Forecasting Stock Index with Multi-objective Optimization Model Based on Optimized Neural Network Architecture Avoiding Overfitting

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Abstract. In this paper, the stock index time series forecasting using optimal neural networks with optimal architecture avoiding overfitting is studied. The problem of neural network architecture selection is a central problem in the application of neural network computation. After analyzing the reasons for overfitting and instability of neural networks, in order to find the optimal NNs (neural networks) architecture, we consider minimizing three objective indexes: training and testing root mean square error (RMSE) and testing error variance (TEV). Then we built a multi-objective optimization model, then converted it to single objective optimization model and proved the existence and uniqueness theorem of optimal solution. After determining the searching interval, a Multiobjective Optimization Algorithm for Optimized Neural Network Architecture Avoiding Overfitting (ONNAAO) is constructed to solve above model and forecast the time series. Some experiments with several different datasets are taken for training and forecasting. And some performance such as training time, testing RMSE and neurons, has been compared with the traditional algorithm (AR, ARMA, ordinary BP, SVM) through many numerical experiments, which fully verified the superiority, correctness and validity of the theory.

Keywords: neural network architecture, RMSE, TEV, multi-objective optimized model, overfitting, instability.

1. Introduction

Since the emergence of stocks, stock index prediction has been widely concerned and actively studied. Many scholars have put forward a number of different prediction methods, which can be divided into two groups. One group includes the traditional statistical methods such as AR [1], ARMA [2], GARCH [3] etc., and the other one relies on artificial intelligence methods such as NNs, SVM [4], ELM [5] etc.. The traditional stock prediction method is based on the linear model, but there is a nonlinear relationship among stock price, the political, economic and social influence of various factors on the stock indexes. As traditional methods [6-8] cannot fully consider these factors, to remedy this defect, in recent years, many scholars use artificial intelligence

method such as neural network on the stock price time series prediction, which have achieved a large number of successful application, such as price prediction [9], power load forecasting [10], water resources variables forecasting [11], chaotic time series forecasting [12], financial and economic forecasting [13] and sunspot series forecasting [14]. Neural networks can overcome the shortcomings of traditional forecasting methods, and they do not need to establish a complex nonlinear mathematical model and mapping [15]. So the stock market is more suitable for the prediction using neural networks compared with the other classic methods [16, 17].

Neural network models have been successfully applied in a variety of applications such as data prediction, image processing and pattern recognition, data mining, expert system, economic analysis etc. The widespread popularity of neural networks in so many fields is mainly due to their ability to approximate complex multivariate nonlinear functions directly from the input samples. Neural networks can provide models for a large class of natural and artificial phenomena that are difficult to handle using classical parametric techniques.

However, NNs (neural networks) have actually many drawbacks, such as the tendency to overfitting [18-21], instability [22] and the difficulties to determine the optimized network structure [23-25]. The overfitting problem is a critical issue that usually leads to poor generalization [26-28]. It is empirically known that the overfitting problem is particularly serious when the number of the neurons in hidden layer is too large [29]. But the process of selecting adequate neural network architecture for a given problem is still a controversial issue.

So the selection of an optimized model size which maximizes generalization is an important topic. There are several theories for determining the optimized network size, such as NIC (Network Information Criterion) [30], which is a generalization of the AIC (Akaike Information Criterion) [31-32], and the VC dimension (Vapnik 1995) [33] which is a measure of the expressive power of a network. NIC relies on a single welldefined minimum to the fitting function and can be unreliable when there are several local minima [34]. Their evaluation is prohibitively expensive for large networks. VC bounds are likely to be too conservative because they provide generalization guarantees simultaneously for any probability distribution and any training algorithm. The computation of VC bounds for practical networks is difficult. Baum and colleagues [35] have obtained some bounds on the number of neurons in an architecture related to the number of training examples. An important contribution about the approximation capabilities of feed-forward networks was made by Barron [36], who computed an estimation of the number of hidden nodes necessary to optimize the approximation error. Yuan HC [37] proposed a method for estimating the number of hidden neurons in feed-forward neural networks based on information entropy. And signal-to-noise-ratio [38] have been also used to analyze the issue about the optimized number of neurons in a neural architecture. The previously mentioned theoretical results have helped much to understand certain issues regarding the properties of feed-forward neural networks. But unfortunately, at the time of practical implementations the bounds are loose or difficult to compute or determine.

Instability is another fatal drawback of NNs: training using the same dataset and the same algorithm may produce very different models [39-40]. Although some constructive approaches [41-44] can solve the instability problem, they cannot guarantee good generalization.

In this paper, we will analyze the characteristics of NNs with optimized network architecture or hidden neuron number. Firstly, we have to solve the problem that the optimized NN must have enough hidden neurons. Secondly, it should have minimal training error and test error, i.e. good generalization. Finally, NN must be stable, that is, for the same sample data set, using the same algorithm multiple tests, the variance of the test error must be minimal. Comprehensively considering of the above factors, a multiobjective optimization model can be constructed to determine the optimized neural architecture for good generalization and avoiding overfitting. And an algorithm for Optimized Neural Network Architecture Avoiding Overfitting (ONNAAO) is constructed for training and forecasting the stock indexes.

This paper is organized as follows: the second section describes the work related to time series forecasting, Section 3 investigates the phenomena of neural network overfitting, bad generalization and high variance caused by noisy data, overfull hidden neurons through some experiments. In Section 4, a multi-objective optimization model and the correlative algorithm (ONNAAO) will be constructed to determine the optimized neural architecture for good generalization and avoiding overfitting. And the theorem of the existence and uniqueness of optimized solution is proved. Section 5 will describes experiments on practical problems related to stock market. In Section 6, a comprehensive comparison of performance with some traditional algorithms is presented. Section 7 provides some conclusions.

2. The Work Related to Time Series Forecasting

For investors, the changes of stock index and stock price are very important information and the forecasting of time series in stock market has long been attracting the eternal interest of countless scientists and researchers for many years [9,17,45-47]. Unfortunately, stock indices and prices are essentially dynamic, nonlinear, nonparametric and chaotic in nature. This means that investors and researchers must have to face highly nonlinear and noisy time series data, which have frequent structural breaks [47]. In fact, the changes of stock index and stock price are affected by many macro-economic factors such as company's policies, political events, movement of other stock market, commodity prices index, bank rate, investors' expectations, general economic conditions, institutional investors' choices and psychological factors of investors. Thus prediction of stock index and price accurately is not only the most extremely challenging applications of time series prediction but also of great interest to investors.

Time series modeling and prediction have important applications in many fields of science and engineering. Conventionally time series forecasting (TSF) has been performed predominantly using statistical-based methods such as the moving average (MA), the autoregressive (AR), the autoregressive integrated moving average (ARIMA) and the autoregressive moving average (ARMA) [48]. However, in recent decades, the excellent performance of neural networks in the prediction and classification of time series has attracted the attention and interest of many scientists in machine learning domain [10, 15, 16, 48-50]. Compared to statistical-based forecasting techniques, NNs have several unique characteristics, including: 1) having no requirement for an explicit

underlying model (nonparametric); 2) being both nonlinear and data driven; 3) being more flexible and universal, thus applicable to more complicated models [51].

Time series forecasting (TSF) takes an existing series of data X_{t-p} , X_{t-2} , X_{t-1} and forecasts the future values of X_t , X_{t+1} , . The goal is to observe or model the existing data series to enable future unknown data values to be forecasted accurately. In the literature [52, 53], many methods have been used to perform time series forecasting. Examples of linear model include Autoregressive (AR):

$$X_{t} = \varphi_{1}X_{t-1} + \varphi_{2}X_{t-2} + \varphi_{p}X_{t-p} + u_{t}$$
(1)

Moving Average (MA):

$$X_{t} = u_{t} - \theta_{1}u_{t-1} - \theta_{2}u_{t-2} - - \theta_{q}u_{t-q}$$
(2)

and Autoregressive Moving Average (ARMA) [54, 55]:

$$X_{t} = \varphi_{1}X_{t-1} + \varphi_{2}X_{t-2} + \varphi_{p}X_{t-p} + u_{t} - \theta_{1}u_{t-1} - \theta_{2}u_{t-2} - \theta_{q}u_{t-q}$$
(3)

where $\varphi_1, \varphi_2, \quad , \varphi_p \quad \theta_1, \theta_2, \quad , \theta_q$ are the parameters of the model, $u_i, i = 1, 2, \quad , t$ is white noise.

However, due to the complexity and non-linearity of the time-series data, the abovementioned linear models often have a poor prediction performance for the stock time series in practical applications. And NNs are advanced model and tool capable of extracting complex, nonlinear relationships among variables [48, 56, 57]. A three-layer feed forward NNs model is usually used to process the time series data.

The neural network forecaster can be described as follows:

$$X_{t} = NN(X_{t-1}, X_{t-2}, X_{t-p})$$
(4)

The corresponding structure is $p \times q \times 1$, where p is the number of inputs, q is the number of neurons in the hidden layer, and one output unit. So the output of the NNs is given by

$$X_{t} = \sum_{j=0}^{q} c_{j} \varphi(\sum_{i=1}^{p} w_{ij} X_{t-i} + \theta_{j})$$
(5)

where w_{ij} is the weight that connects the node *i* in the input layer neurons to the node *j* in the hidden layer; c_j is the weight that connects the node *j* in the hidden layer neurons to the node in the output layer neurons; θ_j is the threshold of neuron; and φ is the activation function. However, new problems have arisen, which are described in next section.

3. The Phenomena of Neural Networks Over-fitting, Poor Generalization and High Variance

The problem of neural network architecture selection is a central problem in the application of neural network computation. A network that is too small, either in

number of neurons or number of hidden layers, will tend to learn the grossest behavior of the training data and ignore subtleties. However, a network that is too large will tend to over-specialize and learn the training data too well, resulting in overfitting and high variance. We will describe these phenomena through some simple experiments.

Example [58]: the following sample dataset A comes from the sine function which contained 60 points as shown in Fig. 1.



Fig. 1. Sample dataset A generated by the sine function

In the following experiments, we will approximate the dataset using traditional single hidden layer feed-forward neural networks with different number of hidden neurons trained by BP (Back Propagation) algorithm. Although there are many variants of BP algorithm, a faster BP algorithm called Levenberg-Marquardt is used in our experiments due to its faster convergence rate. All the experiments are carried out in MATLAB 7.10 (R2010a) environment running on an Intel(R) Core(TM) i3-2120 3.30GHz CPU. We will use 54 points of the dataset to train the neural networks and the other 6 points to test the un-optimized and the optimized networks.

In Fig. 2, the neural network only needs 4 hidden neurons, based on the experience, to fit the function very well with 0.39 CPU training time (second), training RMSE and 0.0013825 testing RMSE.

But if we increase the number of hidden neurons to 7, training the NNs with the same training dataset and testing dataset twice, we got different results in Fig.3 and Fig.4, in which the testing RMSE are rising to 0.050339 and 0.031242, which are 36.41 and 22.6 times of that in Fig. 3.



Fig. 2. Results of training and testing with 4 hidden neurons using dataset A



Fig. 3. Results of first training and testing with 7 hidden neurons using dataset A

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Fig. 4. Results of second training and testing with 7 hidden neurons using dataset A

In the following experiments, on the same dataset A, for every number of neurons between 1 and 10, we will train 20 NNs and compute the following index: training and testing root mean square error (RMSE)

$$RMSE = \sqrt{\frac{1}{n+1} \sum_{i=0}^{n} (f(x_i) - y_i)^2}$$
(6)

testing error variance (TEV)

$$error_{ij} = f(x_{j}) - y_{ij}$$

$$mean_{i} = \frac{1}{n} \sum_{j=1}^{n} error_{ij} = \frac{1}{n} \sum_{j=1}^{n} (f(x_{j}) - y_{ij})$$

$$mean = \frac{1}{m} \sum_{i=1}^{n} mean_{i}$$

$$TEV = \frac{1}{m} \sum_{i=1}^{m} (mean_{i} - mean)^{2}$$

$$i = 1, \quad ,m; \quad j = 1, \quad ,n$$
(7)

where y_{ij} is the output of x_j in the *i*-th training NNs.

The results are exhibited in Fig.5. in which we can find the optimized NNs architecture for the dataset A is 4 hidden neurons.



Fig. 5. The statistics performance of 20 NNs for each number of hidden neurons using dataset A

If we add a noise to the dataset A, we can get sample dataset B which comes from function

$$y = f_1(x) = \begin{cases} \sin x & x \neq \frac{\pi}{2} \\ 2 & x = \frac{\pi}{2} \end{cases}$$
(8)

and also contains 60 points as shown in Fig.6.



Fig. 6. Sample dataset *B* generated by the function $y = f_1(x)$

On the sample dataset *B*, for every number of neurons between 1 and 10, we will also train 20 NNs and compute the following index: training and testing root mean square

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error (RMSE). The results are exhibited in Fig. 7 in which we can find the optimized NNs architecture for the dataset A is 6 hidden neurons because of the noise. Then we use the optimized NNs architecture with 6 hidden neurons to train a NNs which can fit the dataset B very well and have good generalization in Fig. 8.



Fig. 7. The statistics performance of 20 NNs for each number of hidden neurons using dataset B



Fig. 8. Results of first training and testing with 6 hidden neurons using dataset B

4. Multi-objective Optimization Model for NNs Architecture

There are many good theoretical results [36, 59-61] on the number of neurons in an optimized NNs architecture related to the function complexity under the sample datasets, which have helped much to understand certain issues regarding the properties of feed-forward neural networks but unfortunately at the time of practical implementations the bounds are loose or difficult to compute. Based on the above analysis, comprehensively considering of the above factors, in this paper, a multi-objective optimization model was built to find the optimized NNs architecture as follows:

min training RMSE
min testing RMSE
min TEV
st. NNs: NN(x) =
$$\sum_{k=1}^{p} c_k \phi(\mathbf{w}_k \cdot \mathbf{x} + b_k)$$

 $RMSE = \sqrt{\frac{1}{n+1} \sum_{i=0}^{n} (f(x_i) - y_i)^2}$
 $error_{ij} = f(x_j) - y_{ij}$
 $mean_i = \frac{1}{n} \sum_{j=1}^{n} error_{ij} = \frac{1}{n} \sum_{j=1}^{n} (f(x_j) - y_{ij})$ (9)
 $mean = \frac{1}{m} \sum_{i=1}^{n} mean_i$
 $TEV = \frac{1}{m} \sum_{i=1}^{m} (mean_i - mean)^2$
 $i = 1, \quad ,m; \quad j = 1, \quad ,n$
 $neurons p \in [a, b], p \in Z$
 $a = \lceil (N+M)/4 \rceil$
 $b = \lceil 2T/(5*(N+M)) \rceil$

where y_{ii} is the output of x_i in the *i*-th training NNs, *k* is the number of hidden neurons.

In this model, we will find an optimized NNs which hold three objective, minimal *training RMSE, testing RMSE* and *TEV*, which has the best generalization and stability. The searching interval [a, b] can be determined by the following analysis: Some have a theoretical formulation behind, but others are just justified based on experience. The following notation is used: N is the input dimension of the data, N_h represents the number of hidden neurons in the single hidden layer used in the neural architectures and M is used for the output dimension (taken as 1 for all the problems considered). T is used to indicate the number of available training vectors. The following approaches described below correspond to two widely used software frameworks Weka [62] and Neuralware [63].

Weka is a popular collection of machine learning algorithms for solving real-world data mining problems. Weka permits to compare the predictive accuracy of different learning algorithms. In the implementation of neural network architectures, Weka estimates by default the architecture size as $N_h = (N+M)/2$. It is not clear the justification for the introduction of this rule that has been also suggested in other works [64]. Based on experimental results, it seems that Weka suggests it based on its simplicity and on previous experience. Neuralware is another well-known commercial implementation of artificial neural networks. They suggest architecture with $N_h = T / (5^*(N+M))$ neurons. Because T is commonly very large, we have:

$$T / (5^*(N+M)) > (N+M) / 2$$
 (10)

So we take $a = \lceil (N+M)/4 \rceil$ and $b = \lceil 2T/(5^*(N+M)) \rceil$, that means the optimized number of hidden neurons can be found in [a, b].

There are many approaches to solve the multi-objective optimization problems [65] such as weighted sum approaches [66], lexicography approaches [67] and Pareto approaches [68] etc.

In this paper, weighted sum approach was used to convert multi-objective optimization to single objective optimization, and we simply selected the weight $w_i = 1/3$ i = 1,2,3. Then we get the single objective optimization model as follows:

min
$$z = \frac{1}{3}$$
 training $RMSE + \frac{1}{3}$ testing $RMSE + \frac{1}{3}TEV$
st. $NNs: NN(x) = \sum_{k=1}^{p} c_k \phi(w_k \cdot x + b_k)$
 $RMSE = \sqrt{\frac{1}{n+1}\sum_{i=0}^{n} (f(x_i) - y_i)^2}$
 $error_{ij} = f(x_j) - y_{ij}$
 $mean_i = \frac{1}{n}\sum_{j=1}^{n} error_{ij} = \frac{1}{n}\sum_{j=1}^{n} (f(x_j) - y_{ij})$ (11)
 $mean = \frac{1}{m}\sum_{i=1}^{n} mean_i$
 $TEV = \frac{1}{m}\sum_{i=1}^{m} (mean_i - mean)^2$
 $i = 1, \quad ,m; \quad j = 1, \quad ,n$
 $neurons \ p \in [a, b], \ p \in Z$
 $a = \lceil (N+M)/4 \rceil$
 $b = \lceil 2T/(5^*(N+M)) \rceil$

In order to prove the existence of the optimized solution for this model, we first introduce some previous works on approximation of functions by NNs, and then we will prove the theorem of the existence and uniqueness of optimized solution.

There are many good results on approximation to continuous functions and dataset by neural networks using traditional algorithm such as BP, ELM, SVM and some constructive approaches.

Let $\phi : \mathbf{R} \to \mathbf{R}$. Define

$$\sum^{d} (\phi) \equiv span \left\{ \phi(\mathbf{w}.\mathbf{x} + b) : b \in \mathbf{R}, \mathbf{w}, \mathbf{x} \in \mathbf{R}^{d} \right\},$$
(12)

Then $N \in \sum^{d} (\phi)$ if and only if

$$NN(\mathbf{x}) = \sum_{j=0}^{n} c_j \varphi(w_j \mathbf{x} + b_j)$$
(13)

where c_j , j = 0, n are real numbers and n is a positive integer.

We say that ϕ is a sigmoid function, if it verifies $\lim_{t\to\infty} \phi(t) = 0$ and $\lim_{t\to\infty} \phi(t) = 1$, then (12) is called single-layer feed-forward neural network. If $\phi(\mathbf{x}) = \phi(||\mathbf{x}-\mathbf{x}_0||)$ $x \in \mathbf{R}^d$, we call $\phi(\mathbf{x})$ RBF (Radical Basis Function) function, then (12) is called RBF (Radical Basis Function) neural networks.

In the case of continuous functions we have the following density results

Theorem 1 ([69) Let $\phi \in C(\mathbf{R})$. Then $\sum^{d} (\phi)$ is dense in $C(\mathbf{R}^{d})$ in the topology of uniform convergence on compact if and only if ϕ is not a polynomial.

Corollary 1 ([70]) $y = f(x) \in C(\mathbb{R}^d)$ can be approximated by a simplest neural networks (such as with Minimum number of hidden neurons).

In the case of not necessarily continuous functions we also have some density results. **Theorem 2** ([71]) Let ϕ be bounded, measurable and sigmoidal. Then $\sum^{d} (\phi)$ is dense in $L^{1}([0,1]^{d})$.

The following theorem is a generalization of the above results.

Theorem 3 ([72]) Let ϕ be a Lebesgue measurable function, not a.e. equal to a polynomial, satisfying $\int_{a}^{b} |\phi(x)|^{p} dx < \infty$ for all $a, b \in \mathbb{R}$. Let K be a compact set in \mathbb{R}^{d} . Then for any function $f \in L^{p}(K)$ $(p \ge 1)$ and every $\varepsilon > 0$, there is a network $N \in \sum^{d} (\phi)$ such that

$$\|N - f\|_{K,\rho} < \varepsilon \tag{14}$$

where $||g||_{K,p} \equiv (\int_{K} |g(x)|^{p} dx)^{\frac{1}{p}}$.

For RBF neural networks we have the following results.

Theorem 4 ([73]) Let ϕ be a RBF function, then for any function $f \in L^p(\mathbf{R})$ $(p \ge 1)$ and every $\varepsilon > 0$, there is a network $N \in \sum^{d} (\phi)$ such that

$$\|N - f\|_{p} < \varepsilon \tag{15}$$

where $||g||_{p} \equiv (\int |g(x)|^{p} dx)^{\frac{1}{p}}$.

There are some constructive approaches for function approximation.

Theorem 5 ([41]) 1. Let $\mathbf{x} \in [a,b]^k \subset \mathbf{R}^k$, and $f(\mathbf{x})$ be a multivariate continuous function, $\mathbf{x}_i \in [a,b]^k$ i = 0,1, ..., n be an uniform grid partition to $[a,b]^k$, where

[a,b] is divided to *s* equal partition, and arrange by breadth-first such that x_0,x_1, \ldots, x_n $(n = s^k)$. Then

$$\|\mathbf{x}_{i} - \mathbf{x}_{i-1}\| = \frac{b-a}{n^{\frac{1}{2k}}} = \frac{b-a}{s^{\frac{1}{2}}}$$
(16)

2. A depends on n, that is A = A(n).

3. The real numbers f_i are the images of X_i under a multivariate continuous function f(x), that is $f_i = f(x_i)$, i = 0, 1, 2, ..., n.

For each $\varepsilon > 0$, we can construct a decay RBF neural network $W_a(\mathbf{x}, A(n))$, and there exists a function A(n) and a natural number N such that, when n > N, we have

$$\left|f(\mathbf{x}) - W_a(\mathbf{x}, n, A(n))\right| < \varepsilon \tag{17}$$

for all $x \in [a,b]^k$.

Based on above theorems, we can prove the following theorem about the existence and uniqueness of optimized solution.

Theorem 6 For a given dataset, there exists only one optimized solution for the multiobjective optimization model (11).

Proof, we will first prove that the feasible region *D* is not empty.

We assume the sample dataset *S* is came from a certain continuous function y = f(x), for each hidden neurons $p \in [a,b]$, from the density theorem1-4, we can find a NNs with *p* hidden neurons using various traditional algorithm such BP, ELM, SVM and some constructive approaches:

$$NN(\mathbf{x}) = \sum_{k=1}^{p} c_k \phi(\mathbf{w}_k . \mathbf{x} + b_k)$$
(18)

which has the minimal distance

$$RMSE = \varepsilon = \|N - f\|_{K, n}$$
(19)

So the feasible region *D* of multi-objective optimization model (1) is not empty.

Then, as the number of hidden neurons $p \in [a,b]$ is an integer, the searching interval is finite, which makes the multi-objective optimization model (11) have only one optimized solution for the certain sample dataset $S \square$

Based on theorem 6 we can get the following algorithm to solve the above multiobjective optimization model:

```
Step 1: based on the input data, compute the searching
interval [a, b], a = [(N + M)/4], b = [2T/(5 * (N + M))]. N is the
input dimension of the data, and M is the output
dimension
Step 2:
   for i = a to i = b
      for j = 1 to j = m,
         train a neural network with i hidden neurons
         using Levenberg-Marquardt algorithm for the
         training dataset.
Step 3:
   for each trained neural network,
      compute training RMSE, testing RMSE and TEV, then
      z = 1/3 (training RMSE + testing RMSE + TEV)
Step 4: determine the optimized neural network
architecture or number of hidden neurons of NNs based on
the minimal z.
Step 5: construct an optimized NNs with minimal z to
training and forecasting the stock indexes.
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Although there are many algorithms to train the NNs, in this paper, we use Levenberg-Marquardt BP algorithm for the all experiments, due to its faster convergence rate.

For above datasets A and B, using the algorithm 4.1 we can get the results of Fig.9 and Fig. 10. In Fig. 9, we can see that the optimized value is 4 hidden neurons for the dataset A, and in Fig. 9, we can see that the optimized value is 6 hidden neurons for the dataset B.



Fig. 9. The results for dataset A, optimized value is 4



Fig. 10. The results for dataset *B*, optimized value is 6

5. Experiments on Stock Data

All stock market trends are fast changing. They are affected by not only the individual investors and many institutional investors, but also impacted by domestic political, economic situations and many other factors. Therefore, it is very difficult to build a classical parameter model to predict the market movement [46]. But it is easy to build a NNs model to fit the stock dataset, and the choice of optimized neural network architecture is still a problem that has not been solved yet. In this section, we will use above multi-objective optimization algorithm to build an optimized neural network architecture model to predict Chinese Shanghai Composite Index.

We first collected the sample data of Chinese Shanghai Composite closing Index from internet stock database. The collection period is from November 25, 2015 to January 16, 2017 and the number of data totaled 280 (Fig. 11).

We will use 275 points of the dataset to train the neural networks and the other 5 points to test the old and the optimized networks.

Then we use the above multi-objective optimization algorithm to find the optimized neural networks architecture or the optimized number of the hidden neurons. The searching interval [a, b] is [1, 60]. Fig. 12 shows the three objective values in the searching process, Fig 13 depicts the result for the stock dataset, optimized value is 57.



Fig. 11. Chinese Shanghai Composite closing Index in 280 days



Fig. 12. The three objective value in the searching process

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Fig. 13. The result for the stock dataset, optimized value is 57

In the end, we built a neural network with 57 hidden neurons, and trained it with 275 Chinese Shanghai Composite closing Index using Levenberg-Marquardt BP algorithm, and predicted the last 5 as it is shown in Fig. 14. Fig.15 is the enlarged part of the predicted values.



Fig. 14. The application of the optimized NNs for prediction



Fig. 15. The enlarged part of the predicted values

The results of these experiments are presented in table 1. We collected another dataset: Jinlong Automobile (600686) from April 19, 2016 to June 13, 2017, a total of 280 days closing price as shown in Figure 16.



Fig. 16. A total of 280 days closing price of Jinlong Automobile (600686) from April 19, 2016 to June 13, 2017, in 280 days

We also use 275 points of the dataset to train the neural networks and the other 5 points to test the optimized networks. And we also use the proposed multi-objective optimization algorithm to find the optimized neural networks architecture or the optimized number of the hidden neurons. The searching interval [a, b] is [1, 70]. Fig. 17 shows the three objective values in the searching process, Fig 18 depicts the result for the stock dataset, optimized value is 62.



Fig. 17. The three objective value in the searching process



Fig. 18. The result for the stock dataset J, optimized value is 62

In the end, we built a neural network with 62 hidden neurons, and trained it with 275 closing price of Jinlong Automobile (600686) from April 19, 2016 to June 13, 2017, in 280 days, using Levenberg-Marquardt BP algorithm, and predicted the last 5 as it is shown in Fig.19. Fig.20 is the enlarged part of the predicted values.

The experimental results are summarized in Table 1.



Fig. 19. The application of the optimized NNs for prediction



Fig 20. The enlarged part of the predicted values

Dataset (number)	Come from	Searching interval	Number of experiments for each NNs	Optimal value of hidden neurons
A(60)	$y = \sin x$	[1,10]	20	4
B(60)	$y=f_1(x)$	[1,10]	20	6
S(280)	Chinese Shanghai Composite closing Index	[1,60]	20	57
J(280)	closing price of Jinlong Automobile (600686)	[1,70]	20	62

Table 1. Results above experiments

6. Performance Comprehensive Comparison with Traditional Algorithms

In this section, in order to illustrate the originality, novelty and superiority of the presented algorithm (ONNAAO), we will make many numerical experiments for the problem of stock indexes prediction with the above datasets, some performance of the presented algorithm, such as training time, training RMSE, testing RMSE and neurons, will be compared with the traditional algorithms such as AR, ARMA, ordinary BP, SVM.

In the following experiments, a faster BP algorithm called Levenberg-Marquardt algorithm is used, although there are many variants of BP algorithms. The SVM algorithm source codes are downloaded from LIBSVM3.21 [74].

To compare the performance of the algorithms mentioned above, in each experiment 30 trials have been carried out for each algorithm and the average training time, the ratio of the average training time with ONNAAO average training time (RATT):

 $RATT = \frac{average \ training \ time \ of \ the \ traditional \ algorithms}{average \ training \ time \ of \ ONNAAO}$

the average testing, the average testing RMSE, the testing standard deviations (Dev), and the ratio of the average testing RMSE with ONNAAO average testing RMSE (RATR):

 $RATR = \frac{average\ testing\ time\ of\ the\ traditional\ algorithms}{average\ trsting\ RMSE\ time\ of\ ONNAAO}$

which are showed in the table 2.

Algorithms	Training performance		Testing performance			Parameters
	Time	RATT	Average RMSE	Dev	RATR	
ONNAO	1.78975	1	96.9096	73.6057	1	Nodes=57
Ordinary BP	1.88548	1.0535	117.1466	106.9294	1.2088	Nodes=100
AR(p)	1.3634	0.7617	145.3068	20.12	1.4994	P=20
ARMA(p,q)	1.4735	0.8232	208.9682	78.9804	2.1563	P=20, q=15
SVM	2.5364	1.4171	765.3969	101.334	7.898	SVs=56

Table 2. Performance comparison for ONNAAO

From the performance comparison in table 2, we can see that the proposed ONNAAO algorithm has the best average testing RMSE, although the running time of ONNAAO is not the shortest, which fully shows that the ONNAAO algorithm has better prediction accuracy in performance compared with traditional prediction algorithms. Although in the forecasting problem there are also some approaches [4, 42,48] with the hybrid algorithms such as neural networks combined with some other techniques, wavelets for example, but the ONNAAO algorithm is relatively simple and intuitive.

Remark 1. The training and testing time of ONNAAO are the time of training and testing after determining the number of hidden neurons for optimized neural network architecture.

7. Conclusions

In this paper, our goal is to find the optimized neural networks architecture and reduce the over-fitting phenomenon. Firstly, we analyzed the reasons for over-fitting and instability of NNs. Then we consider minimizing three objective indexes: training and testing root mean square error (RMSE) and testing error variance (TEV). Lastly we built a multi-objective optimization model, then convert to single objective optimization model to find the optimized NNs architecture. At the same time, the existence and uniqueness theorem 6 of optimized solution is proved. And an algorithm for Optimized Neural Network Architecture Avoiding Overfitting (ONNAAO) is constructed to training and forecasting two stock closing price datasets. Lastly, some performance such as training time, testing RMSE and neurons, has been compared with the traditional algorithm (AR, ARMA, ordinary BP, SVM) through many numerical experiments, which fully verified the better prediction accuracy, correctness and validity of the theory.

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