlinear neutral delay dynamic equations, see $[2-4,14,18,19,22]$. However, we have relatively fewer results in the literature for dynamic equations with a sublinear neutral term. Dzurina et al.. [9] studied the oscillation of second-order difference equation with several sublinear neutral terms of the following form:

$$
\left(a(t) z^{\prime}(t)\right)^{\prime}+q(t) x^{\beta}(\sigma(t))=0, \quad t \geq t_{0}>0
$$

where $m>0$ is an integer, $z(t)=x(t)+\sum_{i=1}^{m} p_{i}(t) x^{\alpha_{i}}\left(\tau_{i}(t)\right)$.
In [21] Sivaraj et al. established adequate conditions for the oscillation of all solutions of a nonlinear differential equations

$$
\left(a(t)\left(x(t)+p(t) x^{\alpha}(\tau(t))\right)^{\prime}\right)^{\prime}+q(t) x^{\beta}(\sigma(t))=0, \quad t \geqslant t_{0}
$$

where $\alpha$ and $\beta$ are ratio of odd positive integers.
In [8], Dharuman et al.obtained the oscillation criteria of the solution of a particular case for (1) when $\mathbb{T}=\mathbb{Z}$

$$
\Delta\left(a_{n} \Delta\left(x_{n}+p_{n} x_{n-k}^{\alpha}\right)\right)+q_{n} x_{n+1-l}^{\beta}=0, n \geq n_{0}
$$

where $0<\alpha \leq 1, \beta$ are ratio of odd positive integers.
Recently, Soliman et al.[20] established the sufficient conditions for the oscillatory behavior of solutions of (1), under the conditions either

$$
\int_{t_{0}}^{\infty} \frac{1}{r(s)} \Delta s=\infty, \quad \text { or } \quad \int_{t_{0}}^{\infty} \frac{1}{r(s)} \Delta s<\infty
$$

Indeed, equation (1) has numerous applications in mathematical, theoretical, and chemical material science; for example, it appears in a variety of real-world issues such as in the study of $p$-Laplace equations non-Newtonian fluid theory, the turbulentflow of a polytrophic gas in a porous medium, and so on. As a result, there has been a lot of research activity concerning oscillatory behavior of various classes of differential equations. We refer the reader to [1,5,15-17]. See also [11] and [10] for models from mathematical biology formulated by PDE's.

This study aims to unify and continue further investigation of the oscillation criteria of (1). The obtained results are appropriate for non-neutral differential and difference equations $(p(t)=0)$. We present a more general study than those previously reported in the literature in a manner such that we cover all possible cases for (1) (Sublinear case, superlinear case and linear case).

## 2. Preliminary Lemmas

In this section, we state and demonstrate some preparatory lemmas that are crucial to prove the main results obtained herein.

Lemma 2.1. [12] If $a$ and $b$ are nonnegative, then

$$
\begin{equation*}
a^{\alpha} b^{1-\alpha} \leq \alpha a+(1-\alpha) b \quad \text { for } 0<\alpha \leq 1 \tag{3}
\end{equation*}
$$

where equality holds if and only if $a=b$.
Theorem 2.2. [7] Assume that $v: \mathbb{T} \rightarrow \mathbb{R}$ is strictly increasing and $\tilde{\mathbb{T}}:=v(\mathbb{T})$ is a time scale. Let $y: \tilde{\mathbb{T}} \rightarrow \mathbb{R}$. If $y^{\tilde{\Delta}}(v(t))$ and $v^{\Delta}(t)$ exist for $t \in \mathbb{T}^{\kappa}$, then

$$
(y \circ v)^{\Delta}(t)=y^{\tilde{\Delta}}(v(t)) v^{\Delta}(t)
$$

Where $\tilde{\Delta}$ denotes to the derivative on $\tilde{\mathbb{T}}$.

Lemma 2.3. Let (H1)-(H3) and (2) hold. If $x(t)$ be an eventually positive solution of $(1)$, then $z(t)$ satisfies
(I) $z(t)>0, z^{\Delta}(t)>0$, and $\left(r(t) z^{\Delta}(t)\right)^{\Delta}<0, t \geq t_{1} \geq t_{0}$,
(II) $\frac{z(t)}{R(t)}$ is decreasing for $t \geq t_{1}$.

Proof. As $x$ is an eventually positive solution of (1), then by (H2) and (H3) there exists $t_{1} \in\left[t_{0}, \infty\right)_{\mathbb{T}}$ such that $x(t)>0, x(\delta(t))>0$ and $x(\tau(t))>0$ for all $t \in\left[t_{0}, \infty\right)_{\mathbb{T}}$. Now, from (1) we have

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta} \leq-q(t) x^{\beta}(\delta(t)) \tag{4}
\end{equation*}
$$

Hence $\left(r(t) z^{\Delta}(t)\right)$ is a nonincreasing function and is eventually of one sign. Claim that $z^{\Delta}(t)>0$ for all $t \in\left[t_{1}, \infty\right)_{\mathbb{T}}$. If not, then there exists $t_{2} \in\left[t_{1}, \infty\right)_{\mathbb{T}}$ such that $z^{\Delta}(t) \leq 0$ for all $t_{2} \in\left[t_{1}, \infty\right)_{\mathbb{T}}$. Since $q$ not identically equal to zero eventually, we may assume that $z^{\Delta}(t)<0$ for all $t \in\left[t_{2}, \infty\right)_{\mathbb{T}}$. From (4), we have

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right) \leq-c<0, \quad \text { for all } t \in\left[t_{2}, \infty\right)_{\mathbb{T}} \tag{5}
\end{equation*}
$$

where $c:=\left(r\left(t_{2}\right) z^{\Delta}\left(t_{2}\right)\right)>0$, then

$$
\begin{equation*}
z^{\Delta}(t) \leq \frac{-c}{r(t)} \tag{6}
\end{equation*}
$$

Integrate (6) on $\left[t_{2}, t\right) \subset\left[t_{2}, \infty\right)_{\mathbb{T}}$, we obtain

$$
\begin{equation*}
z(t) \leq z\left(t_{2}\right)-c \int_{t_{2}}^{t} \frac{\Delta s}{r(s)} \text { for all } t \in\left[t_{2}, \infty\right)_{\mathbb{T}} \tag{7}
\end{equation*}
$$

Letting $t \rightarrow \infty$, then it follows from (2) that $\lim _{t \rightarrow \infty} z(t)=-\infty$, which is a inconsistency. Then

$$
z(t)>0, z^{\Delta}(t)>0, \text { and }\left(r(t) z^{\Delta}(t)\right)^{\Delta}<0, \quad t \geq t_{1} \geq t_{0}
$$

To prove (II), since (I)holds, then for sufficiently large $t_{1}$

$$
\begin{aligned}
z(t) & \geq z\left(t_{1}\right)+\int_{t_{1}}^{t} \frac{r(s) z^{\Delta}(s)}{r(s)} \Delta s \\
& \geq r(t) R(t) z^{\Delta}(t)
\end{aligned}
$$

Moreover, using the previous inequality, we get

$$
\left(\frac{z(t)}{R(t)}\right)^{\Delta}=\frac{z^{\Delta}(t) R(t)-r^{-1}(t) z(t)}{R(t) R(\sigma(t))} \leq \frac{r(t) z^{\Delta}(t) R(t)-z(t)}{r(t) R(t) R(\sigma(t))} \leq 0
$$

This implies that $\frac{z(t)}{R(t)}$ is decreasing for $t \geq t_{1}$, thereby completes the proof.
Lemma 2.4. Let (H1)-(H3) and (2) hold. Assume $x(t)$ be an eventually positive solution of $(1)$, such that $z(t)$ satisfied (I) of Lemma 2.1. If

$$
\begin{equation*}
\int_{t_{0}}^{\infty}\left(\frac{1}{r(u)} \int_{t_{0}}^{u} q(s) \Delta s\right) \Delta u=\infty \tag{8}
\end{equation*}
$$

Then $z(t) \rightarrow \infty$ as $t \rightarrow \infty$.

Proof. Assume that $x(t)$ be a nonoscillatory solution of (1) on $\left[t_{0}, \infty\right)_{\mathbb{T}}$ such that $x(t)>0, x(\tau(t))>0$, and $x(\delta(t))>0$ for $t \in\left[t_{1}, \infty\right)_{\mathbb{T}}$. We claim that (8) guarantees that $z(t) \rightarrow \infty$ as $t \rightarrow \infty$, since $z(t)$ is a positively increasing function; therefore there exists a constant $k>0$ such that

$$
\begin{equation*}
z(t) \geq k>0, \quad \text { for } t \geq t_{1} \tag{9}
\end{equation*}
$$

Besides, it follows from the definition of $z(t)$ that

$$
\begin{aligned}
x(t) & =z(t)-p(t) x^{\alpha}(\tau(t)) \\
& \geq z(t)-p(t) z^{\alpha}(\tau(t))
\end{aligned}
$$

Applying (3), we get

$$
\begin{align*}
x(t) & \geq z(t)-p(t)(\alpha z(t)+(1-\alpha)) \\
& \geq z(t)\left(1-\alpha p(t)-\frac{p(t)}{z(t)}(1-\alpha)\right) . \tag{10}
\end{align*}
$$

Substituting (9) into (10), we get

$$
\begin{equation*}
x(t) \geq k\left(1-\alpha p(t)-\frac{p(t)}{z(t)}(1-\alpha)\right) . \tag{11}
\end{equation*}
$$

Considering (H2) , we obtain

$$
\begin{equation*}
x(t) \geq k>0, \quad t \geq t_{1} . \tag{12}
\end{equation*}
$$

Integrate (1) from $t$ to $t$ using (12), we obtain

$$
\begin{equation*}
z^{\Delta}(t) \geq \frac{k^{\beta}}{r(t)} \int_{t_{1}}^{t} q(s) \Delta s \tag{13}
\end{equation*}
$$

Integrate (13) from $t_{1}$ to $t$, we conclude

$$
\begin{equation*}
z(t) \geq z\left(t_{1}\right)+k^{\beta} \int_{t_{1}}^{t} \frac{1}{r(s)} \int_{t_{1}}^{t} q(s) \Delta s \Delta u . \tag{14}
\end{equation*}
$$

In view of (8), we conclude that $z(t) \rightarrow \infty$ as $t \rightarrow \infty$, thereby the proof is complete.

## 3. Main Results

In this section, we state and prove new oscillation criteria for Eq.(1), and we present oscillation criteria for the case when (1) is super-linear

Theorem 3.1. Assume that $\beta>1$, (H1) - (H3) and (8) hold, and $\delta^{\Delta}>0$. If there exists a function $\varphi(t) \in$ $C_{r d}^{1}\left(\left[t_{0}, \infty\right) \mathbb{T},(0, \infty)\right)$, such that for sufficiently large $t_{2} \geq t_{1}$,

$$
\begin{equation*}
\limsup _{t \rightarrow \infty}\left[\int_{t_{0}}^{t}\left(\xi^{\beta} \varphi(s) q(s)-\frac{\left(\varphi^{\Delta}(s)\right)^{2} r(\delta(\sigma(s)))}{4 \varphi(s) \delta^{\Delta}(s)}\right) \Delta s\right]=\infty, \tag{15}
\end{equation*}
$$

holds for $\xi \in(0,1)$, then (1) is oscillatory.

Proof. Assume that $x(t)$ be a nonoscillatory solution of (1) on $\left[t_{0}, \infty\right)_{\mathbb{T}}$ such that $x(t)>0, x(\tau(t))>0$, and $x(\delta(t))>0$ for $t \in\left[t_{1}, \infty\right)_{\mathbb{T}}$. From properties of $p(t)$ and $z(t)$, one can see for $\epsilon \in(0,1)$ that

$$
\begin{equation*}
\alpha p(t)+\frac{p(t)}{z(t)}(1-\alpha)<\epsilon \tag{16}
\end{equation*}
$$

This combined with (10) provides

$$
\begin{equation*}
x(t) \geq \xi z(t) \tag{17}
\end{equation*}
$$

where $\xi=(1-\epsilon) \in(0,1)$. Substituting (17) into (1), we have

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) \xi^{\beta} z^{\beta}(\delta(t)) \leq 0 \tag{18}
\end{equation*}
$$

Using (8) it follows that $z(t) \rightarrow \infty$ as $t \rightarrow \infty$ and for $\beta>1$, we have

$$
z^{\beta}(\delta(t)) \geq z(\delta(t))
$$

This combined with (18) provides

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) \xi^{\beta} z(\delta(t)) \leq 0, \quad t \geq t_{2} \tag{19}
\end{equation*}
$$

Defining the function

$$
\begin{equation*}
\omega(t)=\varphi(t) \frac{r(t) z^{\Delta}(t)}{z(\delta(t))}, \quad t \geq t_{2} \tag{20}
\end{equation*}
$$

It is clear that $w(t)>0$ for $t \geq t_{2}$ and

$$
\begin{align*}
\omega^{\Delta}(t) & =\varphi^{\Delta}(t) \frac{r(\sigma(t)) z^{\Delta}(\sigma(t))}{z(\delta(\sigma(t)))}+\varphi(t)\left(\frac{r(t) z^{\Delta}(t)}{z(\delta(t))}\right)^{\Delta} \\
& =\varphi^{\Delta}(t) \frac{r(\sigma(t)) z^{\Delta}(\sigma(t))}{z(\delta(\sigma(t)))}+\varphi(t) \frac{\left[r(t) z^{\Delta}(t)\right]^{\Delta}}{z(\delta(t))}+\varphi(t) r(\sigma(t)) z^{\Delta}(\sigma(t))\left(\frac{1}{z(\delta(t))}\right)^{\Delta} \\
& \leq-\xi^{\beta} \varphi(t) q(t)+\frac{\varphi^{\Delta}(t)}{\varphi(\sigma(t))} \omega(\sigma(t))-\frac{\varphi(t) r(\sigma(t)) z^{\Delta}(\sigma(t)) z^{\Delta}(\delta(t)) \delta^{\Delta}(t)}{z(\delta(t)) z(\delta(\sigma(t)))} \tag{21}
\end{align*}
$$

Since $z^{\Delta}(t)>0, \delta^{\Delta}(t)>0$ and $\left(r(t) z^{\Delta}(t)\right)$ is non increasing, we get

$$
\begin{align*}
\omega^{\Delta}(t) & \leq-\xi^{\beta} \varphi(t) q(t)+\frac{\varphi^{\Delta}(t)}{\varphi(\sigma(t))} \omega(\sigma(t))-\frac{\varphi(t)\left[r(\sigma(t)) z^{\Delta}(\sigma(t))\right]^{2} \delta^{\Delta}(t)}{r(\delta(\sigma(t))) z^{2}(\delta(\sigma(t)))} \\
& \leq-\xi^{\beta} \varphi(t) q(t)+\frac{\varphi^{\Delta}(t)}{\varphi(\sigma(t))} \omega(\sigma(t))-\frac{\varphi(t) \delta^{\Delta}(t)}{\varphi^{2}(\sigma(t)) r(\delta(\sigma(t)))} \omega^{2}(\sigma(t)) \tag{22}
\end{align*}
$$

Completing squares, we get

$$
\begin{align*}
\omega^{\Delta}(t) \leq & -\xi^{\beta} \varphi(t) q(t) \\
& -\frac{\varphi(t) \delta^{\Delta}(t)}{\varphi^{2}(\sigma(t)) r(\delta(\sigma(t)))}\left[\left(\omega(\sigma(t))-\frac{\varphi^{\Delta}(t) r(\delta(\sigma(t))) \varphi(\sigma(t))}{2 \varphi(t) \delta^{\Delta}(t)}\right)^{2}-\left(\frac{\varphi^{\Delta}(t) r(\delta(\sigma(t))) \varphi(\sigma(t))}{2 \varphi(t) \delta^{\Delta}(t)}\right)^{2}\right] \\
\leq & -\xi^{\beta} \varphi(t) q(t)+\frac{\left(\varphi^{\Delta}(t)\right)^{2} r(\delta(\sigma(t)))}{4 \varphi(t) \delta^{\Delta}(t)} . \tag{23}
\end{align*}
$$

Integrating (23) from $t_{2}$ to $t$, we get

$$
\int_{t_{2}}^{t}\left(\xi^{\beta} \varphi(s) q(s)-\frac{\left(\varphi^{\Delta}(s)\right)^{2} r(\delta(\sigma(s)))}{4 \varphi(s) \delta^{\Delta}(s)}\right) \Delta s \leq \omega\left(t_{2}\right) .
$$

Taking limsup $\operatorname{sim}_{t \rightarrow \infty}$, we get a inconsistency with (15). This completes the proof.

The following oscillation results cover the case when (1) is linear.
From Theorem3.1, one can immediately obtain the following oscillation results when $\beta=1$.
Theorem 3.2. Assume that $\beta=1,(H 1)-(H 3)$ and (8) hold, and $\delta^{\Delta}>0$. If there exists a function $\varphi(t) \in$ $C_{r d}^{1}\left(\left[t_{0}, \infty\right)_{\mathbb{T}},(0, \infty)\right)$, such that for sufficiently large $t_{2} \geq t_{1}$,

$$
\begin{equation*}
\limsup _{t \rightarrow \infty}\left[\int_{t_{2}}^{t}\left(\xi \varphi(s) q(s)-\frac{\left(\varphi^{\Delta}(s)\right)^{2} r(\delta(\sigma(s)))}{4 \varphi(s) \delta^{\Delta}(s)}\right) \Delta s\right]=\infty, \tag{24}
\end{equation*}
$$

holds for $\xi \in(0,1)$, then $(1)$ is oscillatory.
In the following, we use the comparison theorem to establish new oscillation criteria for the linear case of (1).

Theorem 3.3. Assume that for sufficient large $t \in\left[t_{0}, \infty\right)_{\mathbb{T}}$, (2) holds if the first-order dynamic equation

$$
\begin{equation*}
u^{\Delta}(t)+\xi q(t) R(\delta(t)) u(\delta(t))=0 \tag{25}
\end{equation*}
$$

oscillatory, then (1) is also oscillatory.
Proof. Suppose that (1) has a nonoscillatory solution $x(t)$ on $\left[t_{0}, \infty\right)_{\mathbb{T}}$. Without loss of generality, we may assume that there exists a $t_{1} \geq t_{0}$ such that $x(t)>0, x(\tau(t))>0$, and $x(\delta(t))>0$, for $t \geq t_{1}$. From (1) and condition (2) we obtain the following for $t \geq t_{1}$,

$$
\begin{equation*}
z(\delta(t))=z\left(t_{1}\right)+\int_{t_{1}}^{\delta(t)} \frac{r(s) z^{\Delta}(s)}{r(s)} \Delta s \geq r(\delta(t)) z^{\Delta}(\delta(t)) R(\delta(t)) \tag{26}
\end{equation*}
$$

As the same Proceeding in the proof of Theorem 3.1, we get

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) \xi z(\delta(t)) \leq 0, \quad t \geq t_{2} \tag{27}
\end{equation*}
$$

This combined with (26) provides

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+\xi q(t) R(\delta(t)) r(\delta(t)) z^{\Delta}(\delta(t)) \leq 0, \quad t \geq t_{2} \tag{28}
\end{equation*}
$$

Defining $u(t):=r(t) z^{\Delta}(t)>00$ and combining this with (28) provides

$$
\begin{equation*}
u^{\Delta}(t)+\xi q(t) R(\delta(t)) u(\delta(t)) \leq 0, \quad t \geq t_{2} \tag{29}
\end{equation*}
$$

where $u:=r(t) z^{\Delta}(t)$, is a positive solution of the first order delay dynamic inequality (29). By [ [13] ,Theorem 3.1], equation (25) also presents a nonoscillatory solution. This contradiction proves that (1) is oscillatory.

In view of Theorem3.3 and [Theorem 1, Theorem 2, [13]].
Corollary 3.4. Let $\delta^{\sigma}(t) \leq t$ and $\delta^{\Delta}(t) \geq 0$, if

$$
\begin{equation*}
\limsup _{t \rightarrow \infty}\left(\frac{\int_{\delta(t)}^{\sigma(t)} \xi q(s) R(\delta(s)) \Delta s}{1-[1-\xi \mu(\delta(t)) q(\delta(t)) R(\delta(\delta(t)))] \xi \mu(\sigma(t)) q(\sigma(t)) R(\delta(\sigma(t)))}\right)>1, \tag{30}
\end{equation*}
$$

holds for $\xi \in(0,1)$, then every solution of $(1)$ is oscillatory.
The following theorem presents oscillation criteria when (1) is sub-linear.

Theorem 3.5. Assume that $0<\beta<1$, (H1) - (H3) and (8) hold, and $\delta^{\Delta}>0$. If there exists a function $\varphi(t) \in$ $C_{r d}^{1}\left(\left[t_{0}, \infty\right)_{\mathbb{T}},(0, \infty)\right)$, such that for sufficiently large $t_{2} \geq t_{1}$,

$$
\begin{equation*}
\limsup _{t \rightarrow \infty}\left[\int_{t_{2}}^{t}\left(\xi^{\beta} R^{\beta-1}(\delta(s)) K^{\beta-1} q(s) \varphi(s)-\frac{\left(\varphi^{\Delta}(s)\right)^{2} r(\delta(\sigma(s)))}{4 \varphi(s) \delta^{\Delta}(s)}\right) \Delta s\right] \Delta s=\infty \tag{31}
\end{equation*}
$$

holds for $\xi \in(0,1)$, then (1) is oscillatory.
Proof. Let $x(t)$ be a nonoscillatory solution of (1) on $\left[t_{0}, \infty\right)_{\mathbb{T}}$ such that $x(t)>0, x(\tau(t))>0$, and $x(\delta(t))>0$ for $t \in\left[t_{1}, \infty\right)_{\mathbb{T}}$. Using the proof of Theorem 3.1. We rewrite (18) as

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) \xi^{\beta} R^{\beta-1}(\delta(t)) \frac{z^{\beta-1}(\delta(t))}{R^{\beta-1}(\delta(t))} z(\delta(t)) \leq 0, \quad t \geq t_{2} \geq t_{1} \tag{32}
\end{equation*}
$$

As $\frac{z(t)}{R(t)}$ is decreasing, there exists a constant $K>0$ such that

$$
\begin{equation*}
\frac{z(t)}{R(t)} \leq K, \quad t \geq t_{2} \geq t_{1} \tag{33}
\end{equation*}
$$

Using (33) and $\beta<1$, then (32) takes the form

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) \xi^{\beta} R^{\beta-1}(\delta(t)) K^{\beta-1} z(\delta(t)) \leq 0, \quad t \geq t_{2} \geq t_{1} \tag{34}
\end{equation*}
$$

Use the definition of $\omega(t)$ in (20). Using the proof of Theorem 3.1, we get

$$
\omega^{\Delta}(t) \leq-\xi^{\beta} R^{\beta-1}(\delta(t)) K^{\beta-1} q(t) \varphi(t)+\frac{\left(\varphi^{\Delta}(t)\right)^{2} r(\delta(\sigma(t)))}{4 \varphi(t) \delta^{\Delta}(t)}
$$

Integrating (??) from $t_{2}$ to $t$, we get

$$
\int_{t_{2}}^{t}\left(\xi^{\beta} R^{\beta-1}(\delta(s)) K^{\beta-1} q(s) \varphi(s)-\frac{\left(\varphi^{\Delta}(s)\right)^{2} r(\delta(\sigma(s)))}{4 \varphi(s) \delta^{\Delta}(s)}\right) \Delta s \leq \omega\left(t_{2}\right)
$$

Considering limsup $\operatorname{sum}_{t \rightarrow \infty}$, we obtain a contradiction with (31). This completes the proof .
Now, we use comparison theorem to establish an oscillation criteria in the case of $0<\beta<1$.
Theorem 3.6. Assume that for sufficient large $t \in\left[t_{0}, \infty\right)_{\mathbb{T}}$, (2) holds if the first order dynamic equation

$$
\begin{equation*}
u^{\Delta}(t)+q(t) \xi^{\beta} R^{\beta}(\delta(t)) K^{\beta-1} u(\delta(t))=0 \tag{35}
\end{equation*}
$$

oscillatory, then (1) is also oscillatory.
Proof. Suppose that (1) has a nonoscillatory solution $x(t)$ on $\left[t_{0}, \infty\right)_{\mathbb{T}}$. Without loss of generality, we may assume that there exists a $t_{1} \geq t_{0}$ such that $x(t)>0, x(\tau(t))>0$, and $x(\delta(t))>0$, for $t \geq t_{1}$. From (1) and condition (2) we obtain the following for $t \geq t_{1}$,

$$
\begin{equation*}
z(\delta(t))=z\left(t_{1}\right)+\int_{t_{1}}^{\delta(t)} \frac{r(s) z^{\Delta}(s)}{r(s)} \Delta s \geq r(\delta(t)) z^{\Delta}(\delta(t)) R(\delta(t)) \tag{36}
\end{equation*}
$$

Using the proof of Theorem 3.5, we get

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) \xi^{\beta} R^{\beta-1}(\delta(t)) K^{\beta-1} z(\delta(t)) \leq 0, \quad t \geq t_{2} \tag{37}
\end{equation*}
$$

Combining this with (36) provides

$$
\begin{equation*}
\left(r(t) z^{\Delta}(t)\right)^{\Delta}+q(t) \xi^{\beta} R^{\beta}(\delta(t)) K^{\beta-1} r(\delta(t)) z^{\Delta}(\delta(t)) \leq 0, \quad t \geq t_{2} \tag{38}
\end{equation*}
$$

Defining $u(t):=r(t) z^{\Delta}(t)>0$, and combining this with (38) provides

$$
\begin{equation*}
u^{\Delta}(t)+q(t) \xi^{\beta} R^{\beta}(\delta(t)) K^{\beta-1} u(\delta(t)) \leq 0, \quad t \geq t_{2} \tag{39}
\end{equation*}
$$

where $u(t):=r(t) z^{\Delta}(t)$, is a positive solution of the first order delay dynamic inequality (39). By [ [13] ,Theorem 3.1], equation (35) also presents a nonoscillatory solution. This contradiction proves that (1) is oscillatory.

Example 3.7. Assume $\mathbb{T}=\mathbb{R}$. Consider the second-order neutral differential equation

$$
\begin{equation*}
\left(t\left(x(t)+\frac{1}{t} x^{1 / 3}(\eta t)\right)^{\prime}\right)^{\prime}+\gamma x^{3}(\lambda t)=0, \quad t \geq 1 \tag{40}
\end{equation*}
$$

Where $\eta, \lambda \in(0,1]$. Here $\alpha=1 / 3, \beta=3, p(t)=\frac{1}{t}, q(t)=\gamma, \tau(t)=\eta t, \delta(t)=\lambda t$ and $r(t)=t$. It is clear that conditions (2) and (8) are satisfied. By using Theorem 3.1 with $\varphi(t)=t$, we have

$$
\begin{aligned}
\limsup _{t \rightarrow \infty}\left[\int_{t_{0}}^{t}\left(\xi^{\beta} \varphi(s) q(s)-\frac{\left(\varphi^{\Delta}(s)\right)^{2} r(\delta(\sigma(s)))}{4 \varphi(s) \delta^{\Delta}(s)}\right) \Delta s\right] & =\limsup _{t \rightarrow \infty}\left[\int_{t_{0}}^{t}\left(\xi^{3} \gamma s-\frac{1}{4}\right) d s\right] \\
& =\infty
\end{aligned}
$$

For $\xi \in(0,1)$, it is clear that (40) satisfied the condition of Theorem 3.1, then equation (40) is oscillatory for all $\gamma>0$.
Example 3.8. Assume that $\mathbb{T}=\mathbb{R}$. Consider the second-order neutral differential equation

$$
\begin{equation*}
\left(x(t)+\frac{p_{0}}{t^{1-\alpha}} x^{\alpha}(\tau(t))\right)^{\prime \prime}+\frac{q_{0}}{t^{\beta+1}} x^{\beta}(\lambda t)=0, \quad t>0 \tag{41}
\end{equation*}
$$

Where $0<\alpha \leq 1, p(t)=\frac{p_{0}}{t^{1-\alpha}}, q(t)=\frac{q_{0}}{t^{\beta+1}}, \tau(t) \leq t, \delta(t)=\lambda t$ and $r(t)=1$. Here, we have three possible cases $0<\beta<1$, $\beta=1$ and $\beta>1$. In the case of $\beta=1, E q$.(41) takes the from

$$
\left(x(t)+\frac{p_{0}}{t^{1-\alpha}} x^{\alpha}(\tau(t))\right)^{\prime \prime}+\frac{q_{0}}{t^{2}} x(\lambda t)=0
$$

Applying corollary 3.4 and take in your account that for $\mathbb{T}=\mathbb{R} ; \sigma(t)=t$ and $\mu(t)=0$. It follows that condition (30) becomes

$$
\begin{aligned}
\limsup _{t \rightarrow \infty}\left(\int_{\delta(t)}^{\sigma(t)} \xi q(s) R(\delta(s)) d s\right) & =\limsup _{t \rightarrow \infty}\left(\int_{\lambda t}^{t} \frac{\xi q_{0}}{s^{2}}(\lambda s) d s\right) \\
& =\xi q_{0}(\ln (t)-\ln (\lambda t)) \\
& =\xi q_{0} \ln \left(\frac{1}{\lambda}\right)
\end{aligned}
$$

Hence, for $\beta=1$ Eq.(41) is oscillatory for $q_{0}>\frac{1}{\xi \ln \left(\frac{1}{\lambda}\right)}$.
Consider $\beta>1$, it is clear that conditions (2) and (8) are satisfied. By using Theorem 3.1 with $\varphi(t)=t^{\beta}$, we have

$$
\begin{aligned}
\limsup _{t \rightarrow \infty}\left[\int_{t_{0}}^{t}\left(\xi^{\beta} \varphi(s) q(s)-\frac{\left(\varphi^{\Delta}(s)\right)^{2} r(\delta(\sigma(s)))}{4 \varphi(s) \delta^{\Delta}(s)}\right) \Delta s\right] & =\underset{t \rightarrow \infty}{\limsup }\left[\int_{t_{0}}^{t}\left(\frac{\xi^{\beta}}{s}-\frac{\beta^{2} s^{2 \beta-2}}{4 s^{\beta} \lambda}\right) d s\right] \\
& =\infty
\end{aligned}
$$

It is clear that (41) satisfied the condition of Corollary 3.1, then equation (41) is oscillatory.
Finally consider $0<\beta<1$. Applying Theorem 3.5, we have $R(t)=t$ and

$$
\limsup _{t \rightarrow \infty}\left[\int_{t_{0}}^{t}\left(\xi^{\beta} \lambda^{\beta-1}(s)^{\beta-1} K^{\beta-1} \frac{q_{0}}{s^{\beta+1}}(s)-\frac{1}{4 \lambda s}\right) d s\right]=\left(\xi^{\beta} \lambda^{\beta-1} K^{\beta-1} q_{0}-\frac{1}{4 \lambda}\right) \ln (t)
$$

Hence (41) is oscillatory when $q_{0}>\frac{1}{4 \xi^{\beta} \lambda^{\beta} K^{\beta-1}}$.
As a special case of (41), consider $\beta=\alpha=1 / 3$ and $\tau(t)=\delta(t)=1 / 2 ;$ Eq.(41) takes the form

$$
\begin{equation*}
\left(x(t)+\frac{1}{t} x^{1 / 3}\left(\frac{t}{2}\right)\right)^{\prime \prime}+\frac{q_{0}}{t^{4 / 3}} x^{1 / 3}\left(\frac{t}{2}\right)=0 \tag{42}
\end{equation*}
$$

It follows that (42) oscillates when $q_{0}>\frac{K^{2 / 3}}{2^{5 / 3} \xi^{1 / 3}}$. By choosing small values of $K$ and $\xi=0.9$, the criteria for oscillation of this equation consistent with the results of [20]

## Example 3.9. [8] Assume $\mathbb{T}=\mathbb{Z}$. Consider the second order neutral difference equation

$$
\begin{equation*}
\Delta\left((n+1) \Delta\left(x_{n}+\frac{1}{n} x_{n-2}^{1 / 3}\right)\right)+\left(4 n+10+\frac{2 n+1}{n(n+1)}\right) x_{n-3}^{3}=0, \quad n \geq 1 \tag{43}
\end{equation*}
$$

Here $\alpha=1 / 3, \beta=3, r_{n}=n+1, p_{n}=\frac{1}{n}, q_{n}=4 n+10+\frac{2 n+1}{n(n+1)}, \tau_{n}=n-2, \delta_{n}=n-3,$. It is clear that conditions (2) and (8) are satisfied. By using Theorem 3.1; take $\varphi_{n}=n$, then condition (15) that becomes

$$
\limsup _{n \rightarrow \infty}\left[\sum_{s=1}^{n} \xi^{3}\left(4 s+10+\frac{2 s+1}{s(s+1)}\right)\right]=\infty .
$$

Therefore, it is Clear that (43) satisfied the condition of Theorem 3.1, then equation (43) is oscillatory.

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