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Reeb Flow Symmetry on 3-Dimensional Almost Paracosymplectic Manifolds

Irem Küpeli Erken^a

^aFaculty of Engineering and Natural Sciences, Department of Mathematics, Bursa Technical University, Bursa, TURKEY

Abstract. Mainly, we prove that the Ricci operator Q of an 3-dimensional almost paracosymplectic manifold M is invariant along the Reeb flow, that is M satisfies $\mathcal{L}_{\xi}Q = 0$ if and only if M is an almost paracosymplectic κ -manifold with $\kappa \neq -1$.

1. Introduction

Almost (para)contact metric structure is given by a pair (η , Φ), where η is a 1-form, Φ is a 2-form and $\eta \wedge \Phi^n$ is a volume element. It is well known that then there exists a unique vector field ξ , called the characteristic (Reeb) vector field, such that $i_{\xi}\eta = 1$, $i_{\xi}\Phi = 0$. The Riemannian or pseudo-Riemannian geometry appears if we try to introduce *a compatible* structure which is a metric or pseudo-metric *g* and an affinor φ ((1,1)-tensor field), such that

$$\Phi(X,Y) = q(\varphi X,Y), \quad \varphi^2 = \epsilon(Id - \eta \otimes \xi). \tag{1}$$

We have almost paracontact metric structure for $\epsilon = +1$ and almost contact metric for $\epsilon = -1$. Then, the triple (φ, ξ, η) is called almost paracontact structure or almost contact structure, resp.

Combining the assumption concerning the forms η and Φ , we obtain many different types of almost (para)contact manifolds, e.g. (para)contact if η is contact form and $d\eta = \Phi$, almost (para)cosymplectic if $d\eta = 0$, $d\Phi = 0$, almost (para)Kenmotsu if $d\eta = 0$, $d\Phi = 2\eta \land \Phi$.

Almost paracosymplectic manifolds were studied by [6], [7]. Later, İ. Küpeli Erken et al. study almost α -paracosymplectic manifolds in [11].

A paracontact metric manifold whose characteristic vector field ξ is a harmonic vector field is called an *H-paracontact* manifold. In [1], G. Calvaruso and D. Perrone proved that ξ is *harmonic* if and only if ξ is an eigenvector of the Ricci operator for contact semi-Riemannian manifolds. G. Calvaruso and D. Perrone [2] proved that all 3-dimensional homogeneous paracontact metric manifolds are *H*-paracontact. Recently, İ. Küpeli Erken, P. Dacko and C. Murathan in [11] study the harmonicity of the characteristic vector field of 3-dimensional almost α -paracosymplectic manifolds. It is proved that characteristic (Reeb) vector field ξ is harmonic on almost α -para-Kenmotsu manifold if and only if it is an eigenvector of the Ricci operator. 3-dimensional almost α -para-Kenmotsu manifolds are also classified.

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Email address: irem.erken@btu.edu.tr (Irem Küpeli Erken)

A symmetry in general relativity is a smooth vector field whose local flow diffeomorphisms preserve certain mathematical or physical quantities ([8], [9]). So, one can regard it as vector fields preserving certain geometric quantities like the metric tensor, the curvature tensor or the Ricci tensor in general relativity.

In [3–5], J.T. Cho study Reeb flow symmetry on almost contact and almost cosymplectic three-manifolds. Ricci collineations on 3-dimensional paracontact metric manifolds were studied in [12]. But no effort has been made to investigate Reeb flow symmetry on 3-dimensional almost paracosymplectic manifolds.

The class of almost paracontact manifolds with which we concerned holds the properties $\mathcal{L}_{\xi}\xi = \mathcal{L}_{\xi}\eta = 0$, that is, the Reeb vector field and its associated 1-form are invariant along the Reeb flow, or the Reeb flow yields a contact transformation, which means a diffeomorphism preserving a contact form. In the present work, we study such a class of almost paracontact metric three-manifolds whose Ricci operator Q is invariant along the Reeb flow ξ , that is, $\mathcal{L}_{\xi}Q = 0$.

The paper is organized in the following way.

Section 2 is preliminary section, where we recall the definition of almost paracontact metric manifold and the class of almost paracontact metric manifolds which are called almost α -paracosymplectic. Section 3 is focused on harmonicity of the characteristic vector field of 3-dimensional almost paracosymplectic manifolds. In Section 4, we proved that for any 3-dimensional almost paracosymplectic κ -manifold is η -Einstein and satisfies the condition $\xi(r) = 0$, where *r* denotes the scalar curvature. Also we proved that the Ricci operator *Q* on a 3-dimensional almost paracosymplectic manifold is invariant along the Reeb vector field if and only if the manifold is an almost paracosymplectic κ -manifold with $\kappa \neq -1$.

For the case $\kappa = -1$, we proved that $\mathcal{L}_{\xi}Q = 0$ if and only if $\nabla_{\xi}Q = 0$.

2. Preliminaries

An (2n + 1)-dimensional smooth manifold *M* is said to have an *almost paracontact structure* if it admits a (1, 1)-tensor field φ , a vector field ξ and a 1-form η satisfying the following conditions:

- (i) $\eta(\xi) = 1, \ \varphi^2 = I \eta \otimes \xi,$
- (ii) the tensor field φ induces an almost paracomplex structure on each fibre of $\mathcal{D} = \ker(\eta)$, i.e. the ±1-eigendistributions, $\mathcal{D}^{\pm} := \mathcal{D}_{\varphi}(\pm 1)$ of φ have equal dimension *n*.

From the definition it follows that $\varphi \xi = 0$, $\eta \circ \varphi = 0$ and the endomorphism φ has rank 2*n*. If an almost paracontact manifold admits a pseudo-Riemannian metric *g* such that

$$g(\varphi X, \varphi Y) = -g(X, Y) + \eta(X)\eta(Y), \tag{2}$$

for all $X, Y \in \Gamma(TM)$, then we say that $(M, \varphi, \xi, \eta, g)$ is an *almost paracontact metric manifold*.

On an almost paracontact metric manifold *M*, if the Ricci operator satisfies

 $Q = \alpha i d + \beta \eta \otimes \xi,$

where both α and β are smooth functions, then the manifold is said to be an η -*Einstein manifold*. Moreover, we can define a skew-symmetric tensor field (a 2-form) Φ by

$$\Phi(X,Y) = g(\varphi Y,X),\tag{3}$$

usually called fundamental form. Notice that any such a pseudo-Riemannian metric is necessarily of signature (n + 1, n). For an almost paracontact metric manifold, there always exists an orthogonal basis $\{X_1, \ldots, X_n, Y_1, \ldots, Y_n, \xi\}$ such that $g(X_i, X_j) = \delta_{ij}$, $g(Y_i, Y_j) = -\delta_{ij}$ and $Y_i = \varphi X_i$, for any $i, j \in \{1, \ldots, n\}$. Such basis is called a φ -basis.

On an almost paracontact manifold, one defines the (1, 2)-tensor field $N^{(1)}$ by

 $N^{(1)}(X,Y) = [\varphi,\varphi](X,Y) - 2d\eta(X,Y)\xi,$

where $[\varphi, \varphi]$ is the Nijenhuis torsion of φ

$$[\varphi,\varphi](X,Y) = \varphi^{2}[X,Y] + [\varphi X,\varphi Y] - \varphi[\varphi X,Y] - \varphi[X,\varphi Y].$$

If $N^{(1)}$ vanishes identically, then the almost paracontact manifold (structure) is said to be *normal* [13]. The normality condition says that the almost paracomplex structure *J* defined on $M \times \mathbb{R}$

$$J(X,\lambda\frac{d}{dt})=(\varphi X+\lambda\xi,\eta(X)\frac{d}{dt}),$$

is integrable.

An almost paracontact metric manifold M^{2n+1} , with a structure (φ, ξ, η, g) is said to be an *almost* α -*paracosymplectic manifold*, if

$$d\eta = 0, \quad d\Phi = 2\alpha\eta \wedge \Phi, \tag{4}$$

where α may be a constant or function on *M*.

For a particular choices of the function α we have the following subclasses,

• almost α -para-Kenmotsu manifolds, $\alpha = const. \neq 0$,

• almost paracosymplectic manifolds, $\alpha = 0$.

If additionally normality conditon is fulfilled, then manifolds are called α -para-Kenmotsu or paracosymplectic, resp.

İ. Küpeli Erken et al. proved the following results in [11]. We will use them in our original results.

Proposition 2.1. [11] For an almost α -paracosymplectic manifold M^{2n+1} , we have

$$i) \mathcal{L}_{\xi} \eta = 0, ii) g(\mathcal{A}X, Y) = g(X, \mathcal{A}Y), iii) \mathcal{A}\xi = 0,$$

$$iv) \mathcal{L}_{\xi} \Phi = 2\alpha \Phi, v) (\mathcal{L}_{\xi}g)(X, Y) = -2g(\mathcal{A}X, Y),$$

$$vi) \eta(\mathcal{A}X) = 0, vii) d\alpha = f\eta \text{ if } n \ge 2$$
(5)

where \mathcal{L} indicates the operator of the Lie differentiation, X, Y are arbitrary vector fields on M^{2n+1} and $f = i_{\xi} d\alpha$.

Proposition 2.2. [11] For an almost α -paracosymplectic manifold, we have

$$\mathcal{A}\varphi + \varphi \mathcal{A} = -2\alpha\varphi, \tag{6}$$
$$\nabla_{\xi}\varphi = 0. \tag{7}$$

Let define $h = \frac{1}{2}\mathcal{L}_{\xi}\varphi$. In the following proposition we establish some properties of the tensor field *h*.

Proposition 2.3. [11]For an almost α -paracosymplectic manifold, we have the following relations

$$g(hX,Y) = g(X,hY), \tag{8}$$

$$h \circ \varphi + \varphi \circ h = 0,$$

$$h\xi = 0,$$

$$\nabla \xi = \alpha \varphi^{2} + \varphi \circ h = -\mathcal{A}.$$
(9)
(10)
(11)

Corollary 2.4. [11]All the above Propositions imply the following formulas for the traces

$$tr(\mathcal{A}\varphi) = tr(\varphi\mathcal{A}) = 0, tr(h\varphi) = tr(\varphi h) = 0,$$

$$tr(\mathcal{A}) = -2\alpha n, tr(h) = 0.$$
 (12)

Theorem 2.5. [11]Let $(M^{2n+1}, \varphi, \xi, \eta, g)$ be an almost α -para-Kenmotsu manifold. Then, for any $X, Y \in \chi(M^{2n+1})$,

$$R(X,Y)\xi = \alpha\eta(X)(\alpha Y + \varphi hY) - \alpha\eta(Y)(\alpha X + \varphi hX) + (\nabla_X \varphi h)Y - (\nabla_Y \varphi h)X.$$
(13)

Theorem 2.6. [11]Let $(M^{2n+1}, \varphi, \xi, \eta, g)$ be an almost α -para-Kenmotsu manifold. Then, for any $X \in \chi(M^{2n+1})$ we have

$$R(\xi, X)\xi = \alpha^2 \varphi^2 X + 2\alpha \varphi h X - h^2 X + \varphi(\nabla_{\xi} h) X,$$
(14)

$$(\nabla_{\xi}h)X = -\alpha^{2}\varphi X - 2\alpha hX + \varphi h^{2}X - \varphi R(X,\xi)\xi, \qquad (15)$$

$$\frac{1}{2}(R(\xi,X)\xi + \varphi R(\xi,\varphi X)\xi) = \alpha^2 \varphi^2 X - h^2 X,$$
(16)

$$S(X,\xi) = -2n\alpha^2 \eta(X) + g(div(\varphi h), X), \qquad (17)$$

$$S(\xi,\xi) = -2n\alpha^2 + trh^2 \tag{18}$$

where S(X, Y) = g(QX, Y).

Henceforward, we denote $S_{ij} = S(e_i, e_j)$ for i, j = 1, 2, 3.

3. Classification of the 3-Dimensional Almost Paracosymplectic Manifolds

In this section, we will give the summary of the classification of 3-dimensional almost paracosymplectic manifolds. 3-dimensional almost paracosymplectic manifolds under assumption that the curvature satisfies (κ , μ , ν)-nullity condition

$$R(X,Y)\xi = \eta(Y)BX - \eta(X)BY,$$
(19)

where *B* is Jacobi operator of ξ , $BX = R(X, \xi)\xi$, and

$$BX = \kappa \varphi^2 X + \mu h X + \nu \varphi h X,$$

for all $X, Y \in \Gamma(TM)$, where κ, μ, ν are smooth functions on M. Particularly $B\xi = 0$.

If an almost paracosymplectic manifold satisfies (19), then the manifold is said to be *almost paracosymplectic* (κ , μ , ν)-*space*.

A 3-dimensional almost paracosymplectic manifold κ -manifold satisfies [11]

$$Q\xi = 2\kappa\xi.$$
(20)

Theorem 3.1. [11]Let $(M^{2n+1}, \varphi, \xi, \eta, g)$ be an almost α -para-Kenmotsu manifold. Characteristic vector field ξ is harmonic if and only if it is an eigenvector of the Ricci operator.

Beside the other results, the different possibilities for the tensor field *h* are analyzed in [11].

The tensor *h* has the canonical form (I). Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -paracosymplectic manifold. Then operator *h* has following types.

 $U_1 = \{p \in M \mid h(p) \neq 0\} \subset M$

 $U_2 = \{p \in M \mid h(p) = 0, \text{ in a neighborhood of } p\} \subset M$

That *h* is a smooth function on *M* implies $U_1 \cup U_2$ is an open and dense subset of *M*, so any property satisfied in $U_1 \cup U_2$ is also satisfied in *M*. For any point $p \in U_1 \cup U_2$ there exists a local orthonormal φ -basis $\{e, \varphi e, \xi\}$ of smooth eigenvectors of *h* in a neighborhood of *p*, where $-g(e, e) = g(\varphi e, \varphi e) = g(\xi, \xi) = 1$. On U_1 we put $he = \lambda e$, where λ is a non-vanishing smooth function. Since trh = 0, we have $h\varphi e = -\lambda \varphi e$. The eigenvalue function λ is continuous on *M* and smooth on $U_1 \cup U_2$. So, *h* has following form

$$\begin{pmatrix}
\lambda & 0 & 0 \\
0 & -\lambda & 0 \\
0 & 0 & 0
\end{pmatrix}$$
(21)

respect to local orthonormal φ -basis { $e, \varphi e, \xi$ }. In this case, we will say the operator *h* is of \mathfrak{h}_1 *type*.

Lemma 3.2. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_1 type. Then for the covariant derivative on \mathcal{U}_1 the following equations are valid

$$i) \nabla_{e}e = \frac{1}{2\lambda} \left[\sigma(e) - (\varphi e)(\lambda) \right] \varphi e + \alpha \xi,$$

$$ii) \nabla_{e}\varphi e = \frac{1}{2\lambda} \left[\sigma(e) - (\varphi e)(\lambda) \right] e - \lambda \xi,$$

$$iii) \nabla_{e}\xi = \alpha e + \lambda \varphi e,$$

$$iv) \nabla_{\varphi e}\xi = \alpha e + \lambda \varphi e,$$

$$iv) \nabla_{\varphi e}\varphi e = -\frac{1}{2\lambda} \left[\sigma(\varphi e) + e(\lambda) \right] \varphi e - \lambda \xi,$$

$$v) \nabla_{\varphi e}\varphi e = -\frac{1}{2\lambda} \left[\sigma(\varphi e) + e(\lambda) \right] \varphi e - \alpha \xi,$$

$$vi) \nabla_{\varphi e}\xi = \alpha \varphi e - \lambda e,$$

$$vii) \nabla_{\xi}e = a_{1}\varphi e, \quad viii) \nabla_{\xi}\varphi e = a_{1}e,$$

$$ix) \left[e, \xi \right] = \alpha e + (\lambda - a_{1})\varphi e,$$

$$x) \left[\varphi e, \xi \right] = -(\lambda + a_{1})e + \alpha \varphi e,$$

$$xi) \left[e, \varphi e \right] = \frac{1}{2\lambda} \left[\sigma(e) - (\varphi e)(\lambda) \right] e + \frac{1}{2\lambda} \left[\sigma(\varphi e) + e(\lambda) \right] \varphi e,$$

$$xii) h^{2} - \alpha^{2}\varphi^{2} = \frac{1}{2} S(\xi, \xi)\varphi^{2}$$

$$(22)$$

where

$$a_1 = g(\nabla_{\xi} e, \varphi e), \ \sigma = S(\xi, .)_{\ker \eta}.$$

Proposition 3.3. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_1 type. Then we have

$$\nabla_{\xi}h = -2a_1h\varphi + \xi(\lambda)s,\tag{23}$$

where s is the (1, 1)-type tensor defined by $s\xi = 0$, se = e, $s\varphi e = -\varphi e$.

Lemma 3.4. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_1 type. Then the Ricci operator Q is given by

$$Q = \left(\frac{r}{2} + \alpha^2 - \lambda^2\right)I + \left(-\frac{r}{2} + 3(\lambda^2 - \alpha^2)\right)\eta \otimes \xi - 2\alpha\varphi h - \varphi(\nabla_{\xi}h) + \sigma(\varphi^2) \otimes \xi - \sigma(e)\eta \otimes e + \sigma(\varphi e)\eta \otimes \varphi e$$
(24)

where r denotes scalar curvature.

Moreover from (24) the components of the Ricci operator Q are can be given by

$$Q\xi = 2(\lambda^{2} - \alpha^{2})\xi - \sigma(e)e + \sigma(\varphi e)\varphi e,$$

$$Qe = \sigma(e)\xi + (\frac{r}{2} + \alpha^{2} - \lambda^{2} - 2a_{1}\lambda)e - (2\alpha\lambda + \xi(\lambda))\varphi e,$$

$$Q\varphi e = \sigma(\varphi e)\xi + (2\alpha\lambda + \xi(\lambda))e + (\frac{r}{2} + \alpha^{2} - \lambda^{2} + 2a_{1}\lambda)\varphi e.$$
(25)

From (25), we get

$$S_{11} = -(\frac{r}{2} + \alpha^2 - \lambda^2 - 2a_1\lambda), S_{12} = -(2\alpha\lambda + \xi(\lambda)), S_{22} = (\frac{r}{2} + \alpha^2 - \lambda^2 + 2a_1\lambda), S_{11} + S_{22} = 4a_1\lambda.$$
(26)

The tensor *h* has the canonical form (II). Using same methods in [10], one can construct a local pseudoorthonormal basis $\{e_1, e_2, e_3\}$ in a neighborhood of *p* where $g(e_1, e_1) = g(e_2, e_2) = g(e_1, e_3) = g(e_2, e_3) = 0$ and $g(e_1, e_2) = g(e_3, e_3) = 1$. Let \mathcal{U} be the open subset of M where $h \neq 0$. For every $p \in \mathcal{U}$ there exists an open neighborhood of p such that $he_1 = e_2, he_2 = 0, he_3 = 0$ and $\varphi e_1 = \pm e_1, \varphi e_2 = \pm e_2, \varphi e_3 = 0$ and also $\xi = e_3$. Thus the tensor h has the form

$$\left(\begin{array}{ccc}
0 & 0 & 0 \\
1 & 0 & 0 \\
0 & 0 & 0
\end{array}\right)$$
(27)

relative a pseudo-orthonormal basis $\{e_1, e_2, e_3\}$. In this case, we call *h* is of \mathfrak{h}_2 *type*.

Remark 3.5. Without loss of generality, we can assume that $\varphi e_1 = e_1 \varphi e_2 = -e_2$. Moreover one can easily get $h^2 = 0$ but $h \neq 0$.

Lemma 3.6. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_2 type. Then for the covariant derivative on \mathcal{U} the following equations are valid

$$i) \nabla_{e_{1}e_{1}} = -b_{1}e_{1} + \xi, \quad ii) \nabla_{e_{1}}e_{2} = b_{1}e_{2} - \alpha\xi, \quad iii) \nabla_{e_{1}}\xi = \alpha e_{1} - e_{2},$$

$$iv) \nabla_{e_{2}}e_{1} = -b_{2}e_{1} - \alpha\xi, \quad v) \nabla_{e_{2}}e_{2} = b_{2}e_{2}, \quad vi) \nabla_{e_{2}}\xi = \alpha e_{2},$$

$$vii) \nabla_{\xi}e_{1} = a_{2}e_{1}, \quad viii) \nabla_{\xi}e_{2} = -a_{2}e_{2},$$

$$ix) [e_{1}, \xi] = (\alpha - a_{2})e_{1} - e_{2}, \quad x) [e_{2}, \xi] = (\alpha + a_{2})e_{2},$$

$$xi) [e_{1}, e_{2}] = b_{2}e_{1} + b_{1}e_{2},$$

$$xii) h^{2} = 0.$$
(28)

where $a_2 = g(\nabla_{\xi}e_1, e_2), b_1 = g(\nabla_{e_1}e_2, e_1)$ and $b_2 = g(\nabla_{e_2}e_2, e_1) = -\frac{1}{2}\sigma(e_1)$.

Proposition 3.7. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_2 type. Then we have

$$\nabla_{\xi} h = 2a_2 \varphi h,\tag{29}$$

on ${\cal U}$.

Lemma 3.8. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_2 type. Then the Ricci operator Q is given by

$$Q = (\frac{r}{2} + \alpha^2)I - (\frac{r}{2} + 3\alpha^2)\eta \otimes \xi - 2\alpha\varphi h - \varphi(\nabla_{\xi}h) + \sigma(\varphi^2) \otimes \xi + \sigma(e_1)\eta \otimes e_2.$$
(30)

A consequence of Lemma 3.8, we can give the components of the Ricci operator Q by following,

$$Q\xi = \sigma(e_1)e_2 - 2\alpha^2\xi,$$

$$Qe_1 = \sigma(e_1)\xi + (\frac{r}{2} + \alpha^2)e_1 - 2(a_2 - \alpha)e_2,$$

$$Qe_2 = (\frac{r}{2} + \alpha^2)e_2.$$
(31)

The tensor *h* has the canonical form (III). We can find a local orthonormal φ -basis $\{e, \varphi e, \xi\}$ in a neighborhood of *p* where $-g(e, e) = g(\varphi e, \varphi e) = g(\xi, \xi) = 1$. Now, let \mathcal{U}_1 be the open subset of *M* where $h \neq 0$ and let \mathcal{U}_2 be the open subset of points $p \in M$ such that h = 0 in a neighborhood of *p*. $\mathcal{U}_1 \cup \mathcal{U}_2$ is an open subset of *M*. For every $p \in \mathcal{U}_1$ there exists an open neighborhood of *p* such that $h = \lambda \varphi e, h\varphi e = -\lambda e$ and $h\xi = 0$ where λ is a non-vanishing smooth function. Since trh = 0, the matrix form of *h* is given by

$$\begin{pmatrix} 0 & -\lambda & 0 \\ \lambda & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$
 (32)

with respect to local orthonormal basis $\{e, \varphi e, \xi\}$. In this case, we say that *h* is of \mathfrak{h}_3 *type*.

Lemma 3.9. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_3 type. Then for the covariant derivative on \mathcal{U}_1 the following equations are valid

$$i) \nabla_{e}e = b_{3}\varphi e + (\alpha + \lambda)\xi, \quad ii) \nabla_{e}\varphi e = b_{3}e, \quad iii) \nabla_{e}\xi = (\alpha + \lambda)e,$$

$$iv) \nabla_{\varphi e}e = b_{4}\varphi e, \quad v) \nabla_{\varphi e}\varphi e = b_{4}e + (\lambda - \alpha)\xi, \quad vi) \nabla_{\varphi e}\xi = -(\lambda - \alpha)\varphi e,$$

$$vii) \nabla_{\xi}e = a_{3}\varphi e, \quad viii) \nabla_{\xi}\varphi e = a_{3}e,$$

$$ix) [e, \xi] = (\alpha + \lambda)e - a_{3}\varphi e, \quad x) [\varphi e, \xi] = -a_{3}e - (\lambda - \alpha)\varphi e,$$

$$xi) [e, \varphi e] = b_{3}e - b_{4}\varphi e,$$

$$xii)h^{2} - \alpha^{2}\varphi^{2} = \frac{1}{2}S(\xi, \xi)\varphi^{2},$$
(33)

where $a_3 = g(\nabla_{\xi} e, \varphi e), b_3 = -\frac{1}{2\lambda} \left[\sigma(\varphi e) + (\varphi e)(\lambda) \right]$ and $b_4 = \frac{1}{2\lambda} \left[\sigma(e) - e(\lambda) \right]$.

Proposition 3.10. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_3 type. So, on U_1 we have

$$\nabla_{\xi}h = -2a_3h\varphi + \xi(\lambda)s,\tag{34}$$

where s is the (1, 1)-type tensor defined by $s\xi = 0$, $se = \varphi e$, $s\varphi e = -e$.

Lemma 3.11. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold with h of \mathfrak{h}_3 type. Then the Ricci operator Q is given by

$$Q = a I + b\eta \otimes \xi - 2\alpha\varphi h - \varphi(\nabla_{\xi}h) + \sigma(\varphi^2) \otimes \xi - \sigma(e)\eta \otimes e + \sigma(\varphi e)\eta \otimes \varphi e,$$
(35)

where *a* and *b* are smooth functions defined by $a = \alpha^2 + \lambda^2 + \frac{r}{2}$ and $b = -3(\lambda^2 + \alpha^2) - \frac{r}{2}$, respectively.

Moreover from the above Lemma the components of the Ricci operator *Q* are given by

$$Q\xi = -2(\alpha^{2} + \lambda^{2})\xi - \sigma(e)e + \sigma(\varphi e)\varphi e,$$

$$Qe = \sigma(e)\xi + (\alpha^{2} + \lambda^{2} + \frac{r}{2} - \xi(\lambda))e - 2a_{3}\lambda\varphi e,$$

$$Q\varphi e = \sigma(\varphi e)\xi + 2a_{3}\lambda e + (\alpha^{2} + \lambda^{2} + \frac{r}{2} + \xi(\lambda))\varphi e.$$
(36)

From (36), we get

$$S_{11} = -(\alpha^2 + \lambda^2 + \frac{r}{2} - \xi(\lambda)), S_{12} = -2a_3\lambda, S_{22} = (\alpha^2 + \lambda^2 + \frac{r}{2} + \xi(\lambda)), S_{11} + S_{22} = 2\xi(\lambda).$$
(37)

Theorem 3.12. [11]Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost α -para-Kenmotsu manifold. If the characteristic vector field ξ is harmonic map then almost α -paracosymplectic (κ, μ, ν) -manifold always exist on every open and dense subset of M. Conversely, if M is an almost α -paracosymplectic (κ, μ, ν) -manifold with constant α then the characteristic vector field ξ is harmonic map.

4. Reeb Flow Symmetry on 3-Dimensional Almost Paracosymplectic Manifolds

In this section, we will study reeb flow symmetry on 3-dimensional almost paracosymplectic manifolds. So, we will take $\alpha = 0$ in results which were given in Section 3.

We recall that the curvature tensor of a 3-dimensional pseudo-Riemannian manifold satisfies

$$R(X,Y)Z = g(Y,Z)QX - g(X,Z)QY + g(QY,Z)X - g(QX,Z)Y - \frac{r}{2}(g(Y,Z)X - g(X,Z)Y)$$
(38)

for all vector fields X, Y, Z, where r denotes the scalar curvature

First of all, we will investigate three possibilities according to canonical form *h* of 3-dimensional almost paracosymplectic manifold.

Case1: We suppose that *h* is \mathfrak{h}_1 type ($\kappa > -1$).

Lemma 4.1. Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost paracosymplectic manifold. If h is \mathfrak{h}_1 type on U_1 , then we have,

$$\mathcal{L}_{\xi}Q = 0$$
 if and only if $\nabla_{\xi}Q = 0$ and $Q\xi = \rho\xi$, where ρ is a function.

Proof. Assume that *M* satisfies $\mathcal{L}_{\xi}Q = 0$. In this case, we have

$$\mathcal{L}_{\xi}(QX) - Q(\mathcal{L}_{\xi}X) = 0$$

$$[\xi, QX] - Q[\xi, X] = 0.$$

From (11), we obtain an equivalent equation to $\mathcal{L}_{\xi}Q = 0$ as follows

$$(\nabla_{\xi}Q)X = (\varphi h Q - Q\varphi h)X. \tag{39}$$

Since $\nabla_{\xi} Q$ is self-adjoint operator, it follows that

$$Q\varphi h - \varphi h Q = Qh\varphi - h\varphi Q.$$

Using the anti-commutative property *h* with φ in the last equation, we have

$$Q\varphi h = \varphi h Q. \tag{40}$$

Hence, from (39) and (40), we get $\nabla_{\xi}Q = 0$ on U_1 . Applying ξ to both sides of (40), we get $hQ\xi = 0$. Using this in the first equation of (25), we obtain $Q\xi = \rho\xi$, $\rho = 2\lambda^2$ on U_1 . Conversely, we assume that $\nabla_{\xi}Q = 0$ and $Q\xi = \rho\xi$, on U_1 . By (18), we find that $\rho = 2\lambda^2$ and

$$S_{13} = S_{31} = 0, \quad S_{23} = S_{32} = 0.$$
 (41)

After some calculations using the fact that $(\nabla_{\xi} S)(\xi, \xi) = 0$ and $\nabla_{\xi} \xi = 0$, one can get

$$\xi(\lambda) = 0. \tag{42}$$

Using the second equation of (25), we obtain $S_{12} = g(Qe_1, e_2) = -\xi(\lambda) = 0$. So we have

$$S_{12} = S_{21} = 0. (43)$$

If we take the covariant derivative of (43) according to ξ and use (22) and $\nabla_{\xi}Q = 0$, we obtain

$$a_1(S_{22} + S_{11}) = 0. (44)$$

By the help of (26) and (44) we find $a_1 = 0$ and

$$S_{11} = -S_{22}.$$
 (45)

From the assumption of $Q\xi = \rho\xi$ and the equations (41), (43) and (45) we get

$$Qe = \left(\frac{r}{2} - \lambda^2\right)e$$

$$Q\varphi e = \left(\frac{r}{2} - \lambda^2\right)\varphi e.$$
(46)

So, we can see $Q\phi h = \phi h Q$ by using (46). Hence, $\mathcal{L}_{\xi} Q = 0$ comes from (39).

Remark 4.2. In Lemma 4.1, for a 3-dimensional almost paracosymplectic manifold with h is \mathfrak{h}_1 type on U_1 , we proved that if $\nabla_{\xi}Q = 0$ and $Q\xi = \rho\xi$, then $\xi(\lambda) = 0$. Now, accept $\mathcal{L}_{\xi}Q = 0$ on U_1 . Using $(\nabla_{\xi}S)(\xi, \xi) = 0$ and $\nabla_{\xi}\xi = 0$, one can get $\xi(\lambda) = 0$. Also, by definition of Ricci curvature S, we have $S_{12} = S_{21} = 0$. From (40) we have $S_{22} = -S_{11} = 0$, $a_1 = 0$. Moreover, one can write $r = -S(e, e) + S(\varphi e, \varphi e) + S(\xi, \xi) = 2(S_{22} + \lambda^2) = 2(-S_{11} + \lambda^2)$.

We now check whether λ is constant or not.

In view of (38), Lemma 4.1 and Remark 4.2, the following formulas hold in U_1

$$R(e, \varphi e)\varphi e = Qe - \lambda^{2}e,$$

$$R(e, \varphi e)e = Q\varphi e - \lambda^{2}\varphi e,$$

$$R(\varphi e, \xi)\varphi e = -\lambda^{2}\xi,$$

$$R(e, \xi)e = \lambda^{2}\xi,$$

$$R(e, \xi)\xi = \lambda^{2}e,$$

$$R(\varphi e, \xi)\xi = \lambda^{2}\varphi e,$$
(47)

where $R(e_i, e_j)e_k = 0$, for $i \neq j \neq k$.

On the other hand, taking into account, (22) and (47), direct calculations give

$$(\nabla_{e}R)(\varphi e, \xi)\varphi e = -e(\lambda^{2})\xi,$$

$$(\nabla_{\varphi e}R)(\xi, e)\varphi e = 0,$$

$$(\nabla_{\xi}R)(e, \varphi e)\varphi e = \xi(\frac{r}{2} - \lambda^{2})e,$$

$$(\nabla_{\varphi e}R)(e, \xi)e = \varphi e(\lambda^{2})\xi,$$

$$(\nabla_{e}R)(\xi, \varphi e)e = 0,$$

$$(\nabla_{\xi}R)(\varphi e, e)e = -\xi(\frac{r}{2} - \lambda^{2})\varphi e.$$

$$(48)$$

With the help of second bianchi identity and (48), we find $e(\lambda) = 0$ and $\varphi e(\lambda) = 0$. Regarding $\xi(\lambda) = 0$, we can conclude that λ is constant on M.

So we can state following

Lemma 4.3. λ *is constant.*

Using Lemma 4.3, (22) returns to

$$\begin{split} i) \nabla_e e &= 0, \ ii) \nabla_e \varphi e = -\lambda \xi, \\ iii) \nabla_e \xi &= \lambda \varphi e, \\ iv) \nabla_{\varphi e} e &= -\lambda \xi, \ v) \nabla_{\varphi e} \varphi e = 0, \\ vi) \nabla_{\varphi e} \xi &= -\lambda e, \\ vii) \nabla_{\xi} e &= 0, \ viii) \nabla_{\xi} \varphi e = 0, \\ ix) [e, \xi] &= \lambda \varphi e, \ x) [\varphi e, \xi] = -\lambda e, \\ xi) [e, \varphi e] &= 0. \end{split}$$

In view of (47) and (49), we have

$$Qe = 0, Q\varphi e = 0, Q\xi = 2\lambda^2 \xi.$$
⁽⁵⁰⁾

From (50) we can easily see that $(\mathcal{L}_{\xi}Q)e = (\mathcal{L}_{\xi}Q)\varphi e = 0$.

Case2: We suppose that *h* is \mathfrak{h}_3 type ($\kappa < -1$).

As the proof of the following lemma is similar to Lemma 4.1, we don't give its proof.

Lemma 4.4. Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost paracosymplectic manifold. If h is \mathfrak{h}_3 type on U_1 , then we have,

 $\mathcal{L}_{\xi}Q = 0$ if and only if $\nabla_{\xi}Q = 0$ and $Q\xi = \rho\xi$, where ρ is a function.

(49)

We now check whether λ is constant or not.

In view of (38) and Lemma 4.4, the following formulas hold in U_1

$$R(e, \varphi e)\varphi e = Qe + \lambda^{2}e,$$

$$R(e, \varphi e)e = Q\varphi e + \lambda^{2}\varphi e,$$

$$R(\varphi e, \xi)\varphi e = \lambda^{2}\xi,$$

$$R(e, \xi)e = -\lambda^{2}\xi,$$

$$R(e, \xi)\xi = -\lambda^{2}e,$$

$$R(\varphi e, \xi)\xi = -\lambda^{2}\varphi e,$$
(51)

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where $R(e_i, e_j)e_k = 0$, for $i \neq j \neq k$.

On the other hand, taking into account, (33) and (51), direct calculations give

$$(\nabla_{e}R)(\varphi e, \xi)\varphi e = \lambda(\frac{r}{2} + 3\lambda^{2})e + e(\lambda^{2})\xi,$$

$$(\nabla_{\varphi e}R)(\xi, e)\varphi e = -\lambda(\frac{r}{2} + 3\lambda^{2})e,$$

$$(\nabla_{\xi}R)(e, \varphi e)\varphi e = \xi(\frac{r}{2} + \lambda^{2})e,$$

$$(\nabla_{\varphi e}R)(e, \xi)e = -\varphi e(\lambda^{2})\xi + \lambda(\frac{r}{2} + 3\lambda^{2})\varphi e,$$

$$(\nabla_{e}R)(\xi, \varphi e)e = -\lambda(\frac{r}{2} + 3\lambda^{2})\varphi e,$$

$$(\nabla_{\xi}R)(\varphi e, e)e = -\xi(\frac{r}{2} + \lambda^{2})\varphi e.$$
(52)

With the help of second bianchi identity and (52), we find $e(\lambda) = 0$ and $\varphi e(\lambda) = 0$. Regarding $\xi(\lambda) = 0$, we can conclude that λ is constant on M.

So we can state following

Lemma 4.5. λ *is constant.*

Using Lemma 4.5, (33) returns to

$$i) \nabla_{e} e = \lambda \xi, \quad ii) \nabla_{e} \varphi e = 0,$$

$$iii) \nabla_{e} \xi = \lambda e,$$

$$iv) \nabla_{\varphi e} e = 0, \quad v) \nabla_{\varphi e} \varphi e = \lambda \xi,$$

$$vi) \nabla_{\varphi e} \xi = -\lambda \varphi e,$$

$$vi) \nabla_{\xi} e = 0, \quad viii) \nabla_{\xi} \varphi e = 0,$$

$$ix) [e, \xi] = \lambda e, \quad x) [\varphi e, \xi] = -\lambda \varphi e,$$

$$xi) [e, \varphi e] = 0.$$
(53)

In view of (51) and (53), we have

$$Qe = 0, Q\varphi e = 0, Q\xi = -2\lambda^2\xi.$$
(54)

From (54) we can easily see that $(\mathcal{L}_{\xi}Q)e = (\mathcal{L}_{\xi}Q)\varphi e = 0$.

Theorem 4.6. Any 3-dimensional almost paracosymplectic κ -manifold is η -Einstein and also we have

$$\xi(r) = 0. \tag{55}$$

Proof. If we replace Y = Z by ξ in (38) and use (19), (20) we get

$$QX = \left(\frac{r}{2} - \kappa\right)X + \left(-\frac{r}{2} + 3\kappa\right)\eta(X)\xi\tag{56}$$

for any vector field $X \in \chi(M)$. So, the manifold is η -Einstein. If we use (56), (11) and (20) in the following well known formula for semi-Riemannian manifolds

$$trace \{Y \to (\nabla_Y Q)X\} = \frac{1}{2} \nabla_X r$$

we obtain $\xi(r) = 0$. \Box

Theorem 4.7. Let *M* be a 3-dimensional almost paracosymplectic manifold. Then $\mathcal{L}_{\xi}Q = 0$ if and only if *M* is an almost paracosymplectic κ -manifold with $\kappa \neq -1$.

Proof. Assume that *M* is a 3-dimensional almost paracosymplectic manifold with *h* of \mathfrak{h}_1 type whose Ricci operator *Q* satisfies $\mathcal{L}_{\xi}Q = 0$. If we take into account Theorem 3.1, Theorem 3.12 and Lemma 4.1, together we obtain that *M* is an almost paracosymplectic κ -manifold with $\kappa = \lambda^2$. Conversely, let *M* is an almost paracosymplectic κ -manifold with $\kappa = \lambda^2$. Conversely, let *M* is an almost paracosymplectic κ -manifold with $\kappa = \lambda^2$. Conversely, let *M* is an almost paracosymplectic κ -manifold with $\kappa \neq -1$. Using Lemma 4.3 and (55), if we take the Lie derivative of (56) according to ξ , we get $\mathcal{L}_{\xi}Q = 0$. The proof for a 3-dimensional almost paracosymplectic manifold with *h* of \mathfrak{h}_3 type is similar to this proved case. So, we complete the proof of the theorem. \Box

Case3:We suppose that *h* is \mathfrak{h}_2 type ($\kappa = -1$).

The proof of following theorem is similar to the Case1(*h* is \mathfrak{h}_1 type). But in this case, one can should be careful while computing because of $g(e_1, e_1) = g(e_2, e_2) = g(e_1, e_3) = g(e_2, e_3) = 0$ and $g(e_1, e_2) = g(e_3, e_3) = 1$.

Theorem 4.8. Let $(M, \varphi, \xi, \eta, g)$ be a 3-dimensional almost paracosymplectic manifold. If h is \mathfrak{h}_2 type on U, then we have,

$$\mathcal{L}_{\xi}Q = 0$$
 if and only if $\nabla_{\xi}Q = 0$.

Remark 4.9. For a 3-dimensional almost paracosymplectic manifold with h is \mathfrak{h}_2 type on U. Then $\mathcal{L}_{\xi}Q = 0$ if and only if $\xi(\sigma(e_1)) - a_2\sigma(e_1) = 0$, $\xi(r) = 0$ and $\xi(a_2) - 2a_2^2 = 0$. Using (28) and (31), one can calculate these relations.

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