



A Note on the Group Inverses of Block Matrices Over Rings

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Abstract. Suppose R is an associative ring with identity 1. The purpose of this paper is to give some necessary and sufficient conditions for the existence and the representations of the group inverse of the block matrix $\begin{pmatrix} AX + YB & A \\ B & 0 \end{pmatrix}$ and $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$ under some conditions. Some examples are given to illustrate our results.

1. The first section

The Drazin (group) inverse of 2×2 block matrices have numerous applications in many areas, especially in singular differential and difference equations and finite Markov chains (see [1,4,5,7,15]). In 1979, Campbell and Meyer proposed a problem to find a concrete expression for Drazin (group) inverse of block matrices $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$, where A and D are square but need not to be the same size (see [1]). Although the problem has not been solved completely yet, ones have got results on group inverses under some special conditions in [2,3,6,9-11,16-18,21].

The purpose of this paper is to extend some recent results on the group inverse of block matrices, as for basic ring and matrix type.

In [23], Li et al. investigate the group inverse of the block matrix $\begin{pmatrix} AX + YB & A \\ B & 0 \end{pmatrix}$ over skew filed under the conditions $A^\#$ exists, $XA = AX$, and $r(A) = r(AX)$. This generalizes Theorem 1.1 of [8]. In this paper, the sufficient and necessary condition for the existence of the group inverse of the above partitioned matrix over any ring is characterized.

In [13], Bu et al. investigated the group inverse of the block matrix $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ over skew filed under the conditions A is invertible and $(D - CA^{-1}B)^\#$ exists. In [19], Deng et al. studied the group inverse of the block matrix $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ over complex Banach spaces under the conditions A and $S = D - CA^\#B$ are group invertible, $A^\tau B = 0$ and $S^\tau C = 0$. In this paper, we will investigate the group inverse of the above block matrix over rings under weaker conditions. We should pointed that the methods of solving problems are quite different from those of [13, 14, 19, 20].

2010 *Mathematics Subject Classification.* Primary 15A09; Secondary 16U30

Keywords. Ring; Group inverse; Block matrix; anti-triangular

Received: 04 March 2015; Accepted: 11 July 2015

Communicated by Dragan S. Djordjević

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Let R, K be an associative ring with identity 1 and skew field, respectively. $R^{m \times n}$ be the set of all $m \times n$ matrices over R . We denote $R^{m \times 1}$ and $R^{1 \times n}$ by R^m and $R^{(n)}$, respectively. For $A \in R^{n \times n}$, if there exists a matrix $X \in R^{n \times n}$ such that $AXA = A$, $XAX = X$ and $AX = XA$, then X is called the group inverse of A and can be denoted by $A^\#$. For $A \in R^{n \times m}$, if X satisfies only $AXA = A$, then A is called regular and X is called a $\{1\}$ -inverse or regular inverse of A . In this case, denote the set of all $\{1\}$ -inverse of A by $A\{1\}$. Let $A^{(1)}$ be any $\{1\}$ -inverse of A , denote $I - A^{(1)}A$ and $I - AA^{(1)}$ by $A^{\pi l}$ and $A^{\pi r}$ respectively. If $A \in K^{m \times n}$, $r(A)$ denotes the rank of A . If A is group invertible, we denote $I - AA^\#$ by A^π , where I is an identity matrix of order n .

In this paper, for $A \in R^{m \times n}$, we also denote by $R(A) = \{Ax | x \in R^n\}$ and $R_r(A) = \{xA | x \in R^m\}$ the range and the row range of A , respectively.

2. Some Lemmas

In the next section we will use the following results.

Lemma 2.1. [22] *Let $A \in R^{n \times n}$, the followings are equivalent:*

- (i) $A^\#$ exists;
- (ii) $A = A^2X$ and $A = YA^2$ for some $X, Y \in R^{n \times n}$. In this case, $A^\# = YAX = AX^2 = Y^2A$;
- (iii) $R(A) = R(A^2), R_r(A) = R_r(A^2)$.

Lemma 2.2. *Let $A, X \in R^{n \times n}$. If $AX = XA$, $A^\#$ exists, then $A^\#X = XA^\#$.*

Proof. The proof of this Lemma is similar to that of Lemma 3.1 in [24], so we omit it here. \square

Lemma 2.3. *Let $A, X \in R^{n \times n}$. If $AX = XA$, $A^\#$ exists, $R(A) \subset R(AX)$ and $R_r(A) \subset R_r(XA)$, then $(XAA^\#)^\#$ exists and the following equalities hold.*

- (i) $XA^2(XAA^\#)^\# = A^2$;
- (ii) $(XAA^\#)^\#A^2X = A^2$;
- (iii) $(XAA^\#)^\#AA^\# = (XAA^\#)^\#$;
- (iv) $AA^\#(XAA^\#)^\# = (XAA^\#)^\#$.

Proof. Since $R(A) \subset R(AX)$, there exists a matrix Y over R such that $A = AXY$. Using Lemma 2, we have $XAA^\# = XA^\#A = XA^\#AXY = XAA^\#XAA^\#Y$, i.e., $R(XAA^\#) \subset R[(XAA^\#)^2]$, so $R(XAA^\#) = R[(XAA^\#)^2]$.

Similarly, using $R_r(A) \subset R_r(XA)$ we also get $R_r(XAA^\#) = R_r[(XAA^\#)^2]$. By Lemma 1, $(XAA^\#)^\#$ exists.

(i) Notice that $R_r(A) \subset R_r(XA)$, then there exists a matrix $Z \in R^{n \times n}$ such that $A = ZXA$. Hence

$$\begin{aligned} XA^2(XAA^\#)^\# &= A^4X[A^\#]^2(XAA^\#)^\# = ZXA^4X[A^\#]^2(XAA^\#)^\# \\ &= ZA^2[(XAA^\#)^2](XAA^\#)^\# = ZA^2(XAA^\#)^\# \\ &= ZX A^2 = ZXAA = A^2 \end{aligned}$$

(ii) Similarly, using $R(A) \subset R(AX)$ we can obtain that $(XAA^\#)^\#A^2X = A^2$.

(iii) By (i), we have

$$\begin{aligned} (XAA^\#)^\#AA^\# &= (XAA^\#)^\#[A^\#]^2A^2 = (XAA^\#)^\#[A^\#]^2XA^2(XAA^\#)^\# \\ &= (XAA^\#)^\#XAA^\#(XAA^\#)^\# = (XAA^\#)^\# \end{aligned}$$

(iv) Similarly, from (ii), we can prove (iv). \square

Lemma 2.4. *Let $A \in R^{m \times n}, B \in R^{n \times m}, R(BAB) = R(B)$ and $R_r(BAB) = R_r(B)$, then $(AB)^\#$ and $(BA)^\#$ exist and the following equalities hold.*

- (i) $(AB)^\# = A[(BA)^\#]^2B$;
- (ii) $(BA)^\# = B[(AB)^\#]^2A$;
- (iii) $(AB)^\#A = A(BA)^\#$;
- (iv) $(BA)^\#B = B(AB)^\#$.

Proof. The proof of this Lemma is similar to those of Lemma 2.2 and 2.3 in [12]. \square

3. Main Results

We begin with the following theorem.

Theorem 3.1. Let $M = \begin{pmatrix} AX + YB & A \\ B & 0 \end{pmatrix}$, where $A, B, X, Y \in R^{n \times n}$, $A^\#$ exists, $XA = AX$, $R(A) \subset R(AX)$ and $R_r(A) \subset R_r(XA)$, then we have

(i) $M^\#$ exists if and only if $R(B) = R(BSB)$, $R_r(B) = R_r(BSB)$, where $S = A^\pi Y - (XAA^\#)^\#$;

(ii) If $M^\#$ exists, then $M^\# = \begin{pmatrix} M_1 & M_2 \\ M_3 & M_4 \end{pmatrix}$, where

$$\begin{aligned} M_1 &= (SB)^\#A^\pi + (SB)^\pi A^\#(XAA^\#)^\# - (SB)^\pi ZB(SB)^\#A^\pi, \\ M_2 &= -(SB)^\#(XAA^\#)^\# + (SB)^\pi A^\#[(XAA^\#)^\#]^2 + (SB)^\pi ZB(SB)^\#[(XAA^\#)^\#]^2, \\ M_3 &= -B(SB)^\#A^\#(XAA^\#)^\# + B[(SB)^\#]^2A^\pi + B(SB)^\#ZB(SB)^\#A^\pi, \\ M_4 &= -B(SB)^\#A^\#[(XAA^\#)^\#]^2 - B[(SB)^\#]^2(XAA^\#)^\# - B(SB)^\#ZB(SB)^\#(XAA^\#)^\#, \\ Z &= A^\#[(XAA^\#)^\#]^2 + A^\#(XAA^\#)^\#Y. \end{aligned}$$

Proof. (i) The “only if” part.

Note that

$$M = \begin{pmatrix} YB & A \\ B & 0 \end{pmatrix} \begin{pmatrix} I & 0 \\ X & I \end{pmatrix}, \tag{1}$$

Using Lemma 3, we know that $(XAA^\#)^\#$ exists, and

$$M^2 = \begin{pmatrix} YBSB & XA^2 + YBA \\ BSB & BA \end{pmatrix} \begin{pmatrix} I & 0 \\ A^\#YB & I \end{pmatrix} \begin{pmatrix} I & 0 \\ A^\#(XAA^\#)^\#B & I \end{pmatrix} \begin{pmatrix} I & 0 \\ X & I \end{pmatrix}, \tag{2}$$

$$M^2 = \begin{pmatrix} I & Y \\ 0 & I \end{pmatrix} \begin{pmatrix} XAYB + AB & XA^2 \\ BYB & BA \end{pmatrix} \begin{pmatrix} I & 0 \\ X & I \end{pmatrix}. \tag{3}$$

By Lemma 1, there exist matrices \bar{X} and \bar{Y} over R such that $M = M^2\bar{X}$ and $\bar{Y}M^2 = M$. Let

$$\bar{X} = \begin{pmatrix} I & 0 \\ -X & I \end{pmatrix} \begin{pmatrix} I & 0 \\ -A^\#(XAA^\#)^\#B & I \end{pmatrix} \begin{pmatrix} I & 0 \\ -A^\#YB & I \end{pmatrix} \begin{pmatrix} X_1 & X_2 \\ X_3 & X_4 \end{pmatrix} \begin{pmatrix} I & 0 \\ X & I \end{pmatrix}, \tag{4}$$

$$\bar{Y} = \begin{pmatrix} Y_1 & Y_2 \\ Y_3 & Y_4 \end{pmatrix} \begin{pmatrix} I & -Y \\ 0 & I \end{pmatrix}. \tag{5}$$

From Eqs. (1), (2), (4) and $M = M^2\bar{X}$, we can obtain following equations

$$YBSBX_1 + (XA^2 + YBA)X_3 = YB, \tag{6}$$

$$YBSBX_2 + (XA^2 + YBA)X_4 = A, \tag{7}$$

$$BSBX_1 + BAX_3 = B, \tag{8}$$

$$BSBX_2 + BAX_4 = 0. \tag{9}$$

It follows, from Eqs. (1), (3), (5) and $\bar{Y}M^2 = M$, that we have

$$Y_1(XAYB + AB) + Y_2BYB = YB, \tag{10}$$

$$Y_1XA^2 + Y_2BA = A, \tag{11}$$

$$Y_3(XAYB + AB) + Y_4BYB = B, \tag{12}$$

$$Y_3XA^2 + Y_4BA = 0. \tag{13}$$

Instead of (8), we have

$$YBSBX_1 + YBAX_3 = YB.$$

Substituting it into (6), we have $XA^2X_3 = 0$, so $(XAA^\#)^\#A^2XX_3 = 0$. By Lemma 3 (ii), it follows by $A^2X_3 = 0$, so $AX_3 = 0$.

Substituting $AX_3 = 0$ into (8), we get $BSBX_1 = B$, i.e., $R(BSB) = R(B)$.

From (13), by Lemma 3 (i), we can get

$$-Y_4BAA^\#YB = Y_3XA^2A^\#YB = Y_3XAYB, \tag{14}$$

and

$$-Y_4BAA^\#(XAA^\#)^\#B = Y_3XA^2A^\#(XAA^\#)^\#B = Y_3AB. \tag{15}$$

Substitute (14) into (12), we have

$$-Y_4BAA^\#YB + Y_3AB + Y_4BYB = B. \tag{16}$$

Substitute (15) into (16), by Lemma 3 (iv), we have

$$-Y_4BAA^\#YB - Y_4BAA^\#(XAA^\#)^\#B + Y_4BYB = B,$$

that is $Y_4BSB = B$, which implies $R_r(B) = R_r(BSB)$. This completes proof of “only if” part.

In what follows, we give the proof of “if” part.

It follows from Lemma 2.4 that $R(BSB) = R(B)$ and $R_r(BSB) = R_r(B)$ imply $(SB)^\#$ and $(BS)^\#$ exist. Let

$$X_1 = (SB)^\#, \quad X_2 = -(SB)^\#(XAA^\#)^\#, \quad X_3 = 0, \quad X_4 = A^\#(XAA^\#)^\#$$

and

$$Y_1 = (SB)^\#A^\#(XAA^\#)^\#, \quad Y_2 = (SB)^\#S, \quad Y_3 = -B(SB)^\#A^\#(XAA^\#)^\#, \quad Y_4 = (BS)^\#.$$

We can easily obtain that $R(BSB) = R(B)$ implies $BSB(SB)^\# = B$.

We claim that X_1, X_2, X_3 and X_4 satisfy the Eqs. (6)-(9). Next, we verify the claim by computation separately.

- (1) $YBSBX_1 + (XA^2 + YBA)X_3 = YBSB(SB)^\# = YB;$
- (2) $YBSBX_2 + (XA^2 + YBA)X_4$
 $= -YBSB(SB)^\#AA^\#(XAA^\#)^\# + (XA^2 + YBA)A^\#(XAA^\#)^\#$
 $= -YBAA^\#(XAA^\#)^\# + XA(XAA^\#)^\# + YBAA^\#(XAA^\#)^\# = A;$
- (3) $BSBX_1 + BAX_3 = BSB(SB)^\# = B;$
- (4) $BSBX_2 + BAX_4$
 $= -BSB(SB)^\#AA^\#(XAA^\#)^\# + BAA^\#(XAA^\#)^\#$
 $= -BAA^\#(XAA^\#)^\# + BAA^\#(XAA^\#)^\# = 0.$

From $S = A^\#Y - (XAA^\#)^\#$, we have $SB - YB = -AA^\#YB - AA^\#(XAA^\#)^\#B$. By Lemma 2.4, we know $B(SB)^\# = (BS)^\#B$.

By Lemma 3 and computations, we also can verify Y_1, Y_2, Y_3 and Y_4 are the solutions of (10)-(13). This shows that there exist matrices \bar{X} and \bar{Y} over R such that $M = M^2\bar{X} = \bar{Y}M^2$ hold. Hence, by Lemma 1, $M^\#$ exists.

(ii) By Lemma 1 and Lemma 3, the expression of $M^\#$ can be obtained from $M^\# = \bar{Y}M\bar{X}$. \square

Example for Theorem 3.1: Let $R = \mathbb{Z}/(6)$, $M = \begin{pmatrix} AX + YB & A \\ B & 0 \end{pmatrix}$, where

$$A = \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix}, \quad B = \begin{pmatrix} -4 & 4 \\ 4 & 4 \end{pmatrix}, \quad X = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, \quad Y = \begin{pmatrix} 2 & -2 \\ 2 & 2 \end{pmatrix}.$$

$$AX = \begin{pmatrix} 4 & 4 \\ 4 & 4 \end{pmatrix}, \quad YB = \begin{pmatrix} -4 & 0 \\ 0 & 4 \end{pmatrix}.$$

It is easy to verify $AX = XA$, $R(A) \subset R(AX)$ and $R_r(A) \subset R_r(XA)$. By a direct computation, we know that $(XAA^\#)^\#$ and $(SB)^\#$ exist.

Further, we have

$$A^\# = \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix}, \quad A^\pi = \begin{pmatrix} -1 & -2 \\ -2 & -1 \end{pmatrix}, \quad (XAA^\#)^\# = \begin{pmatrix} 4 & 4 \\ 4 & 4 \end{pmatrix}, \quad SB = \begin{pmatrix} 4 & -4 \\ 2 & 0 \end{pmatrix}.$$

$$(SB)^\# = \begin{pmatrix} 0 & 2 \\ -4 & 2 \end{pmatrix}, \quad (SB)^\pi = \begin{pmatrix} -3 & 0 \\ 0 & -3 \end{pmatrix}, \quad Z = \begin{pmatrix} 0 & 2 \\ 0 & 2 \end{pmatrix}.$$

Clearly, $R(B) = R(BSB)$ and $R_r(B) = R_r(BSB)$. By Theorem 1, $M^\#$ exists and

$$M^\# = \begin{pmatrix} -4 & -2 & -2 & -2 \\ 0 & 0 & 2 & 2 \\ 4 & 4 & 4 & 4 \\ 4 & 2 & 4 & 4 \end{pmatrix}.$$

The following corollary follow Theorem 1.

Corollary 3.2. [23, Theorem1], Let $M = \begin{pmatrix} AX + YB & A \\ B & 0 \end{pmatrix}$, where $A, B, X, Y \in K^{n \times n}$, $A^\#$ exists, $XA = AX$, $r(A) = r(AX)$, then

- (i) $M^\#$ exists if and only if $r(B) = r(BSB)$, where $S = A^\pi Y - (XAA^\#)^\#$;
- (ii) If $M^\#$ exists, then the representation of $M^\#$ is the same as in Theorem 1.

Proof. When $R = K$, it is easy to see that

$$r(A) = r(AX) \iff R(A) \subset R(AX) \text{ and } R_r(A) \subset R_r(XA);$$

$$r(B) = r(BSB) \iff R(B) \subset R(BSB) \text{ and } R_r(B) \subset R_r(BSB).$$

Whence the corollary is easily proved. \square

Next, we consider the generalizations of some results in [13, 14, 19, 20].

Theorem 3.3. Let $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in R^{(n+m) \times (n+m)}$, where $A \in R^{n \times n}$, $A^\#$ exists, and $A^\pi B = 0$, Let $S = D - CA^\#B$. If $S^\#$ exists, then

- (1) $M^\#$ exists if and only if $P = A^2 + BS^\pi C$ is regular, $P^\pi A = AP^\pi = 0$ and $S^\pi CA^\pi = 0$, for some $P^{(1)} \in P\{1\}$;
- (2) If $M^\#$ exists, then $M^\# = M_1 M_2$, where

$$M_1 = \begin{pmatrix} AP^{(1)}(BS^\#CA^\# + I)AP^{(1)} & -AP^{(1)}B(S^\#)^2 \\ S^\pi CP^{(1)}(I + BS^\#CA^\#)AP^{(1)} & (S^\#)^2 - S^\pi CP^{(1)}B(S^\#)^2 \\ -S^\#CA^\#AP^{(1)} & \end{pmatrix}$$

$$M_2 = \begin{pmatrix} A - BS^\#CA^\pi & BS^\pi \\ CA^\pi & S \end{pmatrix}.$$

Proof. (1): The “Only if ” part.

Since $M^\#$ exists, we have that Lemma 1, there exist matrices X and Y over R such that $M = M^2X = YM^2$. By computations, $A^\pi B = 0$, and $P = A^2 + BS^\pi C$, we have

$$M = \begin{pmatrix} A & 0 \\ S^\pi C & S \end{pmatrix} \Delta_2 = \Delta_1 M_2, \quad M^2 = \Delta_1 \begin{pmatrix} P & 0 \\ 0 & S^2 \end{pmatrix} \Delta_2,$$

where Δ_1, Δ_2 are the following invertible matrices,

$$\Delta_1 = \begin{pmatrix} I & BS^\# \\ CA^\# & I + CA^\#BS^\# \end{pmatrix}, \quad \Delta_2 = \begin{pmatrix} I & A^\#B \\ S^\#C & I + S^\#CA^\#B \end{pmatrix},$$

and

$$\Delta_1^{-1} = \begin{pmatrix} I + BS^\#CA^\# & -BS^\# \\ -CA^\# & I \end{pmatrix}, \quad \Delta_2^{-1} = \begin{pmatrix} I + A^\#BS^\#C & -A^\#B \\ -S^\#C & I \end{pmatrix}.$$

From $M^\#$ exists, we have M^2 is group invertible, so is also regular. By $M^2 = \Delta_1 \text{diag}(P, S^2) \Delta_2$, it is easy to see that P is regular. Let

$$X = \Delta_2^{-1} \begin{pmatrix} X_1 & X_2 \\ X_3 & X_4 \end{pmatrix}, \quad Y = \begin{pmatrix} Y_1 & Y_2 \\ Y_3 & Y_4 \end{pmatrix} \Delta_1^{-1},$$

by the equations $M = M^2X$ and $M = YM^2$, we have

$$\begin{pmatrix} P & 0 \\ 0 & S^2 \end{pmatrix} \begin{pmatrix} X_1 & X_2 \\ X_3 & X_4 \end{pmatrix} = \begin{pmatrix} A - BS^\#CA^\pi & BS^\pi \\ CA^\pi & S \end{pmatrix}$$

and

$$\begin{pmatrix} Y_1 & Y_2 \\ Y_3 & Y_4 \end{pmatrix} \begin{pmatrix} P & 0 \\ 0 & S^2 \end{pmatrix} = \begin{pmatrix} A & 0 \\ S^\pi C & S \end{pmatrix}.$$

From above the two equations, we have

$$PX_1 = A - BS^\#CA^\pi, \tag{17}$$

$$PX_2 = BS^\pi, \tag{18}$$

$$S^2X_3 = CA^\pi, \tag{19}$$

$$S^2X_4 = S, \tag{20}$$

$$Y_1P = A, \tag{21}$$

$$Y_2S^2 = 0, \tag{22}$$

$$Y_3P = S^\pi C, \tag{23}$$

$$Y_4S^2 = S. \tag{24}$$

From (17), we get $PX_1A^\#A = A$, so $PP^{(1)}A = A$, i.e., $P^{\pi r}A = 0$. By (21), we have $AP^{(1)}P = A$, i.e., $AP^{\pi l} = 0$. Using (19), we get $S^\pi CA^\pi = 0$.

The “if ” part.

Let

$$X_1 = P^{(1)}A(I - A^\#BS^\#CA^\pi), \quad X_2 = P^{(1)}BS^\pi, \quad X_3 = (S^\#)^2CA^\pi, \quad X_4 = S^\#$$

and

$$Y_1 = AP^{(1)}, \quad Y_2 = 0, \quad Y_3 = S^\pi CA^\#AP^{(1)}, \quad Y_4 = S^\#.$$

Note that, by $A^\pi B = 0$, $P^{\pi r}A = AP^{\pi l} = 0$ and $S^\pi CA^\pi = 0$, it is easy to verify X_1, X_2, X_3, X_4 and Y_1, Y_2, Y_3, Y_4 satisfy the Eqs.(17) – (20) and (21) – (24), respectively. That implies $M = M^2X = YM^2$ have solution X, Y , so $M^\#$ exists.

(2) By Lemma 1, we can compute that

$$\begin{aligned} M^\# &= Y^2M = \begin{pmatrix} Y_1 & Y_2 \\ Y_3 & Y_4 \end{pmatrix} \Delta_1^{-1} \begin{pmatrix} Y_1 & Y_2 \\ Y_3 & Y_4 \end{pmatrix} \Delta_1^{-1} \Delta_1 M_2 \\ &= \begin{pmatrix} AP^{(1)} & 0 \\ S^\pi CA^\# AP^{(1)} & S^\# \end{pmatrix} \begin{pmatrix} I + BS^\# CA^\# & -BS^\# \\ -CA^\# & I \end{pmatrix} \begin{pmatrix} AP^{(1)} & 0 \\ S^\pi CA^\# AP^{(1)} & S^\# \end{pmatrix} \begin{pmatrix} A - BS^\# CA^\pi & BS^\pi \\ CA^\pi & S \end{pmatrix} \\ &= M_1 M_2. \end{aligned}$$

□

Example for Theorem 3.3: Let \mathbb{Z} be the integer ring, and let $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$ be a matrix over $\mathbb{Z}/(6\mathbb{Z})$, where

$$A = \begin{pmatrix} 2 & 0 \\ 2 & 4 \end{pmatrix}, \quad B = \begin{pmatrix} 2 & 0 & 2 \\ 2 & 4 & 4 \end{pmatrix}, \quad C = \begin{pmatrix} 2 & 2 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad D = \begin{pmatrix} 4 & 2 & 0 \\ 4 & 3 & 4 \\ 0 & 4 & 3 \end{pmatrix}.$$

Then

$$\begin{aligned} A^\# &= \begin{pmatrix} 2 & 0 \\ 2 & 4 \end{pmatrix}, \quad A^\pi = \begin{pmatrix} 3 & 0 \\ 0 & 3 \end{pmatrix}, \quad A^\pi B = 0, \quad S = D - CA^\# B = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \\ S^\# &= \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad S^\pi = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad P = A^2 + BS^\pi C = \begin{pmatrix} 4 & 0 \\ 4 & 4 \end{pmatrix}. \end{aligned}$$

Let $P^{(1)} = \begin{pmatrix} 4 & 0 \\ -4 & 4 \end{pmatrix}$. Therefore $P^{\pi r} A = AP^{\pi l} = 0$, $S^\pi CA^\pi = 0$. By Theorem 2, we have

$$M^\# = \begin{pmatrix} -2 & 2 & -2 & 2 & 2 \\ -2 & 2 & -2 & 2 & 0 \\ -2 & 2 & 2 & 2 & 0 \\ -1 & -2 & 2 & 1 & -2 \\ 0 & -1 & 0 & 2 & 1 \end{pmatrix}.$$

By computations, from Theorem 2, we can obtain the following corollaries.

Corollary 3.4. [13, Theorem 3.1][14, Corollary 3.1], $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in R^{(n+m) \times (n+m)}$, where $A \in R^{n \times n}$ is invertible and $S = D - CA^{-1}B$ is group invertible, then

(i) $M^\#$ exists if and only if $P = A^2 + BS^\pi C$ is invertible;

(ii) If $M^\#$ exists, then $M^\# = \begin{pmatrix} M_1 & M_2 \\ M_3 & M_4 \end{pmatrix}$, where

$$M_1 = AP^{-1}(A + BS^\# C)P^{-1}A,$$

$$M_2 = AP^{-1}(A + BS^\# C)P^{-1}BS^\pi - AP^{-1}BS^\#,$$

$$M_3 = S^\pi CP^{-1}(A + BS^\# C)P^{-1}A - S^\# CP^{-1}A,$$

$$M_4 = S^\pi CP^{-1}(A + BS^\# C)P^{-1}BS^\pi - S^\# CP^{-1}BS^\pi - S^\pi CP^{-1}BS^\# + S^\#.$$

Proof. When A is invertible, we have $A^\pi = P^{\pi r} = P^{\pi l} = 0$. Further, $PP^{(1)} = I = P^{(1)}P$, this implies P is invertible and $P^{(1)} = P^{-1}$. Whence the corollary is easily proved. □

Corollary 3.5. [19, Theorem12], $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in R^{(n+m) \times (n+m)}$, where $A \in R^{n \times n}$ and $S = D - CA^\#B$ are group invertible, $A^\pi B = 0$ and $S^\pi C = 0$, then $M^\#$ exists and

$$M^\# = \begin{pmatrix} A^\# + A^\#BS^\#CA^\# & -A^\#BS^\# \\ -S^\#CA^\# & S^\# \end{pmatrix} \begin{pmatrix} I - A^\#BS^\#CA^\pi & A^\#BS^\pi \\ S^\#CA^\pi & I \end{pmatrix}.$$

Proof. Note that $S^\pi C = 0$, $P = A^2$ and $P^{(1)} = (A^\#)^2$, the proof immediately follows from Theorem 2. \square

Corollary 3.6. [20, Theorem5], $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in R^{(n+m) \times (n+m)}$, where $A \in R^{n \times n}$ and $S = D - CA^\#B$ are group invertible, $A^\pi B = 0$, $CA^\pi = 0$ and $S^\pi C = 0$, then $M^\#$ exists and

$$M^\# = \begin{pmatrix} A^\# + A^\#BS^\#CA^\# & A^\#(I + BS^\#CA^\#)A^\#BS^\pi - A^\#BS^\# \\ -S^\#CA^\# & S^\#(I - C(A^\#)^2BS^\pi) \end{pmatrix}.$$

Proof. Note that $CA^\pi = 0$, the proof immediately follows from Corollary 3. \square

Acknowledgments The authors show great thanks to the editor and referee for their careful reading of the manuscript and valuable comments which greatly improved the readability of the paper.

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