# A Study of Second Order Semilinear Elliptic Pde Involving Measures 

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#### Abstract

The objective of this article is to study the boundary value problem for the general semilinear elliptic equation of second order involving $L^{1}$ functions or Radon measures with finite total variation. The study investigates the existence and uniqueness of 'very weak' solutions to the boundary value problem for a given $L^{1}$ function. However, a 'very weak' solution need not exist when an $L^{1}$ function is replaced with a measure due to which the corresponding reduced limits has been found for which the problem admits a solution in a 'very weak' sense.


## 1. Introduction and preliminaries

Solving PDEs with $L^{1}$ functions or measures as data became very fashionable in the modern theory of PDEs. The motivation for studying such problems have been discussed beautifully by Brezis in the preface of [16]. One of the most important example where the measure data arise naturally in the nonlinear PDE enters from the heat generation. Heat generation from the exothermic reaction driven by the Arrhenius reaction-term with the pre-exponential factor of the Transition state theory [18] can be presented by the semilinear elliptic PDE with nonlinear term given by

$$
k(u)=c_{1} u \exp \left(-\frac{c_{2}}{u}\right) \text { for } u>0
$$

where $c_{1}, c_{2}>0$ are the parameters. Here the function $u$ represents the thermodynamic temperature of this model. For the analytical treatment, define $k(0):=0$ and consider an odd extension of the function $k$ by inserting an absolute value $|u|$, i.e.

$$
k(u)=c_{1} u \exp \left(-\frac{c_{2}}{|u|}\right) .
$$

Then the heat generation can be described by the following PDE involving measure

$$
\begin{align*}
-\Delta u & =\lambda k(u)+\mu \text { in } \Omega \\
u & =0 \text { on } \partial \Omega . \tag{1}
\end{align*}
$$

We remark that for example heating of the substance at one single point by laser can be expressed by taking $\mu:=\delta_{x_{0}}$ being the Dirac measure concentrated at point $x_{0} \in \Omega$ [17]. The PDEs involving measures also have

[^0]an important role in the theory of probability and in the use of probabilistic methods [3] which gives a new strength to the whole subjects in the recent years.

In the present article, we are concerned with the boundary value problems for the general second order semilinear elliptic equation involving measures of finite total variation. Problems of this type, involving elliptic operators modeled upon the Laplacian or the $p$-Laplacian, have been systematically studied in the literature, starting with the papers $[13,14]$, where measure on the right-hand side are considered. Contribution to this topic can be found in [1], [2], [4] and the references therein. In all these articles the elliptic operator which has been considered are either the Laplacian or the $p$-Laplacian. In 2004, Veron[15] studied the elliptic PDE involving measures where a general linear second order elliptic operator with variable coefficients is appeared, which is precisely the following

$$
\begin{align*}
-L u & =\lambda \text { in } \Omega, \\
u & =\mu \text { on } \partial \Omega, \tag{2}
\end{align*}
$$

where $\Omega$ is a smooth domain in $\mathbb{R}^{N}, L$ is a general linear elliptic operator of second order, $\lambda$ and $\mu$ are Radon measures, respectively in $\Omega$ and $\partial \Omega$. Motivated by the interest shared by the mathematical community in this topic, we study here the existence and uniqueness of solutions to the following Dirichlet problem of the form

$$
\begin{align*}
-L u+g \circ u & =\mu \text { in } \Omega  \tag{3}\\
u & =v \text { on } \partial \Omega
\end{align*}
$$

where, $\Omega$ is a bounded domain in $\mathbb{R}^{N}$ with $C^{2}$ boundary $\partial \Omega, L$ is a linear second order differential operator in divergence form, given by

$$
\begin{equation*}
L u=\sum_{i, j=1}^{N} \frac{\partial}{\partial x_{i}}\left(a_{i j}(x) \frac{\partial u}{\partial x_{j}}\right)-\sum_{j=1}^{N} b_{j}(x) \frac{\partial u}{\partial x_{j}}+\sum_{j=1}^{N} \frac{\partial\left(c_{j}(x) u\right)}{\partial x_{j}}-d u, \tag{4}
\end{equation*}
$$

where the functions $a_{i j}, b_{j}, c_{j}$ and $d$ are Lipschitz continuous in $\Omega$ and the principle part of $L$ satisfies the uniform ellipticity condition,

$$
\begin{equation*}
\sum_{i, j=1}^{N} a_{i j}(x) \xi_{i} \xi_{j} \geq \alpha \sum_{i=1}^{N} \xi_{i}^{2}, \forall \xi=\left(\xi_{1}, \xi_{2}, \cdots, \xi_{N}\right) \in \mathbb{R}^{N} \tag{5}
\end{equation*}
$$

for almost all $x \in \Omega$ with $\alpha>0$ and the input data $\mu, v$ are supposed to be Radon measures over $\Omega, \partial \Omega$ respectively and $g$ is a given nonlinear function defined on $\Omega \times \mathbb{R}$ with $g \circ u(x)=g(x, u(x))$. We also assume the following conditions on $g$ :
(a) $g(x, \cdot) \in C(\mathbb{R}), \quad g(x, 0)=0$,
(b) $g(x, \cdot)$ is non decreasing,
(c) $g(\cdot, t) \in L^{1}(\Omega, \rho)$,
where $L^{1}(\Omega, \rho)$ denotes the weighted Lebesgue space with the weight $\rho(x)=\operatorname{dist}(x, \partial \Omega)$ for $x \in \bar{\Omega}$. The family of functions satisfying (6), will be denoted by $\mathscr{G}_{0}$. Observe that if $g \in \mathscr{G}_{0}$, then the function $g^{*}$ given by $g^{*}(x, t)=-g(x,-t)$ is also in $\mathscr{G}_{0}$. Some examples of the nonlinear function $g(x, u(x))$ are the following: $|u|^{q}$ for $q \geq 1, e^{a u}-1$ where $a>0, e^{-k / \rho}|u|^{q-1} u$ where $k \geq 0 \& q>1, \rho(x)^{\alpha}|u|^{q} \operatorname{sign}(u)$ where $\alpha>-2 \& q>1$, $\rho(x)^{\alpha}|u|^{q-1} u$ for $q>1$ etc.
If $L$ is defined by (4), then its adjoint operator $L^{*}$ is given by

$$
\begin{equation*}
L^{*} \varphi=\sum_{i, j=1}^{N} \frac{\partial}{\partial x_{j}}\left(a_{i j} \frac{\partial \varphi}{\partial x_{i}}\right)-\sum_{j=1}^{N} c_{j} \frac{\partial \varphi}{\partial x_{j}}+\sum_{j=1}^{N} \frac{\partial}{\partial x_{j}}\left(b_{j} \varphi\right)-d \varphi \tag{7}
\end{equation*}
$$

We assume an important uniqueness condition, symmetric in the $b_{j}$ and $c_{j}$, is the following

$$
\begin{equation*}
\int_{\Omega}\left(d v+\sum_{j=1}^{N} \frac{1}{2}\left(b_{j}+c_{j}\right) \frac{\partial v}{\partial x_{j}}\right) d x \geq 0, \quad \forall v \in C_{c}^{1}(\Omega), v \geq 0 \tag{8}
\end{equation*}
$$

Under the assumption that the coefficients $a_{i j}, b_{j}, c_{j}$ and $d$ are bounded and measurable in $\Omega$, the uniform ellipticity condition (5), and the uniqueness condition (8), the two operators $L$ and $L^{*}$ define an isomorphism between $W_{0}^{1,2}(\Omega)$ and $W^{-1,2}(\Omega)$. Through out this paper, we assume for the operator $L$, the functions $a_{i j}, b_{j}$, $c_{j}$ and $d$ are Lipschitz continuous functions in $\Omega$, the uniform ellipticity condition (5) and the uniqueness condition (8) holds.

Not many evidences are found in the literature which addresses the problem of existence of a solution to the equation (3) with measure data and hence the reader is suggested to refer to Brezis [5] which is one of the earliest attempts made in studying the non-linear equations with measure data. In fact, he considered the equation of the type

$$
\begin{align*}
-\Delta u+|u|^{p-1} u & =f(x) \text { in } \Omega  \tag{9}\\
u & =0 \text { on } \partial \Omega
\end{align*}
$$

where $\Omega \subset \mathbb{R}^{N}$ and $0 \in \Omega$ with $f$ a given function in $L^{1}(\Omega)$ or a measure. A detailed study of non-linear elliptic partial differential equations of the above type with measures can be found in Brezis et al [6]. Here they have introduced the notion of 'reduced limit'. Readers will perhaps often need to refer to Marcus and Véron [12] for its richness in addressing problems concerning the existence of a solution to the nonlinear, second order elliptic equations involving measures. Some other pioneering contribution to nonlinear problems with $L^{1}$ data or measure data which is worth mentioning are due to Brezis \& Strauss [7], Marcus \& Ponce [11], Bhakta and Marcus [10] and the references therein. The present work in this article draws its motivation from Marcus \& Ponce [11] and Bhakta and Marcus [10] in which they have considered the problem (3) for $L=\Delta$, with data $(\mu, 0)$ and $(0, v)$ respectively. In this article we address the problem for a general linear, second order, elliptic differential operator $L$ and also with input data $(\mu, v)$. For an general elliptic operator $L$, things become more complicated if the associated adjoint is not self adjoint.

We now begin our approach to the problem (3) by defining some of the notations and the definitions which will be quintessential to our study. We denote $\mathfrak{M}(\Omega)$ to be the space of finite Borel measures endowed with the norm $\|\mu\|_{\mathfrak{M}(\Omega)}=\int_{\Omega} d|\mu|$. The measure space $\mathfrak{M}(\Omega)$ is the dual of

$$
C_{0}(\bar{\Omega})=\{f \in C(\bar{\Omega}): f=0 \text { on } \partial \Omega\} .
$$

Similarly, we denote $\mathfrak{M}(\partial \Omega)$ to be the space of bounded Borel measures on $\partial \Omega$ with the usual total variation norm.

Definition 1.1. Let $\left\{\mu_{n}\right\}$ be a bounded sequence of measures in $\mathfrak{M}(\Omega)$. We say that $\left\{\mu_{n}\right\}$ converges weakly in $\Omega$ to a measure $\tau \in \mathfrak{M}(\Omega)$ if $\left\{\mu_{n}\right\}$ converges weakly to $\tau$ in $\mathfrak{M}(\Omega)$, i.e.

$$
\int_{\Omega} \varphi d \mu_{n} \rightarrow \int_{\Omega} \varphi d \tau ; \forall \varphi \in C_{0}(\bar{\Omega}) .
$$

We denote this convergence by $\mu_{n} \underset{\Omega}{\stackrel{\rightharpoonup}{\Omega}} \tau$.
We denote by $\mathfrak{M}(\Omega, \rho)$, the space of signed Radon measures $\mu$ in $\Omega$ such that $\rho \mu \in \mathfrak{M}(\Omega)$. The norm of a measure $\mu \in \mathfrak{M}(\Omega, \rho)$ is given by $\|\mu\|_{\Omega, \rho}=\int_{\Omega} \rho d|\mu|$. This space is the dual of

$$
C_{0}(\bar{\Omega}, \rho)=\left\{h \in C_{0}(\bar{\Omega}): \frac{h}{\rho} \in C_{0}(\bar{\Omega})\right\}
$$

where $\frac{h}{\rho} \in C_{0}(\bar{\Omega})$ means $\frac{h}{\rho}$ has a continuous extension to $\bar{\Omega}$, which is zero on $\partial \Omega$.

Definition 1.2. A sequence $\left\{\mu_{n}\right\}$ in $\mathfrak{M}(\Omega, \rho)$ converges 'weakly' to $\mu \in \mathfrak{M}(\Omega, \rho)$ if

$$
\int_{\Omega} f d \mu_{n} \rightarrow \int_{\Omega} f d \mu ; \forall f \in C_{0}(\bar{\Omega}, \rho) .
$$

The weak convergence in this sense is equivalent to the weak convergence $\rho \mu_{n} \rightharpoonup \rho \mu$ in $\mathfrak{M}(\Omega)$. For this and other properties of weak convergence of measures we refer to the textbook [12]. In this article, we consider the problem (3) with $\mu \in \mathfrak{M}(\Omega, \rho)$ and $v \in \mathfrak{M}(\partial \Omega)$.
The following two definitions of convergence are due to Bhakta and Marcus [10] which are relevant to our study.

Definition 1.3. Let $\left\{\mu_{n}\right\}$ be a bounded sequence of measures in $\mathfrak{M}(\Omega, \rho)$ and $\rho \mu_{n}$ is extended to a Borel measure $\left(\mu_{n}\right)_{\rho} \in \mathfrak{M}(\bar{\Omega})$ defined as zero on $\partial \Omega$. We say that $\left\{\rho \mu_{n}\right\}$ converge weakly in $\bar{\Omega}$ to a measure $\tau \in \mathfrak{M}(\bar{\Omega})$ if $\left\{\left(\mu_{n}\right)_{\rho}\right\}$ converges weakly to $\tau$ in $\mathfrak{M}(\bar{\Omega})$, i.e.

$$
\int_{\Omega} \varphi \rho d \mu_{n} \rightarrow \int_{\bar{\Omega}} \varphi d \tau ; \forall \varphi \in C(\bar{\Omega})
$$

We denote this convergence by $\rho \mu_{n} \underset{\Omega}{\longrightarrow} \tau$.
Definition 1.4. Let $\left\{\mu_{n}\right\}$ be a sequence in $\mathfrak{M}_{\text {loc }}(\Omega)$, the space of measures $\mu$ on

$$
\mathfrak{B}_{c}=\{E \Subset \Omega: E \text { Borel }\}
$$

such that $\mu \chi_{K}$ is a finite measure for every compact subset $K \subset \Omega$. We say that $\left\{\mu_{n}\right\}$ converges weakly to $\mu \in \mathfrak{M}_{\text {loc }}(\Omega)$ if it convergence in the sense of distribution, i.e.

$$
\int_{\Omega} \varphi d \mu_{n} \rightarrow \int_{\Omega} \varphi d \mu ; \forall \varphi \in C_{c}(\Omega) .
$$

We denote this convergence by $\mu_{n} \underset{d}{\rightharpoonup} \mu$.
Remark 1.5. It can be seen that if $\rho \mu_{n} \underset{\Omega}{\rightharpoonup} \tau$ then $\mu_{n} \underset{d}{ } \mu_{\text {int }}:=\frac{\tau}{\rho} \chi_{\Omega}$. Thus $\tau$ as in the definition $1.3, \tau=\tau \chi_{\partial \Omega}+\rho \mu_{\text {int }}$.
Let us now come back to our considered semilinear elliptic boundary problem involving measures. Here we will study the existence and uniqueness of 'very weak solution' for the problem (3). The main reason for attempting the very weak solution instead of weak solution for the problem (3) comes from the following fact. There are many simple linear elliptic PDEs of second order with $L^{1}$ data or measure data on smooth domain $\Omega \subset \mathbb{R}^{N}$ for which very weak solutions exists but not weak solutions. For example consider Brezis' problem [8], i.e. Poission equations $-\Delta u=f$ in $\Omega$, under the homogeneous Dirichlet boundary conditions $u=0$ on $\partial \Omega$ for a right hand side $f \in L^{1}(\Omega, \rho)$. In this Poission problem, for every $f \in L^{1}(\Omega, \rho)$, existence and uniqueness of a very weak solution $u \in L^{1}(\Omega)$ satisfying

$$
-\int_{\Omega} u \Delta v d x=\int_{\Omega} f v d x
$$

for all $v \in C^{2}(\bar{\Omega})$ with $v=0$ on $\partial \Omega$ is known, but there exists smooth domain $\Omega$ and right hand side function $f \in L^{1}(\Omega, \rho), f \notin L^{1}(\Omega)$ such that very weak solution $u$ does not have a weak derivative $\nabla u \in L^{1}(\Omega)$, i.e. $u \notin W^{1,1}(\Omega)$ and hence is not a weak solution. Thus such a weakening the notion of strong solution is necessary for our considered problem.
Definition 1.6. We will define $u \in L^{1}(\Omega)$ to be a 'very weak solution' of the problem (3), if $g \circ u \in L^{1}(\Omega, \rho)$ and $u$ satisfies the following

$$
\begin{equation*}
\int_{\Omega}\left(-u L^{*} \varphi+(g \circ u) \varphi\right) d x=\int_{\Omega} \varphi d \mu-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d v, \forall \varphi \in C_{c}^{2, L}(\bar{\Omega}) \tag{10}
\end{equation*}
$$

where

$$
C_{c}^{2, L}(\bar{\Omega}):=\left\{\varphi \in C^{2}(\bar{\Omega}): \varphi=0 \text { on } \partial \Omega \text { and } L^{*} \varphi \in L^{\infty}(\Omega)\right\} .
$$

and $\frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}}=\sum_{i, j=1}^{N} a_{i j} \frac{\partial \varphi}{\partial x_{i}} \mathbf{n}_{j}, \mathbf{n}_{j}$ 's are being the component of the outward normal unit vector $\mathbf{n}$ to $\partial \Omega$.
Notice that the co-normal derivative on the boundary following $L^{*}, \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}}$ can be written as

$$
\begin{equation*}
\frac{\partial \varphi}{\partial n_{L^{*}}}=\nabla \varphi A \cdot \mathbf{n}=\nabla \varphi \cdot \mathbf{n} A^{T} \tag{11}
\end{equation*}
$$

where the matrix $A$ is given by $A=\left(a_{i j}\right)_{N \times N}$ which corresponds to the principle part of the elliptic differential operator $L$. By the uniform ellipticity condition (5), we have $\mathbf{n} \cdot \mathbf{n} A^{T}>0$.
The most important thing here is that the problem may or may not posses a solution in the very weak sense for every measure. Such an example can be found in Brezis [5]. Hence the concept of a 'good measure' was introduced in the literature, which is defined as follows.

Definition 1.7. We denote by $\mathfrak{M}^{g}(\bar{\Omega})$ the set of pairs of measures $(\mu, v) \in \mathfrak{M}(\Omega, \rho) \times \mathfrak{M}(\partial \Omega)$ for which the boundary value problem (3) possesses a solution in very weak sense. If $(\mu, v) \in \mathfrak{M}^{g}(\bar{\Omega})$, we call $(\mu, v)$ is a pair of good measures.

### 1.1. Reduced limit

Let $\left\{\mu_{n}\right\}$ and $\left\{v_{n}\right\}$ be sequences of measures in $\mathfrak{M}(\Omega, \rho)$ and $\mathfrak{M}(\partial \Omega)$ respectively. Assume that there exists a solution $u_{n}$ of the problem (3) with data $\left(\mu_{n}, v_{n}\right)$, i.e. $u_{n}$ satisfies the equation (10) with $\mu=\mu_{n}$ and $v=v_{n}$. Further assume that the sequences of measures converge in a weak sense to $\mu$ and $v$ respectively while the sequence of very weak solutions $\left\{u_{n}\right\}$ converges to $u$ in $L^{1}(\Omega)$. In general $u$ is not a very weak solution to the boundary value problem (3) with data $(\mu, v)$. However if there exists measures $\left(\mu^{\#}, v^{\#}\right)$ such that $u$ is a very weak solution of the boundary value problem (3) with this data, then the pair $\left(\mu^{\#}, v^{\#}\right)$ is called the 'reduced limit' of the sequence $\left\{\mu_{n}, v_{n}\right\}$. The notion of 'reduced limit' was introduced by Brezis et al. [6] for $L=-\Delta$. The 'reduced measure' as defined by Brezis et al [6] is the largest good measure $\leq \mu$ for a Laplacian. In short, the job of a reduced limit of a sequence of measures is to characterize the class of measures to which the problem has a solution. Here in this work, our main aim is to determined the reduced limit corresponding to our problem (3).

We will use here a well known variational technique to show existence of solution in $W_{0}^{1,2}(\Omega)=$ $\left\{v \in L^{2}(\Omega): \nabla v \in L^{2}(\Omega),\left.v\right|_{\partial \Omega}=0\right\}$ with the Sobolev Norm $\|v\|_{1,2}=\left(\int_{\Omega}|\nabla v|^{2} d x\right)^{\frac{1}{2}}$. Now let us define $\langle u, v\rangle=\int_{\Omega} \sum_{i, j=1}^{n} a_{i j} u_{x_{i}} v_{x_{j}}$ over $W_{0}^{1,2}(\Omega)$. Then the uniform ellipticity condition (5), implies that $<,>$ is an inner product on $W_{0}^{1,2}(\Omega)$. It can be seen that the norm $\|u\|=\langle u, u\rangle^{1 / 2}$ is equivalent to the Sobolev norm of $W_{0}^{1,2}(\Omega)$. This norm equivalence will be effectively used in the manuscript. The manuscript has been organized into three sections. In Section 2, we begin by studying the semilinear boundary value problem with $L^{1}$ data and show certain basic lemmas and existence theorems. In Section 3, we continue the study by considering the semilinear problem with measure data and determines the reduced limit corresponding to the problem.

## 2. Semilinear problem with $L^{1}$ data

In this section we consider the nonlinear boundary value problem with $L^{1}$ data which is as follows

$$
\begin{align*}
-L u+g \circ u & =f \text { in } \Omega \\
u & =\eta \text { on } \partial \Omega . \tag{12}
\end{align*}
$$

Here $g \in \mathscr{G}_{0}, f \in L^{1}(\Omega, \rho)$ and $\eta \in L^{1}(\partial \Omega)$.
Now we have the following result due to Theorem 2.4, [15].

Lemma 2.1. Let $f \in L^{1}(\Omega, \rho)$ and $\eta \in L^{1}(\partial \Omega)$. Then there exists a unique very weak solution $u \in L^{1}(\Omega)$ to the problem

$$
\begin{align*}
-L u & =f \text { in } \Omega \\
u & =\eta \text { on } \partial \Omega . \tag{13}
\end{align*}
$$

Furthermore, for any $\varphi \in C_{c}^{2, L}(\bar{\Omega}), \varphi \geq 0$, there holds

$$
-\int_{\Omega} u_{+} L^{*} \varphi d x \leq \int_{\Omega} f\left(s i g n_{+} u\right) \varphi d x-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d v_{+}
$$

and

$$
-\int_{\Omega}|u| L^{*} \varphi d x \leq \int_{\Omega} f(\operatorname{sign} u) \varphi d x-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d|v| .
$$

Lemma 2.2. If $u_{i} \in L^{1}(\Omega)$ are very weak solutions of (12) corresponding to $f=f_{i}, \eta=\eta_{i}$ for $i=1$, 2 ; then we have the following estimate

$$
\begin{equation*}
\left\|u_{1}-u_{2}\right\|_{L^{1}(\Omega)}+\left\|g \circ u_{1}-g \circ u_{2}\right\|_{L^{1}(\Omega, p)} \leq C\left(\left\|f_{1}-f_{2}\right\|_{L^{1}(\Omega, \rho)}+\left\|\eta_{1}-\eta_{2}\right\|_{L^{1}(\partial \Omega)}\right) \tag{14}
\end{equation*}
$$

for some $C>0$.
Proof. Since $u_{1}, u_{2}$ are very weak solutions of (12), then we have

$$
-\int_{\Omega} u_{i} L^{*} \varphi d x+\int_{\Omega}\left(g \circ u_{i}\right) \varphi d x=\int_{\Omega} f_{i} \varphi d x-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d \eta_{i}
$$

for all $\varphi \in C_{c}^{2, L}(\bar{\Omega}), i=1,2$. Consequently,

$$
-\int_{\Omega}\left(u_{1}-u_{2}\right) L^{*} \varphi d x+\int_{\Omega}\left(g \circ u_{1}-g \circ u_{2}\right) \varphi d x=\int_{\Omega}\left(f_{1}-f_{2}\right) \varphi d x-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d\left(\eta_{1}-\eta_{2}\right)
$$

for all $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. This implies that $u_{1}-u_{2}$ is a very weak solution of

$$
\begin{align*}
-L u & =f_{1}-f_{2}-g \circ u_{1}+g \circ u_{2} \quad \text { in } \Omega,  \tag{15}\\
u & =\eta_{1}-\eta_{2} \text { on } \partial \Omega .
\end{align*}
$$

Therefore, by Lemma 2.1, for any $\varphi \in C_{c}^{2, L}(\bar{\Omega}), \varphi \geq 0$

$$
\begin{equation*}
-\int_{\Omega}\left|u_{1}-u_{2}\right| L^{*} \varphi d x \leq \int_{\Omega}\left(f_{1}-f_{2}-g \circ u_{1}+g \circ u_{2}\right) \operatorname{sign}\left(u_{1}-u_{2}\right) \varphi d x-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d\left|\eta_{1}-\eta_{2}\right| \tag{16}
\end{equation*}
$$

Let $\varphi_{0}$ be the test function satisfying

$$
\begin{align*}
-L^{*} \varphi & =1
\end{align*} \quad \text { in } \Omega,
$$

Existence of solution of the PDE (17) is guaranteed by the Lemma 2.1 in [15]. Since the coefficients of $L$ are Lipschtiz continuous, from [15] we have $\varphi_{0} \in C_{c}^{2}(\bar{\Omega})$ and $L^{*} \varphi_{0} \in L^{\infty}(\Omega)$, hence $\varphi_{0} \in C_{c}^{2, L}(\bar{\Omega})$. It can be seen that $\varphi_{0}>0$ in $\Omega$. This is due to a result in Theorem 2.11, [15] that there exists $\lambda>0$ such that $0<\lambda G_{-\Delta}^{\Omega}<G_{L^{*}}^{\Omega}<\lambda^{-1} G_{-\Delta^{\prime}}^{\Omega}$ where $G_{-\Delta^{\prime}}^{\Omega} G_{L^{*}}^{\Omega}$ in $\Omega \times \Omega \backslash D_{\Omega}$ are the Green's function of $-\Delta, L^{*}$ respectively and $D_{\Omega}=\{(x, x): x \in \Omega\}$. Since from Zhao [19], $G_{-\Delta}^{\Omega}(x, y)>0$, hence we have $\int_{\Omega} G_{-\Delta}^{\Omega}(x, y) d y>0$. It is easy to see that the integral $\int_{\Omega} G_{-\Delta}^{\Omega}(x, y) d y$ is finite. Further, there exists $c>0$ such that $c^{-1}<\frac{\varphi_{0}}{\rho}<c$ in $\Omega$ since $\frac{\varphi_{0}}{\rho}$ can be continuously extended to $\partial \Omega$ as $\left.\frac{\varphi_{0}}{\rho}\right|_{\partial \Omega}=-\frac{\partial \varphi_{0}}{\partial \mathbf{n}_{L^{*}}} \cdot \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}}$ (refer Corollary 3.13) where $-\frac{\partial \varphi_{0}}{\partial \mathbf{n}_{L^{*}}}$ is bounded
by the Hopf's lemma (refer Theorem 2.13, [15]) and $\frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}}$ is bounded by the uniform ellipticity condition (5). Therefore, taking $\varphi=\varphi_{0}$ as a test function in (16), we obtain

$$
\int_{\Omega}\left|u_{1}-u_{2}\right| d x \leq \int_{\Omega}\left(f_{1}-f_{2}\right) \varphi_{0} \operatorname{sign}\left(u_{1}-u_{2}\right) d x+\int_{\Omega}\left(-g \circ u_{1}+g \circ u_{2}\right) \operatorname{sign}\left(u_{1}-u_{2}\right) \varphi_{0} d x-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d\left|\eta_{1}-\eta_{2}\right|
$$

This implies that

$$
\left\|u_{1}-u_{2}\right\|_{L^{1}(\Omega)}+\int_{\Omega}\left(g \circ u_{1}-g \circ u_{2}\right) \operatorname{sign}\left(u_{1}-u_{2}\right) \varphi_{0} d x \leq \int_{\Omega}\left(f_{1}-f_{2}\right) \varphi_{0} \operatorname{sign}\left(u_{1}-u_{2}\right) d x-\int_{\partial \Omega} \frac{\partial \varphi_{0}}{\partial \mathbf{n}_{L^{*}}} d\left|\eta_{1}-\eta_{2}\right|
$$

By the property of $g$, we have $\left(g \circ u_{1}-g \circ u_{2}\right) \operatorname{sign}\left(u_{1}-u_{2}\right)=\left|g \circ u_{1}-g \circ u_{2}\right|$. Thus from the above equation it follows that

$$
\begin{align*}
c_{3}\left(\left\|u_{1}-u_{2}\right\|_{L^{1}(\Omega)}\right. & \left.+\int_{\Omega}\left|g \circ u_{1}-g \circ u_{2}\right| \cdot \rho d x\right) \\
& \leq\left\|u_{1}-u_{2}\right\|_{L^{1}(\Omega)}+\int_{\Omega}\left|g \circ u_{1}-g \circ u_{2}\right| \cdot \frac{\varphi_{0}}{\rho} \rho d x \\
& \leq \int_{\Omega}\left(f_{1}-f_{2}\right) \varphi_{0} \operatorname{sign}\left(u_{1}-u_{2}\right) d x+c_{0}\left\|\eta_{1}-\eta_{2}\right\|_{L^{1}(\partial \Omega)} \\
& \leq c \int_{\Omega}\left|f_{1}-f_{2}\right| \rho d x+c_{0}\left\|\eta_{1}-\eta_{2}\right\|_{L^{1}(\partial \Omega)} \tag{18}
\end{align*}
$$

We thus have the result

$$
\left\|u_{1}-u_{2}\right\|_{L^{1}(\Omega)}+\left\|g \circ u_{1}-g \circ u_{2}\right\|_{L^{1}(\Omega ; \rho)} \leq C\left(\left\|f_{1}-f_{2}\right\|_{L^{1}(\Omega ; \rho)}+\left\|\eta_{1}-\eta_{2}\right\|_{L^{1}(\partial \Omega)}\right),
$$

if $C$ is chosen to be $\max \left\{c / c_{3}, c_{0} / c_{3}\right\}$ where $c_{3}=\min \left\{1, c^{-1}\right\}$.
This also implies that if $u \in L^{1}(\Omega)$ is a very weak solution of the boundary value problem (12), then

$$
\begin{equation*}
\|u\|_{L^{1}(\Omega)}+\|g \circ u\|_{L^{1}(\Omega ; \rho)} \leq C\left(\|f\|_{L^{1}(\Omega ; \rho)}+\|\eta\|_{L^{1}(\partial \Omega)}\right) \tag{19}
\end{equation*}
$$

for some $C>0$.
Lemma 2.3. (Comparison of solutions) Let $u_{1}$ and $u_{2}$ be very weak solutions in $L^{1}(\Omega)$ of the boundary value problem (12) corresponding to $f=f_{1}, \eta=\eta_{1}$ and $f=f_{2}, \eta=\eta_{2}$ respectively. If $f_{1} \leq f_{2}$ and $\eta_{1} \leq \eta_{2}$, then $u_{1} \leq u_{2}$ a.e. in $\Omega$.

Proof. By Lemma 2.2, $u_{1}-u_{2}$ is a weak solution of the problem (15). Applying Lemma 2.1 with $\varphi=\varphi_{0}$, where $\varphi_{0}$ is a solution to (17), we have

$$
\begin{equation*}
-\int_{\Omega}\left(u_{1}-u_{2}\right)_{+} L^{*} \varphi_{0} d x \leq \int_{\Omega}\left(f_{1}-f_{2}-g \circ u_{1}+g \circ u_{2}\right) \operatorname{sign}_{+}\left(u_{1}-u_{2}\right) \varphi_{0} d x-\int_{\partial \Omega} \frac{\partial \varphi_{0}}{\partial \mathbf{n}_{L^{*}}} d\left(\eta_{1}-\eta_{2}\right)_{+} \tag{20}
\end{equation*}
$$

Since $\eta_{1} \leq \eta_{2}$, we have $\left(\eta_{1}-\eta_{2}\right)_{+}=0$. Then from the equation (20), it follows that

$$
\begin{equation*}
\int_{\Omega}\left(u_{1}-u_{2}\right)_{+} d x \leq \int_{\Omega}\left(f_{1}-f_{2}\right) \operatorname{sign}_{+}\left(u_{1}-u_{2}\right) \varphi_{0} d x+\int_{\Omega}\left(g \circ u_{2}-g \circ u_{1}\right) \operatorname{sign} n_{+}\left(u_{1}-u_{2}\right) \varphi_{0} d x \tag{21}
\end{equation*}
$$

Since the test function $\varphi_{0}>0$ and $f_{1} \leq f_{2}$, the first integral in right-hand side of (21) is less than or equal to zero. Now taking $A=\Omega \cap\left\{x \in \Omega: g \circ u_{2}-g \circ u_{1} \geq 0\right\}$ and $B=\Omega \cap\left\{x \in \Omega: g \circ u_{2}-g \circ u_{1}<0\right\}$, we have

$$
\begin{aligned}
\int_{\Omega}\left(g \circ u_{2}-g \circ u_{1}\right) \operatorname{sign}_{+}\left(u_{1}-u_{2}\right) \varphi_{0} d x & =\left(\int_{A}+\int_{B}\right)\left[\left(g \circ u_{2}-g \circ u_{1}\right) \operatorname{sign}_{+}\left(u_{1}-u_{2}\right) \varphi_{0}\right] d x \\
& =\int_{B}\left(g \circ u_{2}-g \circ u_{1}\right) \varphi_{0} d x \\
& \leq 0
\end{aligned}
$$

Thus from (21), we get $\int_{\Omega}\left(u_{1}-u_{2}\right)_{+} d x \leq 0$ which shows that $\left(u_{1}-u_{2}\right)_{+}=0$. Therefore $u_{1} \leq u_{2}$ a.e. in $\Omega$.
Theorem 2.4. (Existence of very weak solution) The boundary value problem given by (12) possesses a unique very weak solution $u$ in $L^{1}(\Omega)$.

Proof. We first prove the existence of weak solution with the test function space $W_{0}^{1,2}(\Omega)$, for the case when $f \in L^{\infty}(\Omega)$ and $\eta=0$. Now, for each $n \in \mathbb{N}$, take $g_{n}(x, t)=\min \{g(x,|t|), n\} \operatorname{sign}(g)$ and let $G_{n}(x, \cdot)$ be the primitive of $g_{n}(x, \cdot)$ such that $G_{n}(x, 0)=0$. Note that $G_{n}$ is a non negative function. $u \in W_{0}^{1,2}(\Omega)$ is a weak solution of the problem (12) with $g=g_{n}$ and $\eta=0$ if

$$
\int_{\Omega} a_{L}(u, v) d x+\int_{\Omega}\left(g_{n} \circ u\right) v d x=\int_{\Omega} f v d x, \forall v \in W_{0}^{1,2}(\Omega)
$$

where

$$
a_{L}(u, v)=\sum_{i, j=1}^{N} a_{i j} \frac{\partial u}{\partial x_{j}} \frac{\partial v}{\partial x_{i}}+\sum_{i=1}^{N}\left(b_{i} \frac{\partial u}{\partial x_{i}} v+c_{i} \frac{\partial v}{\partial x_{i}} u\right)+d u v .
$$

Let $A_{L}(u, v)=\int_{\Omega} a_{L}(u, v) d x$, for all $u, v \in W_{0}^{1,2}(\Omega)$. Then by this definition the bilinear form is continuous on $W_{0}^{1,2}(\Omega)$ and

$$
A_{L}(v, v)=\int_{\Omega}\left(\sum_{i, j=1}^{N} a_{i j} \frac{\partial v}{\partial x_{j}} \frac{\partial v}{\partial x_{i}}+\frac{1}{2} \sum_{i=1}^{N}\left(b_{i}+c_{i}\right) \frac{\partial v^{2}}{\partial x_{i}}+d v^{2}\right) d x
$$

By the uniqueness condition (8), we have $\int_{\Omega}\left(d v^{2}+\sum_{i=1}^{N} \frac{1}{2}\left(b_{i}+c_{i}\right) \frac{\partial v^{2}}{\partial x_{i}}\right) d x \geq 0$. Thus from the uniform ellipticity condition (5) we have,

$$
A_{L}(v, v) \geq c_{1} \int_{\Omega}|\nabla v|^{2} d x, \quad \forall v \in W_{0}^{1,2}(\Omega)
$$

Let us consider the functional

$$
I_{n}(u)=A_{L}(u, u)+\int_{\Omega}\left(G_{n} \circ u\right) d x-\int_{\Omega} f u d x
$$

over $W_{0}^{1,2}(\Omega)$. Since $u \in W_{0}^{1,2}(\Omega)$ and $W_{0}^{1,2}(\Omega) \hookrightarrow L^{2}(\Omega) \hookrightarrow L^{1}(\Omega)$, we have

$$
\begin{aligned}
I_{n}(u) & \geq c_{1}\|\nabla u\|_{2}^{2}+\int_{\Omega}\left(G_{n} \circ u\right) d x-\|u\|_{1} \cdot\|f\|_{\infty} \\
& \geq c_{1}\|\nabla u\|_{2}^{2}+\int_{\Omega}\left(G_{n} \circ u\right) d x-c_{2}\|\nabla u\|_{2} \cdot\|f\|_{\infty} \\
& =\left(c_{1}\|\nabla u\|_{2}-c_{2}\|f\|_{\infty}\right)\|\nabla u\|_{2}+\int_{\Omega}\left(G_{n} \circ u\right) d x
\end{aligned}
$$

where $c_{1}, c_{2}>0$ are constants. Since $G_{n}$ is a nonnegative function, it shows that $I_{n}(u) \rightarrow \infty$, when $\|\nabla u\|_{2} \rightarrow \infty$. Therefore, the functional $I_{n}(u)$ is coercive.
Now we will show that the functional $I_{n}(u)$ is weakly lower semi-continuous. For this let $v_{m} \rightharpoonup u$ weakly in $W_{0}^{1,2}(\Omega)$. By Fatou's lemma,

$$
\int_{\Omega} G_{n} \circ u d x \leq \lim _{m \rightarrow \infty} \inf \int_{\Omega} G_{n} \circ v_{m} d x
$$

Now the first term of $A_{L}(v, v)$ is equivalent to the Sobolev norm of $W_{0}^{1,2}(\Omega)$ and $a_{i j}$ 's are Lipschitz continuous functions in $\Omega$, hence

$$
\begin{equation*}
\int_{\Omega} \sum_{i, j=1}^{N} a_{i j} \frac{\partial u}{\partial x_{j}} \frac{\partial u}{\partial x_{i}} \leq \lim _{m \rightarrow \infty} \inf \int_{\Omega} \sum_{i, j=1}^{N} a_{i j} \frac{\partial v_{m}}{\partial x_{j}} \frac{\partial v_{m}}{\partial x_{i}} \tag{22}
\end{equation*}
$$

Since the embedding $W_{0}^{1,2}(\Omega) \hookrightarrow L^{2}(\Omega)$ is compact therefore $v_{m} \rightarrow u$ in $L^{2}(\Omega)$ and also we have $\frac{\partial v_{m}}{\partial x_{i}} \rightharpoonup \frac{\partial u}{\partial x_{i}}$ in $L^{2}(\Omega)$ for each $i=1,2, \cdots, N$. Since $b_{i}$ 's are Lipschitz continuous functions on $\Omega$, by the strong convergence of $v_{m}$ in $L^{2}(\Omega)$ and the weak convergence of $\frac{\partial v_{m}}{\partial x_{i}}$ in $L^{2}(\Omega)$, one can see that

$$
\begin{aligned}
\lim _{m \rightarrow \infty} \lim _{n \rightarrow \infty} \int_{\Omega} b_{i} v_{m} \frac{\partial v_{m}}{\partial x_{i}} d x & =\lim _{n \rightarrow \infty} \lim _{m \rightarrow \infty} \int_{\Omega} b_{i} v_{m} \frac{\partial v_{m}}{\partial x_{i}} d x \\
& =\int_{\Omega} b_{i} u \frac{\partial u}{\partial x_{i}} d x
\end{aligned}
$$

Therefore taking $m=n$, we have $\int_{\Omega} b_{i} v_{m} \frac{\partial v_{m}}{\partial x_{i}} d x \rightarrow \int_{\Omega} b_{i} u \frac{\partial u}{\partial x_{i}} d x$ as $m \rightarrow \infty$ for each $i=1,2, \cdots, N$. Thus

$$
\begin{equation*}
\lim _{m \rightarrow \infty} \int_{\Omega} \frac{1}{2} \sum_{i=1}^{N}\left(b_{i}+c_{i}\right) \frac{\partial v_{m}^{2}}{\partial x_{i}}=\int_{\Omega} \frac{1}{2} \sum_{i=1}^{N}\left(b_{i}+c_{i}\right) \frac{\partial u^{2}}{\partial x_{i}} \tag{23}
\end{equation*}
$$

Similarly, for the third term of $A_{L}(v, v)$ we have

$$
\begin{equation*}
\lim _{m \rightarrow \infty} \int_{\Omega} d v_{m}^{2}=\int_{\Omega} d u^{2} \tag{24}
\end{equation*}
$$

Therefore, combining (22), (23) and (24) we have

$$
\begin{aligned}
I_{n}(u) & \leq \lim _{m \rightarrow \infty} \inf A_{L}\left(v_{m}, v_{m}\right)+\lim _{m \rightarrow \infty} \inf \int_{\Omega} G_{n} \circ v_{m} d x-\lim _{m \rightarrow \infty} \int_{\Omega} f v_{m} \\
& \leq \lim _{m \rightarrow \infty} \inf I_{n}\left(v_{m}\right) .
\end{aligned}
$$

Thus $I_{n}(u)$ is weakly lower semi-continuous and coercive. Hence the variational problem $\min _{u \in W_{0}^{1,2}(\Omega)}\left\{I_{n}(u)\right\}$ possesses a weak solution $u_{n} \in W_{0}^{1,2}(\Omega)$. The minimizer $u_{n}$ is a weak solution of the boundary value problem

$$
\begin{align*}
-L u+g_{n} \circ u & =f \text { in } \Omega \\
u & =0 \text { on } \partial \Omega \tag{25}
\end{align*}
$$

where $f \in L^{\infty}(\Omega)$. That is $u_{n} \in W_{0}^{1,2}(\Omega)$ satisfies,

$$
\begin{equation*}
\int_{\Omega}\left(\sum_{i, j=1}^{N} a_{i j} \frac{\partial u_{n}}{\partial x_{j}} \frac{\partial v}{\partial x_{i}}+\sum_{i=1}^{N}\left(b_{i} \frac{\partial u_{n}}{\partial x_{i}} v+c_{i} \frac{\partial v}{\partial x_{i}} u_{n}\right)+d u_{n} v\right)+\int_{\Omega}\left(g_{n} \circ u_{n}\right) v=\int_{\Omega} f v, \tag{26}
\end{equation*}
$$

for every $v \in W_{0}^{1,2}(\Omega)$. Thus by taking $v=\varphi$, where $\varphi \in C_{c}^{2, L}(\bar{\Omega})$ in the equation (26) and then applying integration by parts we get

$$
\begin{equation*}
-\int_{\Omega} u_{n} L^{*} \varphi+\int_{\Omega}\left(g_{n} \circ u_{n}\right) v=\int_{\Omega} f \varphi \tag{27}
\end{equation*}
$$

for every $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. This shows that $u_{n}$ is a very weak solution of the boundary value problem

$$
\begin{align*}
-L u+g_{n} \circ u & =f \text { in } \Omega \\
u & =0 \text { on } \partial \Omega \tag{28}
\end{align*}
$$

where $f \in L^{\infty}(\Omega)$. Further, by (19), the sequences $\left\{u_{n}\right\}$ and $\left\{g_{n} \circ u_{n}\right\}$ are bounded in $L^{1}(\Omega)$ and $L^{1}(\Omega, \rho)$ respectively.
Now consider the case $f \geq 0$. Then by comparison of solutions (by the Lemma 2.3) we obtain $u_{n} \geq 0$. Since $u_{n}$ is a very weak solution of the problem (28), we write as following

$$
\begin{align*}
-L u_{n}+g_{n} \circ u_{n} & =f \text { in } \Omega, \\
u_{n} & =0 \text { on } \partial \Omega . \tag{29}
\end{align*}
$$

A slight manipulation of (29) gives the following

$$
\begin{align*}
-L u_{n}+g_{n+1} \circ u_{n} & =f+g_{n+1} \circ u_{n}-g_{n} \circ u_{n} \text { in } \Omega,  \tag{30}\\
u_{n} & =0 \text { on } \partial \Omega .
\end{align*}
$$

Choose $f^{*}=f+g_{n+1} \circ u_{n}-g_{n} \circ u_{n}$, then $f^{*} \geq f$ on $\Omega$ because the sequence $\left\{g_{n}\right\}$ is monotonically increasing. We also have $u_{n+1}$, which is a very weak solution to the problem

$$
\begin{align*}
-L u_{n+1}+g_{n+1} \circ u_{n+1} & =f \text { in } \Omega  \tag{31}\\
u_{n+1} & =0 \text { on } \partial \Omega
\end{align*}
$$

Since $f^{*} \geq f$, hence from (30) and (31) we have $u_{n+1} \leq u_{n}$. Thus $\left\{u_{n}\right\}$ is a bounded monotonically decreasing sequence and so by the dominated convergence theorem we have $u_{n} \rightarrow u$ in $L^{1}(\Omega)$, for some $u$. Therefore there exists a subsequence, which we will still denote as $u_{n}$, converges to $u$ pointwise a.e. and hence $g_{n} \circ u_{n} \rightarrow g \circ u$. Indeed,

$$
\begin{aligned}
g_{n} \circ u_{n}(x) & =\min \left\{g\left(x,\left|u_{n}(x)\right|\right), n\right\} \operatorname{sign}(g) \\
& =\min \left\{g\left(x, u_{n}(x)\right), n\right\} \operatorname{sign}(g) \\
& =g\left(x, u_{n}(x)\right), \text { for } n \geq k(x)
\end{aligned}
$$

From (6), we have $g_{n} \circ u_{n}(x)=g \circ u_{n}(x) \rightarrow g \circ u(x)$ a.e. for $n \geq k(x)$. Now by the Theorem 2.4 of Véron [15], let $V$ be the very weak solution of

$$
\begin{align*}
-L v & =f \text { in } \Omega,  \tag{32}\\
v & =0 \text { on } \partial \Omega .
\end{align*}
$$

Notice that as $u_{n} \geq 0$, we have $g_{n} \circ u_{n} \geq 0$. Thus,

$$
\begin{aligned}
-L u_{n} & =f-g_{n} \circ u_{n} \leq f=-L v \text { in } \Omega, \\
u_{m} & =0
\end{aligned} \quad v=0 \text { on } \partial \Omega .
$$

Therefore, by comparison of solutions, we have $u_{n} \leq V$ and hence $g \circ u_{n} \leq g \circ V$. In other words, if $V$ is a very weak solution of the boundary value problem (32), then the sequence $\left\{g \circ u_{n}\right\}$ is dominated by $g \circ V$. Since $u_{n} \rightarrow u$ and $g \circ u_{n} \rightarrow g \circ u$ in $L^{1}(\Omega)$, hence $\int_{\Omega} u_{n} L^{*} \varphi \rightarrow \int_{\Omega} u L^{*} \varphi$ and $\int_{\Omega}\left(g \circ u_{n}\right) \varphi \rightarrow \int_{\Omega}(g \circ u) \varphi$ for all $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. Thus we can conclude that $u \in L^{1}(\Omega)$ is a very weak solution of

$$
\begin{align*}
-L u+g \circ u & =f \text { in } \Omega, \\
u & =0 \text { on } \partial \Omega . \tag{33}
\end{align*}
$$

We now drop the condition $f \geq 0$. Let $\tilde{u}_{n}$ be a very weak solution of (28) with $f$ replaced by $|f|$. Then $\tilde{u}_{n} \geq 0$ and

$$
\begin{aligned}
-L u_{n}+g_{n} \circ u_{n} & =f \leq|f|=-L \tilde{u}_{n}+g_{n} \circ \tilde{u}_{n} \text { in } \Omega, \\
u_{n} & =0 \\
\tilde{u}_{n} & =0 \text { on } \partial \Omega .
\end{aligned}
$$

Hence by the comparison of solutions, we have $u_{n} \leq \tilde{u}_{n}$. Since $g\left(x,-\tilde{u}_{n}(x)\right) \leq 0$, hence one can show that $g_{n}\left(x,-\tilde{u}_{n}(x)\right)=-g_{n}\left(x, \tilde{u}_{n}(x)\right)$ and also

$$
\begin{align*}
-L\left(-\tilde{u}_{n}\right)+g_{n} \circ\left(-\tilde{u}_{n}\right) & =-|f| \text { in } \Omega \\
-\left(\tilde{u}_{n}\right) & =0 \text { on } \partial \Omega . \tag{34}
\end{align*}
$$

Again by comparison of solutions we have $-\tilde{u}_{n} \leq u_{n}$, as $-|f| \leq f$. Therefore, $\left|u_{n}\right| \leq \tilde{u}_{n}$. By the similar argument as previous, the sequence $\left\{\tilde{u}_{n}\right\}$ is bounded in $L^{1}(\Omega)$ and monotonically decreasing, hence $\left\{u_{n}\right\}$ is also a bounded monotonically decreasing sequence. Thus $u_{n} \rightarrow u$ in $L^{1}(\Omega)$, for some $u$ and therefore there exists a subsequence such that $u_{n}(x) \rightarrow u(x)$ a.e.. Hence $\left\{g_{n} \circ u_{n}\right\}$ converges a.e. and is dominated by $\left\{g_{n} \circ \tilde{u}_{n}\right\}$. Therefore $u$ is a very weak solution of the boundary value problem (33). By using the density arguments in the estimates (14), we obtain the existence of very weak solution for every $f \in L^{1}(\Omega ; \rho)$.
Suppose $\eta \neq 0$ and $\eta \in C^{2}(\partial \Omega)$ and let $v$ be a classical solution (refer [15]) of

$$
\begin{align*}
-L v & =0 \text { in } \Omega \\
v & =\eta \text { on } \partial \Omega . \tag{35}
\end{align*}
$$

Let $w=u-v$. So we have $L(w+v)=L w$. Then the problem (12) can be written as

$$
\begin{align*}
-L w+\tilde{g} \circ w & =\tilde{f} \text { in } \Omega  \tag{36}\\
w & =0 \text { on } \partial \Omega
\end{align*}
$$

where $\tilde{g} \circ w=g(x, w(x)+v(x))-g(x, v(x))$ and $\tilde{f}=f-g \circ v$. Clearly $\tilde{g} \in \mathscr{G}_{0}$ and $\tilde{f} \in L^{1}(\Omega ; \rho)$. Therefore the boundary value problem (12) possesses a weak solution whenever $f \in L^{1}(\Omega, \rho)$ and $\eta \in C^{2}(\partial \Omega)$.
Suppose $f \in L^{1}(\Omega, \rho)$ and $\eta \in L^{1}(\partial \Omega)$, by density there exists a sequence $\left\{\eta_{n}\right\} \subset C^{\infty}(\partial \Omega)$ such that $\eta_{n} \rightarrow \eta$ in $L^{1}(\partial \Omega)$. To each $\left(f, \eta_{n}\right)$, there exists a very weak solution $u_{n} \in L^{1}(\Omega)$. By estimate (14), we have $u_{n} \rightarrow u$ in $L^{1}(\Omega)$ and $g \circ u_{n} \rightarrow g \circ u$ in $L^{1}(\Omega, \rho)$. This precisely shows that $u$ is a very weak solution of the boundary value problem (12).

## 3. Semilinear problem with measure data

In this section we prove the following main result.
Theorem 3.1. Assume that $\left\{\mu_{n}, v_{n}\right\} \subset \mathfrak{M}^{g}(\bar{\Omega})$ such that $\rho \mu_{n} \underset{\bar{\Omega}}{\stackrel{\rightharpoonup}{2}} \tau$ in $\mathfrak{M}(\bar{\Omega})$ and $v_{n} \rightharpoonup v$ in $\mathfrak{M}(\partial \Omega)$. Let $u_{n}$ be the solution of

$$
\begin{align*}
-L u+g \circ u & =\mu_{n} \text { in } \Omega \\
u & =v_{n} \text { on } \partial \Omega \tag{37}
\end{align*}
$$

where $g \in \mathscr{G}_{0}$ and suppose that

$$
u_{n} \rightarrow u \text { in } L^{1}(\Omega) .
$$

Then
(i) $\left\{\rho\left(g \circ u_{n}\right)\right\}$ converges weakly in $\bar{\Omega}$ and
(ii) there exists $\mu^{\#} \in \mathfrak{M}(\Omega, \rho), v^{\#} \in \mathfrak{M}(\partial \Omega)$ such that $u$ is a weak solution of

$$
\begin{align*}
-L u+g \circ u & =\mu^{\#} \text { in } \Omega \\
u & =v^{\#} \text { on } \partial \Omega . \tag{38}
\end{align*}
$$

Furthermore, if $\mu_{n} \geq 0$ and $v_{n} \geq 0$ for every $n$, then

$$
0 \leq v^{\#} \leq\left(v+\frac{\tau}{\mathbf{n} \cdot \mathbf{n} A^{T}} \chi_{\partial \Omega}\right)
$$

where $\mathbf{n}$ is the outward normal unit vector to the boundary $\partial \Omega$ and $A=\left(a_{i j}\right)_{N \times N}$, the matrix corresponding to the principle part of elliptic differential operator $L$.

The measures $\mu^{\#}$ and $v^{\#}$ are called reduced limit of the sequences of measures $\left\{\mu_{n}\right\}$ and $\left\{v_{n}\right\}$ respectively. We divide the proof into several lemmas and theorems. We now begin with the following existence theorem.

Theorem 3.2. Consider the boundary value problem

$$
\begin{align*}
-L u+g \circ u & =\mu \text { in } \Omega \\
u & =v \text { on } \partial \Omega \tag{39}
\end{align*}
$$

with $g \in \mathscr{G}_{0}, \mu \in \mathfrak{M}(\Omega, \rho)$ and $v \in \mathfrak{M}(\partial \Omega)$. If a solution exists, then

$$
\begin{equation*}
\|u\|_{L^{1}(\Omega)}+\|g \circ u\|_{L^{1}(\Omega, \rho)} \leq C\left(\|\mu\|_{M_{( }(\Omega, \rho)}+\|v\|_{\left.M_{( }(\Omega)\right)}\right) \tag{40}
\end{equation*}
$$

If $u_{i} \in L^{1}(\Omega)$ are very weak solutions corresponding to $\mu=\mu_{i}$, for $i=1,2$, then we have the following estimate

$$
\begin{equation*}
\left\|u_{1}-u_{2}\right\|_{L^{1}(\Omega)}+\left\|g \circ u_{1}-g \circ u_{2}\right\|_{L^{1}(\Omega ; \rho)} \leq C\left(\left\|\mu_{1}-\mu_{2}\right\|_{\mathfrak{M}(\Omega, \rho)}+\left\|v_{1}-v_{2}\right\|_{\mathfrak{M}(\partial \Omega)}\right) \tag{41}
\end{equation*}
$$

Furthermore, if $\mu_{1} \leq \mu_{2}, v_{1} \leq v_{2}$ then $u_{1} \leq u_{2}$. This also implies that the problem in (39) possesses at most one very weak solution $u \in L^{1}(\Omega)$ if at all a solution exists to it.

Proof. The proof runs along the same lines as that of the corresponding Lemmas (2.2), (2.3) and Theorem (2.4) in the previous section.

In contrast to the case of when $L=\Delta$ with $L^{1}$ data, the problem with measure data does not necessarily possess a solution. It may so happen that $\mu_{n} \rightharpoonup \delta_{0}$ and $u_{n} \rightarrow 0$ in $L^{1}(\Omega)$, although 0 is not a solution of (39) with $L=\Delta, \mu=\delta_{0}$ and $v=0$ [5]. However, if a solution exists then it is unique and the inequality (40) remain valid.
The following corollary is an immediate consequence of the definition of a good measure and Theorem 3.2.
Corollary 3.3. Assume that $(\mu, v) \in \mathfrak{M}^{g}(\bar{\Omega})$. Then the boundary value problem (39) possess a unique very weak solution in $L^{1}(\Omega)$.

We state the following theorem.
Theorem 3.4. Assume that $(\mu, v) \in \mathfrak{M}^{g}(\bar{\Omega})$ with $\mu \geq 0$ and $v \geq 0$. Then the very weak solution $u$ of the boundary value problem (39), is in $L^{p}(\Omega)$ for $1 \leq p<\frac{N}{N-1}$ and there exists a constant $C(p)$ such that

$$
\begin{equation*}
\|u\|_{L^{p}(\Omega)} \leq C(p)\left(\|\mu\|_{\mathfrak{M}(\Omega, \rho)}+\|v\|_{\mathfrak{M}(\partial \Omega)}\right) \tag{42}
\end{equation*}
$$

Proof. The range of $p$ can be found by using the Green function of the elliptic operator $L$ which is obtained in the work of Véron ([15]). Note that in our case we are considering $p$ is strictly less than $N$. The estimate is an immediate consequence of (41) and the notion of representing the solution in terms of Green's function.

Corollary 3.5. Under the assumptions made in Theorem 3.4, the solution $u$ of the problem (39) is in $W_{l o c}^{1, p}(\Omega)$ for $\in\left[1, \frac{N}{N-1}\right)$. Also for every relatively compact domain $\Omega^{\prime}$ in $\Omega$, there exists a constant $C(q)$ such that

$$
\begin{equation*}
\|u\|_{L^{p}\left(\Omega^{\prime}\right)} \leq C(p)\left(\|\mu\|_{M_{\left(\Omega^{\prime}\right)}}+\|v\|_{M_{( }(\Omega)}\right) . \tag{43}
\end{equation*}
$$

The following definitions and propositions are due to Marcus and Véron [12].

Definition 3.6. We say that $\left\{\Omega_{n}\right\}$ is uniformly of class $C^{2}$ if $\exists r_{0}, \gamma_{0}, n_{0}$ such that for any $X \in \partial \Omega$ :
There exists a system of Cartesian coordinates $\xi$ centered at $X$, a sequence $\left\{f_{n}\right\} \subset C^{2}\left(B_{r_{0}}^{N-1}(0)\right)$ and $f \in C^{2}\left(B_{r_{0}}^{N-1}(0)\right)$ such that the following statement holds. Let

$$
Q_{0}:=\left\{\xi=\left(\xi_{1}, \xi^{\prime}\right) \in \mathbb{R} \times \mathbb{R}^{N-1}:\left|\xi^{\prime}\right|<r_{0},\left|\xi_{N}\right|<\gamma_{0}\right\} .
$$

Then the surfaces $\partial \Omega_{n} \cap Q_{0}, n>n_{0}$ and $\partial \Omega \cap Q_{0}$ can be expressed as $\xi_{1}=f_{n}\left(\xi^{\prime}\right)$ and $\xi_{1}=f\left(\xi^{\prime}\right)$ respectively and

$$
f_{n} \rightarrow f \text { in } C^{2}\left(B_{r_{0}}^{N-1}(0)\right)
$$

Definition 3.7. A sequence $\left\{\Omega_{n}\right\}$ is an exhaustion of $\Omega$ if $\bar{\Omega}_{n} \subset \Omega_{n+1}$ and $\Omega_{n} \uparrow \Omega$. We say that an exhaustion $\Omega_{n}$ is of class $C^{2}$ if each domain $\Omega_{n}$ is of this class. If, in addition, $\Omega$ is a $C^{2}$ domain and the sequence of domains $\left\{\Omega_{n}\right\}$ is uniformly of class $C^{2}$, we say that $\left\{\Omega_{n}\right\}$ is a uniform $C^{2}$ exhaustion.

Definition 3.8. Let $u \in W_{l o c}^{1, p}(\Omega)$ for some $p>1$. We say that u possesses an $M$-boundary trace on $\partial \Omega$ if there exists $v \in \mathfrak{M}(\partial \Omega)$ such that, for every uniform $C^{2}$ exhaustion $\left\{\Omega_{n}\right\}$ and every $h \in C(\bar{\Omega})$,

$$
\int_{\partial \Omega_{n}} u L_{\partial \Omega_{n}} h d S \rightarrow \int_{\partial \Omega} h d v
$$

where $u \mathrm{~L}_{\Omega_{n}}$ denotes the Sobolev trace, $d S=d \mathbb{H}^{N-1}$ and $\mathbb{H}^{N-1}$ denotes the $(N-1)$ dimensional Hausdorff measure. The M-boundary trace $v$ of $u$ is denoted by tru.

Remark 3.9. If $u \in W^{1, p}(\Omega)$ for some $p>1$, then the Sobolev trace $=M$ - boundary trace.
Definition 3.10. We say that $u \in L^{1}(\Omega)$ satisfies $-L u=\mu$ in $\Omega$, in the sense of distribution if it satisfies

$$
-\int_{\Omega} u L^{*} \varphi=\int_{\Omega} \varphi d \mu
$$

for every $\varphi \in C_{c}^{\infty, L}(\Omega)$, where $C_{c}^{\infty, L}(\Omega)=\left\{\varphi \in C_{c}^{\infty}(\Omega): L^{*} \varphi \in L^{\infty}(\Omega)\right\}$.
Proposition 3.11. Let $\mu \in \mathfrak{M}(\Omega, \rho)$ and $v \in \mathfrak{M}(\partial \Omega)$. Then a function $u \in L^{1}(\Omega)$ is a very weak solution of the problem

$$
\begin{aligned}
-L u & =\mu \text { in } \Omega \\
u & =v \text { on } \partial \Omega
\end{aligned}
$$

if and only if

$$
\begin{aligned}
-L u & =\mu \text { in } \Omega(\text { in the sense of distribution }) \\
\operatorname{tr} u & =v \text { on } \partial \Omega(\text { in the sense of Definition 3.8) }
\end{aligned}
$$

Proof. The proof follows the Proposition 1.3.7, [12].
The following result is an immediate consequence of the Proposition 3.11.
Proposition 3.12. Let $\mu \in \mathfrak{M}(\Omega, \rho)$ and $v \in \mathfrak{M}(\partial \Omega)$. Then a function $u \in L^{1}(\Omega)$, with $g \circ u \in L^{1}(\Omega, \rho)$, satisfies (10) if and only if

$$
\begin{aligned}
-L u+g \circ u & =\mu \text { in } \Omega(\text { in the sense of distribution }) \\
\operatorname{tr} u & =v \text { on } \partial \Omega \text { (in the sense of Definition 3.8) }
\end{aligned}
$$

We prove the following crucial lemma.

Lemma 3.13. Let $\rho \mu_{n} \underset{\Omega}{\rightharpoonup} \tau$. Then

$$
\lim _{n \rightarrow \infty} \int_{\Omega} \varphi d \mu_{n}=\int_{\Omega} \varphi d \mu_{i n t}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} d \tau
$$

for all $\varphi \in C_{c}^{2, L}(\bar{\Omega})$, where $\mathbf{n}$ is the outward normal unit vector to $\partial \Omega$ and $A=\left(a_{i j}\right)_{N \times N}$.
Proof. Consider $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. Since $\varphi$ vanishes on $\partial \Omega$, so for $x_{0} \in \partial \Omega, \nabla \varphi\left(x_{0}\right)$ is normal to $\partial \Omega$, that is

$$
\nabla \varphi\left(x_{0}\right)=c \mathbf{n}, \quad \text { where } c:=\frac{\partial \varphi}{\partial \mathbf{n}}\left(x_{0}\right)
$$

As $\rho(x)=\operatorname{dist}(x, \partial \Omega)$, hence $\nabla \rho\left(x_{0}\right)=-\mathbf{n}$. Thus for given any direction $v$, we have

$$
\lim _{t \rightarrow 0+} \frac{\varphi\left(x_{0}-t v\right)}{\rho\left(x_{0}-t v\right)}=\frac{\nabla \varphi\left(x_{0}\right) \cdot v}{\nabla \rho\left(x_{0}\right) \cdot v}=\frac{\nabla \varphi\left(x_{0}\right) \cdot v}{-\mathbf{n} \cdot v}=-c=-\frac{\partial \varphi}{\partial \mathbf{n}}\left(x_{0}\right) .
$$

In particular, taking $v=\mathbf{n} A^{T}\left(x_{0}\right)$ in the above we get,

$$
\lim _{t \rightarrow 0+} \frac{\varphi\left(x_{0}-t v\right)}{\rho\left(x_{0}-t v\right)}=\frac{\nabla \varphi\left(x_{0}\right) \cdot \mathbf{n} A^{T}\left(x_{0}\right)}{\nabla \rho\left(x_{0}\right) \cdot \mathbf{n} A\left(x_{0}\right)}=\frac{\nabla \varphi\left(x_{0}\right) \cdot \mathbf{n} A^{T}\left(x_{0}\right)}{-\mathbf{n} \cdot \mathbf{n} A^{T}\left(x_{0}\right)}=-\frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}}\left(x_{0}\right) \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}\left(x_{0}\right)} .
$$

Now take $\bar{\varphi}(x)= \begin{cases}\frac{\varphi}{\rho}(x) ; & x \in \Omega, \\ -\frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} ; & x \in \partial \Omega\end{cases}$
Then $\bar{\varphi} \in C(\bar{\Omega})$ and using remark 1.5, we have,

$$
\begin{aligned}
\lim _{n \rightarrow \infty} \int_{\Omega} \varphi d \mu_{n} & =\lim _{n \rightarrow \infty} \int_{\Omega} \rho \bar{\varphi} d \mu_{n} \\
& =\int_{\bar{\Omega}} \bar{\varphi} d \tau \quad\left(\text { since } \rho \mu_{n} \stackrel{\rightharpoonup}{\bar{\Omega}} \tau\right) \\
& \left.=\int_{\bar{\Omega}} \bar{\varphi} \chi_{\partial \Omega} d \tau+\int_{\bar{\Omega}} \rho \bar{\varphi} d \mu_{i n t} \quad \text { (since } \tau=\rho \mu_{i n t}+\tau \chi_{\partial \Omega}\right) \\
& =\int_{\partial \Omega} \bar{\varphi} d \tau+\int_{\Omega} \rho \bar{\varphi} d \mu_{i n t} \\
& =\int_{\Omega} \varphi d \mu_{i n t}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial n_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} d \tau
\end{aligned}
$$

Hence the lemma.
Lemma 3.14. Assume that the given conditions in the Theorem 3.1 are holds. Then there exists a subsequence $\left\{u_{n_{k}}\right\}$ of $\left\{u_{n}\right\}$ that converges in $L^{1}(\Omega)$.

Proof. By the given condition we have $\left\|\mu_{n}\right\|_{\mathfrak{M}(\Omega, \rho)}+\left\|v_{n}\right\|_{\mathfrak{M}(\partial \Omega)} \leq c, \forall n \in \mathbb{N}$, for some $c>0$. Therefore, by (42), $\left\{u_{n}\right\}$ is bounded in $L^{p}(\Omega)$ for every $p \in\left[1, \frac{N}{N-1}\right)$. This implies that $\left\{u_{n}\right\}$ is uniformly integrable in $L^{p}(\Omega)$, for each such $p$. By Vitali's convergence theorem there exists a subsequence $\left\{u_{n_{k}}\right\}$ such that $u_{n_{k}} \rightarrow u$ in $L^{1}(\Omega)$, for some $u \in L^{1}(\Omega)$.

Proof. [Proof of the Theorem 3.1] By our assumption, $\left\{\mu_{n}\right\}$ is bounded in $\mathfrak{M}(\Omega, \rho)$ and $\left\{v_{n}\right\}$ is bounded in $\mathfrak{M}(\partial \Omega)$. Using (40), we have $\left\{g \circ u_{n}\right\}$ is bounded in $L^{1}(\Omega, \rho)$ and hence $\left\{\rho\left(g \circ u_{n}\right)\right\}$ is also bounded $L^{1}(\Omega)$. Therefore, there exists a subsequence of $\left\{\rho\left(g \circ u_{n}\right)\right\}$ still denoted by $\left\{\rho\left(g \circ u_{n}\right)\right\}$ converges weakly in $\bar{\Omega}$. Thus

$$
\rho g \circ u_{n} \underset{\bar{\Omega}}{\stackrel{\rightharpoonup}{\rightharpoonup}} \lambda \text { (say) }
$$

Take $\lambda_{\text {int }}=\frac{\lambda}{\rho} \chi_{\Omega}$ and $\lambda_{b d}=\lambda \chi_{\partial \Omega}$. Then by the lemma 3.13,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \int_{\Omega}\left(g \circ u_{n}\right) \varphi d x=\int_{\Omega} \varphi d \lambda_{i n t}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} d \lambda \tag{44}
\end{equation*}
$$

and since $\rho \mu_{n} \underset{\bar{\Omega}}{\longrightarrow} \tau$ in $\mathfrak{M}(\bar{\Omega})$,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \int_{\Omega} \varphi d \mu_{n}=\int_{\Omega} \varphi d \mu_{i n t}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} d \tau \tag{45}
\end{equation*}
$$

for all $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. Since $u_{n}$ is a weak solution of (3), we have,

$$
\int_{\Omega}\left(-u_{n} L^{*} \varphi+\left(g \circ u_{n}\right) \varphi\right) d x=\int_{\Omega} \varphi d \mu_{n}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d v_{n}
$$

for every $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. Taking the limit $n \rightarrow \infty$ and using (44) and (45), we have

$$
-\int_{\Omega} u L^{*} \varphi d x+\int_{\Omega} \varphi d \lambda_{i n t}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} d \lambda_{b d}=\int_{\Omega} \varphi d \mu_{i n t}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} d \tau_{b d}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d v
$$

for every $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. The above equation can also be expressed as

$$
-\int_{\Omega} u L^{*} \varphi d x+\int_{\Omega}(g \circ u) \varphi d x=\int_{\Omega}(g \circ u) \varphi d x-\int_{\Omega} \varphi d\left(\lambda_{i n t}-\mu_{i n t}\right)+\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} \frac{1}{\mathbf{n} \cdot \mathbf{n} A^{T}} d\left(\lambda_{b d}-\tau_{b d}\right)-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d v
$$

for every $\varphi \in C_{c}^{2, L}(\bar{\Omega})$. This shows that $u$ is a weak solution of (38), where

$$
\begin{align*}
& \mu^{\#}=g \circ u-\left(\lambda_{i n t}-\mu_{i n t}\right),  \tag{46}\\
& v^{\#}=v-\frac{\left(\lambda_{b d}-\tau_{b d}\right)}{\mathbf{n} \cdot \mathbf{n} A^{T}} . \tag{47}
\end{align*}
$$

Further, if $\mu_{n}, v_{n} \geq 0$ then by comparison of solutions $u_{n} \geq 0$. Hence $\rho g \circ u_{n} \geq 0$ and in this case $\lambda \geq 0$ and $v^{\#} \geq 0$. Also by uniformly ellipticity condition (5), $\mathbf{n} \cdot \mathbf{n} A^{T}>0$. Hence by (47), we obtain $v^{\#} \leq v+\frac{\tau_{b d}}{\mathbf{n} \cdot \mathbf{n} A^{T}}$.
Remark 3.15. The Theorem 3.1 in this paper, is a generalization of the Theorem 4.1 of Bhakta and Marcus [10], in which the case $L=-\Delta$ has been considered. In fact by putting $A=I$ in (46) and (47), we have the corresponding reduced limit

$$
\begin{aligned}
\mu^{\#} & =g \circ u-\left(\lambda_{i n t}-\mu_{i n t}\right), \\
v^{\#} & =v-\left(\lambda_{b d}-\tau_{b d}\right) .
\end{aligned}
$$

One more important thing is that the reduced limit of the boundary value problem depends on the matrix $A_{N \times N}$ corresponding to the principle part of the elliptic operator $L$.

We now investigate the relation between the reduced limit and weak limit which is given in terms of the following theorem.
Theorem 3.16. In addition to the assumptions of Theorem 3.1, assume that the uniform ellipticity condition (5) holds with $\alpha \geq 1$ and also assume that the nonlinear function $g$-satisfies

$$
\begin{equation*}
\lim _{a, t \rightarrow \infty} \frac{g(x, a t)}{a g(x, t)}=\infty \tag{48}
\end{equation*}
$$

uniformly with respect to $x \in \Omega$. Let $v_{n}$ be the very weak solution of

$$
\begin{align*}
-L v_{n} & =\mu_{n} \text { in } \Omega \\
v_{n} & =v_{n} \text { on } \partial \Omega \tag{49}
\end{align*}
$$

If $\mu_{n}, v_{n} \geq 0$ and $\left\{g \circ v_{n}\right\}$ is bounded in $L^{1}(\Omega ; \rho)$ then $v^{\#}$ (reduced limit of $\left\{v_{n}\right\}$ ) and $v^{\#} \leq v+\frac{\tau_{b d}}{\mathbf{n} \cdot \mathbf{n} A^{T}}$ are mutually absolutely continuous.
Proof. Since $\mu_{n}, v_{n} \geq 0$, hence by the theorem $3.1,0 \leq v^{\#} \leq v+\frac{\tau_{b d}}{\mathbf{n} \cdot \mathbf{n}_{b d} A^{T}}$. Therefore, $v^{\#}$ is absolutely continuous with respect to $v+\frac{\tau_{b d}}{\mathbf{n} \cdot \mathbf{n} A^{T}}$. Thus we only need to show $v+\frac{\tau_{b d}}{\mathbf{n} \cdot \mathbf{n} A^{T}}$ is absolutely continuous with respect to $v^{\#}$.
Let $\alpha \in(0,1]$. Then we have $0 \leq g \circ\left(\alpha v_{n}\right) \leq g \circ v_{n}$. By our assumption $\left\{g \circ v_{n}\right\}$ is bounded in $L^{1}(\Omega ; \rho)$. Hence there exists $c_{0}>0$ such that

$$
\left\|g \circ\left(\alpha v_{n}\right)\right\|_{L^{1}(\Omega, \rho)} \leq c_{0} ; \forall n \geq 1, \forall \alpha \in(0,1)
$$

Let $\left\{\alpha_{k}\right\}$ be a sequence in $(0,1)$ such that $\alpha_{k} \downarrow 0$. Then one can extract a subsequence of $\left\{\rho g \circ\left(\alpha_{k} v_{n}\right)\right\}$ such that there exists a measure $\sigma_{k} \in \mathfrak{M}(\bar{\Omega})$ such that

$$
\rho g \circ\left(\alpha_{k} v_{n}\right) \underset{\Omega}{\stackrel{\rightharpoonup}{\Omega}} \sigma_{k}
$$

for each $k$. Let $w_{n, k}$ be the very weak solution of the problem

$$
\begin{align*}
-L w+g \circ w & =\alpha_{k} \mu_{n} \text { in } \Omega, \\
w & =\alpha_{k} v_{n} \text { on } \partial \Omega . \tag{50}
\end{align*}
$$

We will denote $w_{n}$ to be the very weak solution of

$$
\begin{align*}
-L w+g \circ w & =\mu_{n} \text { in } \Omega \\
w & =v_{n} \text { on } \partial \Omega . \tag{51}
\end{align*}
$$

Since $\alpha_{k} \mu_{n} \leq \mu_{n}$ and $\alpha_{k} v_{n} \leq v_{n}$, hence by comparison of solutions when applied to (50) and (51), we have, $w_{n, k} \leq w_{n}$. Now observe that $g \circ \alpha_{k} v_{n} \geq 0$. Since $v_{n}$ is a solution of (49), we have

$$
\begin{aligned}
-\int_{\Omega} \alpha_{k} v_{n} L^{*} \varphi d x+\int_{\Omega}\left(g \circ \alpha_{k} v_{n}\right) \varphi d x & \geq-\int_{\Omega} v_{n} L^{*} \varphi d x+\int_{\Omega}\left(g \circ \alpha_{k} v_{n}\right) \varphi d x \\
& =\int_{\Omega} \varphi d \mu_{n}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d v_{n}+\int_{\Omega}\left(g \circ \alpha_{k} v_{n}\right) \varphi d x \\
& \geq \int_{\Omega} \varphi d \mu_{n}-\int_{\partial \Omega} \frac{\partial \varphi}{\partial \mathbf{n}_{L^{*}}} d v_{n}
\end{aligned}
$$

for every $\varphi \geq 0 \in C_{c}^{2, L}(\bar{\Omega})$. This shows that $\alpha_{k} v_{n}$ is a super solution of the problem (51) and hence $w_{n} \leq \alpha_{k} v_{n}$. Since $w_{n, k} \leq w_{n}$, we obtain,

$$
0 \leq w_{n, k} \leq \alpha_{k} v_{n}
$$

As $\alpha_{k} v_{n} \leq v_{n}$ and $\left\{v_{n}\right\}$ is bounded in $L^{1}(\Omega)$, hence there exists a subsequence of $\left\{w_{n, k}\right\}$ which converges in $L^{1}(\Omega)$, for each $k \in \mathbb{N}$. The subsequence is still denoted by $\left\{w_{n, k}\right\}$. By the previous theorem, $\left\{\rho\left(g \circ w_{n, k}\right)\right\}$ converges weakly in $\bar{\Omega}$ for each $k$; we denote its limit by $\lambda_{k}$. Let $\left(\mu_{k}^{\#}, v_{k}^{\#}\right)$ be the reduced limit of $\left\{\alpha_{k} \mu_{n}, \alpha_{k} v_{n}\right\}$. Again by the previous theorem,

$$
v_{k}^{\#}=\alpha_{k} v-\frac{\left(\lambda_{k}-\alpha_{k} \tau\right)}{\mathbf{n} \cdot \mathbf{n} A^{T}} \chi_{\partial \Omega}
$$

As $w_{n, k} \leq \alpha_{k} v_{n}$, hence

$$
\rho\left(g \circ \alpha_{k} v_{n}\right)-\rho\left(g \circ w_{n, k}\right) \underset{\bar{\Omega}}{\stackrel{\rightharpoonup}{\rightharpoonup}} \sigma_{k}-\lambda_{k} \geq 0 .
$$

Now by our assumption, since the uniformly ellipticity condition (5) holds with $\alpha \geq 1$, hence we have $\sigma_{k}-\frac{\lambda_{k}}{\mathbf{n} \cdot \mathbf{n} A^{T}} \geq \sigma_{k}-\lambda_{k} \geq 0$ in $\bar{\Omega}$. Thus we obtain,

$$
\begin{equation*}
\left(\sigma_{k}-\frac{\lambda_{k}}{\mathbf{n} \cdot \mathbf{n} A^{T}}\right) \chi_{\partial \Omega}=\sigma_{k} \chi_{\partial \Omega}+v_{k}^{\#}-\alpha_{k}\left(v+\frac{\tau}{\mathbf{n} \cdot \mathbf{n} A^{T}} \chi_{\partial \Omega}\right) \geq 0 \tag{52}
\end{equation*}
$$

Let $u_{n}$ be the solution of (3) corresponding to $\mu=\mu_{n}, v=v_{n}$. By the comparison of solutions we have $w_{n, k} \leq u_{n}$ for all $k, n \in \mathbb{N}$. Consequently,

$$
w_{k}=\lim w_{n, k} \leq \lim u_{n}=u
$$

This implies that

$$
\begin{equation*}
v_{k}^{\#}=\operatorname{tr} w_{k} \leq \operatorname{tr} u \leq v^{\#} \tag{53}
\end{equation*}
$$

Finally, from (52) and (53), we get

$$
\begin{equation*}
\alpha_{k}\left(v+\frac{\tau}{\mathbf{n} \cdot \mathbf{n} A^{T}} \chi_{\partial \Omega}\right) \leq \sigma_{k} \chi_{\partial \Omega}+v^{\#} \tag{54}
\end{equation*}
$$

Since $g$ satisfies (48), hence for every $\epsilon>0$ there exists $a_{0}, t_{0}>1$, such that

$$
\begin{equation*}
\frac{g(x, a t)}{a g(x, t)} \geq \frac{1}{\epsilon}, \quad \forall a \geq a_{0}, t \geq t_{0} \tag{55}
\end{equation*}
$$

We split $\rho\left(g \circ \alpha_{k} v_{n}\right)$ as follows:

$$
\rho\left(g \circ \alpha_{k} v_{n}\right)=\rho\left(g \circ \alpha_{k} v_{n}\right) \chi_{\left[\alpha_{k} v_{n}<t_{0}\right]}+\rho\left(g \circ \alpha_{k} v_{n}\right) \chi_{\left[\alpha_{k} v_{n} \geq t_{0}\right]} .
$$

Now as $\rho\left(g \circ \alpha_{k} v_{n}\right) \underset{\bar{\Omega}}{\longrightarrow} \sigma_{k}$, hence let us say

$$
\rho\left(g \circ \alpha_{k} v_{n}\right) \chi_{\left[\alpha_{k} v_{n}<t_{0}\right]} \stackrel{\rightharpoonup}{\Omega} \sigma_{1, k} \text { and } \rho\left(g \circ \alpha_{k} v_{n}\right) \chi_{\left[\alpha_{k} v_{n} \geq t_{0}\right]} \stackrel{\rightharpoonup}{\Omega} \sigma_{2, k} .
$$

Since $\left\{\rho\left(g \circ \alpha_{k} v_{n}\right) \chi_{\left[\alpha_{k} v_{n}<t_{0}\right]}\right\}$ is uniformly bounded by $\rho\left(g \circ t_{0}\right)$, we have $\sigma_{1, k} \chi_{\partial \Omega}=0$. Thus $\sigma_{k} \chi_{\partial \Omega}=\sigma_{2, k} \chi_{\partial \Omega}$. But

$$
\left\|\sigma_{2, k}\right\|_{\mathfrak{M}(\bar{\Omega})} \leq \liminf \int_{\left[\alpha_{k} v_{n} \geq t_{0}\right]} \rho\left(g \circ \alpha_{k} v_{n}\right) .
$$

Therefore we obtain,

$$
\left\|\sigma_{k} \chi_{\partial \Omega}\right\|_{\mathfrak{M}(\partial \Omega)} \leq \liminf \int_{\left[\alpha_{k} v_{n} \geq t_{0}\right]} \rho\left(g \circ \alpha_{k} v_{n}\right) .
$$

Now as $\alpha_{k} \downarrow 0$, hence for sufficiently large $k$, say $k \geq k_{\epsilon}, \frac{1}{\alpha_{k}} \geq a_{0}$ we apply (55) with $a=\frac{1}{\alpha_{k}}, t=\alpha_{k} v_{n}$ to get

$$
\rho\left(g \circ \alpha_{k} v_{n}\right) \chi_{\left[\alpha_{k} v_{n} \geq t_{0}\right]} \leq \alpha_{k} \epsilon\left(g \circ v_{n}\right)
$$

for $k \geq k_{\epsilon}$ and $n \geq 1$. Hence

$$
\left\|\sigma_{k} \chi_{\partial \Omega}\right\|_{\mathfrak{M}(\partial \Omega)} \leq \epsilon \alpha_{k} \liminf \int_{\Omega} \rho\left(g \circ v_{n}\right) \leq c_{0} \epsilon \alpha_{k}
$$

for all $k \geq k_{\epsilon}$. Therefore

$$
\begin{equation*}
\frac{\left\|\sigma_{k} \chi_{\partial \Omega}\right\|_{\Re( }(\partial \Omega)}{\alpha_{k}} \rightarrow 0, \text { as } k \rightarrow \infty \tag{56}
\end{equation*}
$$

To complete the proof we will show that $v+\tau \chi_{\partial \Omega}$ is absolutely continuous with respect to measure $v^{\#}$. For this let $E \subset \partial \Omega$ be a Borel set such that $v^{\#}(E)=0$. Then by (54),

$$
\alpha_{k}\left(v(E)+\frac{\tau}{\mathbf{n} \cdot \mathbf{n} A^{T}}(E)\right) \leq \sigma_{k}(E), \quad \forall k \geq 1
$$

This inequality and (56) implies that

$$
v(E)+\frac{\tau}{\mathbf{n} \cdot \mathbf{n} A^{T}}(E) \leq \frac{\sigma_{k}(E)}{\alpha_{k}} \leq \frac{\left|\sigma_{k} \chi_{\partial \Omega}\right|(E)}{\alpha_{k}} \rightarrow 0
$$

as $k \rightarrow \infty$. Thus $v(E)+\frac{\tau}{\mathbf{n} \cdot \mathbf{n} A^{T}}(E)=0$. Hence the theorem.

## 4. Conclusions

The semilinear elliptic boundary value problem involving the general linear second order elliptic operator with a nonlinear function and Radon measures has been studied. Although the existence of very weak solution may fail for general measure data input, we however proved that the boundary value problem considered here with $L^{1}$ data possesses a unique very weak solution. We investigated the so-called reduced limits of the sequences $\left\{\mu_{n}, v_{n}\right\}$ of measures for a general linear elliptic operator $L$. It is showed that the reduced limits strictly depends not only on the sequence of input measure datum but also on the elliptic differential operator $L$. We also gave the relation between the weak limit and the reduced limits of sequences of the given measures.

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[^0]:    2010 Mathematics Subject Classification. Primary 35J25; Secondary 35J60, 35 J92
    Keywords. Elliptic PDE; Reduced limit; Good measure; Sobolev space
    Received: 21 August 2018; Accepted: 26 November 2018
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